P.S.R. ENGINEERING COLLEGE

(An Autonomous Institution, Affiliated to Anna University, Chennai)

Sevalpatti (P.O), Sivakasi – 626140.

B.E. Mechanical Engineering

CURRICULUM AND SYLLABI



UG Regulations 2019

Department of Mechanical Engineering

CANDIDATES ADMITTED DURING 2019-2020 AND ONWARDS

P.S.R. ENGINEERING COLLEGE (An Autonomous Institution, Affiliated to Anna University, Chennai) Sevalpatti (P.O), Sivakasi – 626140.

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CANDIDATES ADMITTED DURING 2019-2020 AND ONWARDS

Vision

• To provide broad-based education and training in mechanical engineering and its applications to enable the graduates to meet the demands in a rapidly changing needs in industry, academia and society.

Mission

- To impart high quality technical education and training that encompasses both theory and practices with human and social values
- To equip the students to face tomorrows technology embedded global changes
- To create, explore, and develop innovations in mechanical engineering research

Programme Educational Objectives (PEOs)

- Lead a professional career by acquiring the basic knowledge in the field of specialization and allied Engineering.
- Assess the real life problems and deal with them confidently relevance to the society.
- Engage in lifelong learning by pursuing higher studies and participating in professional organizations.
- Exhibit interpersonal skills and able to work as a team for success.

Programme Specific Outcomes (PSOs)

- Apply the concepts of mathematics and science in mechanical systems.
- Design and analyze components and systems for mechanical engineering applications
- Synthesis data and technical concepts for application to mechanical engineering software.
- Apply manufacturing and management practices in industries.

PROGRAMME OUTCOMES (POs)

Engineering Graduates will be able to:

- a. Engineering Knowledge: Apply the knowledge of mathematics, science, engineering fundamentals, and an engineering specialization to the solution of complex engineering problems.
- b. **Problem Analysis:** Identify, formulate, review research literature, and analyze complex engineering problems reaching substantiated conclusions using first principles of mathematics, natural sciences, and engineering sciences.
- c. **Design/ Development of Solutions:** Design solutions for complex engineering problems and design system components or processes that meet the specified needs with appropriate consideration for the public health and safety, and the cultural, societal, and environmental considerations.
- d. **Conduct Investigations of Complex Problems:** Use research-based knowledge and research methods including design of experiments, analysis and interpretation of data, and synthesis of the information to provide valid conclusions.
- e. **Modern Tool Usage:** Create, select, and apply appropriate techniques, resources, and modern engineering and IT tools including prediction and modeling to complex engineering activities with an understanding of the limitations.
- f. **The Engineer and Society:** Apply reasoning informed by the contextual knowledge to assess societal, health, safety, legal and cultural issues and the consequent responsibilities relevant to the professional engineering practice.
- g. Environment and sustainability: Understand the impact of the professional engineering solutions in societal and environmental contexts, and demonstrate the knowledge of, and need for sustainable development.
- h. **Ethics:** Apply ethical principles and commit to professional ethics and responsibilities and norms of the engineering practice.
- i. **Individual and teamwork:** Function effectively as an individual, and as a member or leader in diverse teams, and in multi disciplinary settings.
- j. **Communication:** Communicate effectively on complex engineering activities with the engineering community and with society at large, such as, being able to comprehend and write effective reports and design documentation, make effective presentations, and give and receive clear instructions.
- k. **Project management and finance:** Demonstrate knowledge and understanding of the engineering and management principles and apply these to one's own work, as a member and leader in a team, to manage projects and in multidisciplinary environments.
- 1. **Lifelong learning:** Recognize the need for, and have the preparation and ability to engage in independent and life-long learning in the broadest context of technological change.

P.S.R. ENGINEERING COLLEGE, SIVAKASI-626 140 U.G REGUALTION-2019 (CBCS) B.E. MECHANICAL ENGINEERING CURRICULUM [I – VIII SEMESTER]

Total Credits:160

		SEMESTER – I					
S.No.	Course	Course Code Course Title		ours wee	_	Credits	Category
	Cour		L	Τ	P	_	l
		THEORY					
1.	191HS11	Communicative English	2	0	0	2	HSMC
2	191HS12	Calculus and Linear Algebra	3	1	0	4	BSC
3	191HS13	Engineering Physics	2	0	0	2	BSC
4	191HS14	Engineering Chemistry	2	0	0	2	BSC
5	191CSF1	Programming For Problem Solving	3	0	0	3	ESC
		THEORY CUM PRACTIC	CAL				
6	191MEF7	Mechanical Workshop	1	0	4	3	ESC
		PRACTICAL			•		
7	191HS17	Physics and Chemistry Laboratory - I	0	0	2	1	BSC
8	191CSF7	C Programming Laboratory	0	0	2	1	ESC
		Total				18	

SEMESTER –II

S.No.	Course Code	Course Title	Н	ours wee	_	Credits	Category
			L	Т	Р		
		THEORY					
1.	191HS21	Technical English	2	0	0	2	HSMC
2	191HS22	Differential Equations and Numerical Methods	3	1	0	4	BSC
3	191HS23	Physics of Materials	2	0	0	2	BSC
4	191HS24	Environmental Science	2	0	0	2	BSC
5	191EEF1	Basic Electrical and Electronics Engineering	3	0	0	3	ESC
		THEORY CUM PRACTICAL					
6	191MEF1	Engineering Graphics	1	0	4	3	ESC
		PRACTICAL					
7	191HS27	Physics and Chemistry Laboratory - II	0	0	2	1	BSC
8	191EEF7	Basic Electrical and Electronics Laboratory	0	0	2	1	ESC
		Total				18	

S.No.	Course Code	Course Title		loui Per weel	K	Credits	Category
		THEORY	L	Τ	Р		
1.	191HS31	Transforms and Discrete Mathematics	2	1	0	3	BSC
2	191BS31	Biology for Engineers	3	0	0	3	BSC
3	191ME31	Engineering Mechanics	3	0	0	3	ESC
4	191ME32	Engineering Thermodynamics	3	1	0	4	PC
5	191ME33	Engineering Metrology and Measurements	3	0	0	3	PC
-		THEORY CUM PRAC	TIC	CAL			
6	191ME34	Manufacturing Processes	3	0	2	4	PC
		PRACTICAL	1	1		I I_	
7	191ME37	Engineering Metrology and Measurements Laboratory	0	0	2	1	PC
8	191ME38	Computer Aided Drafting Laboratory	0	0	2	1	PC
9	191HS37	Communication Skills – I	0	0	2	-	HSMC
10		Value added course - I	1	0	0	-	VC
		Total				22	

SEMESTER – III

SEMESTER - IV

S.No.	Course Code	Course Title		Iou r w		Credits	Category	
	coue		L	Τ	Р			
		THEORY						
1.	191HS42	Probability and Statistics	2	1	0	3	BSC	
2	191ME41	Fluid Mechanics and Machinery	3	0	0	3	PC	
3	191ME42	Mechanics of Materials	3	1	0	4	PC	
4	191ME43	Materials Engineering	3	0	0	3	PC	
5	191ME44	Kinematics of Machinery	3	1	0	4	PC	
		THEORY CUM PRAC	TIC	CAL				
6	191ME45	Manufacturing Technology	3	0	2	4	PC	
		PRACTICAL						
7	191ME47	Fluid Mechanics and Machinery Laboratory	0	0	2	1	РС	
8	191ME48	Materials Testing Laboratory	0	0	2	1	PC	
9	191HS47	Communication Skills – II	0	0	2	-	HSMC	
10		Mandatory course - I	1	0	0	-	MC	
		Total				23		

			F	lour	•6			
S.No.	Course Code	Course Title	Course Title		Per week		Credits	Category
			L	Τ	Р			
		THEORY						
1	191ME51	Dynamics of Machinery	3	0	0	3	PC	
2	191ME52	Thermal Engineering	3	0	0	3	PC	
3	191ME53	Applied Hydraulics & Pneumatics	3	1	0	4	PC	
4	191ME54	Electronics Instrumentation and Control	3	0	0	3	PC	
5		Programme Elective - I	3	0	0	3	PC	
		THEORY CUM PRACT	FIC.	AL				
6	191ME55	Machine Design and Drawing	3	0	2	4	PC	
		PRACTICAL						
7	191ME57	Dynamics Laboratory	0	0	2	1	PC	
8	191ME58	Thermal Engineering Laboratory	0	0	2	1	PC	
9	191HS57	Business English	0	0	2	-	HSMC	
10		Value added course - II	1	0	0	-	VC	
		Total				22		

SEMESTER – V

SEMESTER - VI

S.No.	Course Code	Course Title	Hours Per week L T P		week		Credits	Category
		THEORY						
1	191ME61	Automation in Manufacturing	3	0	0	3	PC	
2	191ME62	Design of Transmission Systems	3	1	0	4	PC	
3	191ME63	Automobile Engineering	3	0	0	3	PC	
4	E1	Programme Elective –II	3	0	0	3	PE	
5	E2	Open Elective –I	3	0	0	3	OE	
		THEORY CUM PRAC	TIC	CAL				
6	191ME64	Heat and Mass Transfer	3	0	2	4	PC	
		PRACTICAL						
7	191ME67	CAD/ CAM Laboratory	0	0	2	1	PC	
8	191ME69	Mini Project	0	0	2	1	PROJ	
9	191HS67	Career English	0	0	2	-	HSMC	
10		Mandatory course - II	1	0	0	-	MC	
		Total				22		

S.No.	Course Code	Course Title		lour Per veel	K	Credits	Category
			L	Τ	P		
		THEORY					
1	191ME71	Total Quality Management	3	0	0	3	PC
2	191ME72	Gas Dynamics and Jet Propulsion	3	0	0	3	PC
3	191ME73	Finite Element Analysis	3	1	0	4	PC
4		Programme Elective –III	3	0	0	3	PE
5		Open Elective –II	3	0	0	3	OE
		THEORY CUM PRAC	TIC	AL		· · · · · · · · · · · · · · · · · · ·	
6	191ME74	Mechatronics	3	0	2	4	PC
		PRACTICAL		•	•		
7	191ME77	Simulation and Analysis Laboratory	0	0	2	1	PC
8	191ME79	Project - I	0	0	4	2	PROJ
9		Value added course - III	1	0	0	-	VC
		Total				23	

SEMESTER – VII

SEMESTER – VIII

S.No.	Course Code	Course Title	Hours Per week		Per week		Per week		Per week		Per week		Per week		Category
			L	Τ	Р										
		THEORY													
1	-	Programme Elective –IV	3	0	0	3	PE								
2	-	Open Elective –III	3	0	0	3	OE								
		PRACTICAL													
3	191ME89	Project – II	0	0	12	6	PROJ								
		Total	•	•		12									

HS - Humanity Science, BS - Basic Science, ES - Engineering Science, PC - Programme Core,

PE – Programme Elective, OE – Open Elective, EEC – Employment Enhancement Course, MC – Mandatory Course

List of Programme Electives

S.No.	Code	Course Title	L-T-P	C	Category
1.	191HSEA	Professional Ethics in Engineering	3-0-0	3	HSMC
2.	191MEEA	Additive Manufacturing	3-0-0	3	PE
3.	191MEEB	Composite Materials and Engineering	3-0-0	3	PE
4.	191MEEC	Computational Fluid Dynamics	3-0-0	3	PE
5.	191MEED	Computer Integrated Manufacturing	3-0-0	3	PE
6.	191MEEE	Fireworks Safety	3-0-0	3	PE
7.	191MEEF	Fundamentals of Nano Technology	3-0-0	3	PE
8.	191MEEG	Hybrid and E-Vehicles	3-0-0	3	PE
9.	191MEEH	Industrial Engineering and Management	3-0-0	3	PE
10.	191MEEI	Product Design and Development	3-0-0	3	PE
11.	191MEEJ	Internet Of Things for Manufacturing	3-0-0	3	PE
12.	191MEEK	Modern Machining Processes	3-0-0	3	PE
13.	191MEEL	Rapid Prototyping	3-0-0	3	PE
14.	191MEEM	Power Plant Engineering	3-0-0	3	PE
15.	191MEEN	Process Planning and Cost Estimation	3-0-0	3	PE
16.	191MEEO	Production Planning and Control	3-0-0	3	PE
17.	191MEEP	Refrigeration and Air Conditioning	3-0-0	3	PE
18.	191MEEQ	Welding Technology	3-0-0	3	PE

List of Open Electives Offered by Mechanical Department

S.No.	Code	Course Title	L-T-P	С	Category
1	1910E6A	Maintenance Engineering	3-0-0	3	OE
2	1910E6B	Non-Destructive Testing and Materials	3-0-0	3	OE
3	1910E6C	Operations Research and Management	3-0-0	3	OE
4	1910E6D	Renewable Sources of Energy	3-0-0	3	OE
5	1910E6E	Robotics	3-0-0	3	OE

		Mandatory Courses			
S. No.	Code	Name of the Course	L-T-P	С	Categ ory
1	191MC01	Design Thinking	2-0-0	0	MC
2	191MC02	Essence of Indian Traditional Knowledge	2-0-0	0	MC
3	191MC03	Indian Constitution	2-0-0	0	MC
4	191MC04	Universal Human Values	2-0-0	0	MC
5	191MC05	Yoga	2-0-0	0	MC

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191HS11		COMMUNIC	ATIVE ENGL	ISH		L-T-P	
D	DE /DTL	(C	D	C I	Cat	2-0-0	2 HSMC
Programme:		. (Common to al	,	Sem: I	Cat	egory: 1	ISMC
Prerequisites:	1	nguage proficier	2				
Aim:		basic Language	Skills in order	to commun	nicate w	vith English	ı
	Language S	peakers.					
Course Outcom							
The Students wi							
CO1: Develop t							
CO2: Listen act	• •	-	-				
CO3: Develop t							
CO4: Develop v						•	
CO5: Use the gr		•	their speaking	and writin	g skill.		
CO6: Speak in I							
UNIT 1 SHAR	ING INFORM	AATION RELA	FEDTO ONES	ELF, FAM	ILY AN	D	6
FRIENDS.	<u> </u>						
Reading - Short				•	•	•	
structures, Develo							
- Introducing one	self, Exchangi	ng personal inforr	nation. Languag	ge Developn	ent – W	'H questions	s, Asking
and answering YI	ES or NO ques	stions, Parts of Sp	eech. Vocabul	ary Develop	ment –	Prefixes &	Suffixes,
Subject verb Agre	-	, 1		5 1			,
UNIT 1I		GENERAL REA	DING AND F	REE WRIT	ING		6
Reading - Comp						ns (Multipl	e choice
questions, Short c							
menualing Dialogu		Dorogroph Writin				contonood I	istoning
TT 1 1 1		Paragraph writin					Listening
Telephonic conve	rsations. Speal	king – Sharing inf	formation of a p	ersonal kind	, Greetii	ngs.	-
Language Develo	rsations. Speal pment – Nour	king – Sharing inf Pronoun agreem	formation of a plant. Vocabular	ersonal kind	, Greetii	ngs.	-
Language Develo Formation. (Norm	rsations. Speal pment – Nour an Lewis' <i>Wo</i>	king – Sharing inf Pronoun agreem rd Power Made E	Formation of a p nent. Vocabular Easy)	ersonal kind y Developm	, Greetin ent – Tl	ngs.	of Word
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Language Develo Formation. (Norm UNIT 111 Reading – Short t Jumbled sentence Narratives from d	rsations. Speal pment – Nour an Lewis' <i>Wo</i> GRAMM exts & Longe s. Listening – ifferent source	king – Sharing inf Pronoun agreem <i>rd Power Made E</i> IAR AND LAN r passages (Cloze Listening to lon s. Speaking – Asl	Cormation of a p nent. Vocabular <i>Casy</i>) GUAGE DEVI reading). Writ ager texts and f king about routi	ersonal kind y Developm CLOPMEN ing – Impor illing up the ne actions an	, Greetin ent – Tl <u>F</u> tance of e table, nd Expre	ngs. he Concept proper pun Product des essing opini-	of Word 6 ctuation, cription, ons.
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Course Outcomes				ŀ	Progr	am O	utcor	nes (I	POs)				Program Specific Outcomes (PSOs)				
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	
CO1										3		3					
CO2										3		2				2	
CO3										3		3				2	
CO4					2					3		3					
CO5										3		3					
CO6										3		2					

191HS12	CALCULUS AND LINEAR ALGEBRA L-T-P	C
	3-1-0	4
Programme:	B.E./B.Tech. (Common to all Branches) Sem: I Category:	BSC
Prerequisites:	Matrices, Differentiation and Integration.	
Aim:	The course is aimed at developing the basic mathematical skills of engineering s	tudents,
Course Outcome	28:	
The students	s will be able to	
	verse and the positive powers of a square matrix	
	concept of orthogonal reduction to diagonalise the given matrix	
** *	the evolute of curves, Beta and Gamma Functions.	
	rangian multiplier method for finding maxima and minima of an unconstrained	
problem		
	concepts of Differentiation and Integration in Vectors.	
	analytic function, when its real or Imaginary part is known.	
UNIT 1	MATRICES	12
•	uation - Eigen Values and Eigen vectors of a real matrix - Properties of Eigen values	
	m (without proof) and its application - Orthogonal Transformation of a Symmetric	e matrix t
diagonal form - Ç	Quadratic form - Orthogonal reduction to canonical form.	
UNIT 1I	CALCULUS	12
Radius of Curvat	ure - Cartesian and Parametric Coordinates - Circle of Curvature - Involutes and	Evolutes
	functions and their properties.	
		12
UNIT 111	MULTIVARIABLE CALCULUS	12
	es - Total Derivative - differentiation of Implicit function – Jacobian - Taylor's E	xpansion
	for function of two variables - Method of Lagrange's multipliers.	
UNIT 1V	VECTOR CALCULUS	12
•	ence and Curl - Directional derivative - Irrotational and Solenoidal vector fields	
•	en's theorem in a plane, Gauss divergence theorem and Stokes' theorem (excluding	g proofs)
Simple applicatio	ons involving cubes and rectangular parallelepiped.	
UNIT V	COMPLEX VARIABLE – DIFFERENTIATION	12
Functions of a co	mplex variable – Analytic functions – Necessary conditions, Cauchy– Riemann eq	uation an
Sufficient conditi	ions (excluding proofs) – Harmonic and orthogonal properties of analytic function	on(withou
proof) – Harmon	ic conjugate – Construction of analytic functions – Conformal mapping : $w = z + z$	c, cz, 1/z
and bilinear trans		
	T (I) · I	60
	I otal Periods:	
Text books:	Total Periods:	00
	al, "Higher Engineering Mathematics", Khanna Publishers, New Delhi, 43 rd Editi	
1. B.S. Grewa 2014.	al, " Higher Engineering Mathematics ", Khanna Publishers, New Delhi, 43 rd Editi	
 B.S. Grewa 2014. G.B. Thoma 		
1. B.S. Grewa 2014.	al, " Higher Engineering Mathematics ", Khanna Publishers, New Delhi, 43 rd Editi	
 B.S. Grewa 2014. G.B. Thoma 2002 References:	al, " Higher Engineering Mathematics ", Khanna Publishers, New Delhi, 43 rd Editi as and R.L. Finney, Calculus and Analytic geometry, 9 th edition, Pearson, Reprint,	on,
 B.S. Grewa 2014. G.B. Thoma 2002 References: Veerarajan. <i>T</i> 	al, " Higher Engineering Mathematics ", Khanna Publishers, New Delhi, 43 rd Editi as and R.L. Finney, Calculus and Analytic geometry, 9 th edition, Pearson, Reprint, T., " Engineering Mathematics for first year ", Fourth Edition, Tata Mc-Graw – Hi	on,
2014. 2. G.B. Thoma 2002 References: 1. Veerarajan. <i>T</i> New Delhi, 2	al, " Higher Engineering Mathematics ", Khanna Publishers, New Delhi, 43 rd Editi as and R.L. Finney, Calculus and Analytic geometry, 9 th edition, Pearson, Reprint, <i>C.</i> , " Engineering Mathematics for first year ", Fourth Edition, Tata Mc-Graw – Hi 2008.	on,
 B.S. Grewa 2014. G.B. Thoma 2002 References: Veerarajan.7 New Delhi, 2 Erwin Kreys. 	al, " Higher Engineering Mathematics ", Khanna Publishers, New Delhi, 43 rd Editi as and R.L. Finney, Calculus and Analytic geometry, 9 th edition, Pearson, Reprint, <i>T.</i> , " Engineering Mathematics for first year ", Fourth Edition, Tata Mc-Graw – Hi 2008. <i>zig</i> , Advanced Engineering Mathematics , 9 th Edition, John Wiley & Sons, 2006.	on,
 B.S. Grewa 2014. G.B. Thoma 2002 References: Veerarajan. <i>T</i> New Delhi, 2 Erwin <i>Kreys</i>. 	al, " Higher Engineering Mathematics ", Khanna Publishers, New Delhi, 43 rd Editi as and R.L. Finney, Calculus and Analytic geometry, 9 th edition, Pearson, Reprint, <i>C.</i> , " Engineering Mathematics for first year ", Fourth Edition, Tata Mc-Graw – Hi 2008.	on,
 B.S. Grewa 2014. G.B. Thoma 2002 References: Veerarajan.7 New Delhi, 2 Erwin Kreys. G.B. Thomas 	al, " Higher Engineering Mathematics ", Khanna Publishers, New Delhi, 43 rd Editi as and R.L. Finney, Calculus and Analytic geometry, 9 th edition, Pearson, Reprint, <i>T.</i> , " Engineering Mathematics for first year ", Fourth Edition, Tata Mc-Graw – Hi 2008. <i>zig</i> , Advanced Engineering Mathematics , 9 th Edition, John Wiley & Sons, 2006.	on, 11, 11,2002.

Course Outcomes				ł	Progr	am O	utcor	nes (l	POs)				Program Specific Outcomes (PSOs)				
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	
CO1	3	3		1								2		2	1		
CO2	2	3		2								1				1	
CO3	3	3										3	2				
CO4	1	1													2		
CO5	3	2		1										2			
CO6	2	2		1								3	2			2	

191HS13	ENGINEERING PHYSICS			L-T-P	C
	1			2-0-0	2
Programme:	B.E./B.Tech. (Common to all Branches)	Sem:	Ι	Category:	BSC
Prerequisites:	School Level Physics				
	To endow the students with the fundamentals of	Physics ar	nd apply	new ideas in	the field
AIM:	of Engineering and Technology.	5	11 5		
Course Outcome					
The Students will	be able to				
	the theory and various crystal structures.				
	It the basic configuration of a Laser, types of lasers	and the in	ndustria	1	
application					
CO3: Understand	l principle behind fiber optic communication and th	ne electror	ic devic	ces	
involved in	the transmission and reception of data.				
CO4: Know abou	it basics of properties of matter and its applications	,			
CO5: Gain know	ledge about basic equations of Quantum mechanics	s and its ap	oplicatio	ons.	
CO6: Understand	the basic concepts of acoustics and ultrsonics.				
UNIT 1	SOLID STATE PHYSI				6
	- Bravais lattice - Lattice planes - Miller indices		0		
	ns per unit cell – Atomic radius – Coordination nur			ctor for SC, E	BCC, FC
	es – Crystal Defects-point, Line and surface defects	- burger	vector.		
UNIT 1I	WAVE OPTICS		• •	D	6
	action – Principle of Spontaneous emission and sti s A and B coeffcients – Derivation- Types of lasers				
	ng, cutting and Soldering FIBER OPTICS: Op				
	ht in optical fibres- Numerical aperture and Accept				
	Active and passive) – Displacement and Temperatu	•		op	
UNIT 1II	PROP ERTIES OF MATTER	R			6
•	strain diagram and its uses -factors affecting elasti			•	
	ations - twisting couple- torsion pendulum: theo				
	-cantilever: theory and experiment-uniform a	and non-u	iniform	bending: th	eory an
·	aped girders - stress due to bending in beams.				
UNIT 1V Plack body redict	QUANTUM PHYSICS ion – Planck's theory -Photoelectric effect - Matter	, WOLOG	Sahrädi	naor'a mono	6
	and time dependent equations – Physical signification				
dimensional box.	and time dependent equations - 1 hysical significe				
	A COLICTICS AND HI TDASC				
UNIT V	ACOUSTICS AND ULTRASO		on Lour	standard int	<u>6</u>
	assification of sound - loudness and intensity - We ecibel - reverberation - reverberation time - Sabine'				
•	ctors affecting acoustics of buildings: focusing, inte			L	
	emedies. Ultrasonics: Ultrasonics - production - ma				
	THELIES. UTIL ASUMES. UTILASUMES - DIOUUCION - MA	agnetostri	cuon an	d piezoelectri	
- acoustic grating	- industrial applications - NDT.	agnetostri	chon an	d piezoelectri	e method
- acoustic grating	-	agnetostri		d piezoelectri Total Period	
	-	agnetostri		-	
Text books:	- industrial applications - NDT.			Total Period	
Text books: 1. Gaur R. K., Gu	- industrial applications - NDT.	lications,	New De	Total Period	ls 30
Text books: 1. Gaur R. K., Gu 2. Avadhanulu M	 - industrial applications - NDT. - industrial applicat	lications,	New De	Total Period	ls 30
Text books: 1. Gaur R. K., Gu 2. Avadhanulu M New Delhi, 20	 - industrial applications - NDT. - industrial applicat	lications,	New De	Total Period	ls 30
Text books: 1. Gaur R. K., Gu 2. Avadhanulu M New Delhi, 20 References:	 - industrial applications - NDT. - industrial applicat	lications, 2 ng Physics	New De s", S.Ch	Total Period Ethi (2016) and and comp	ls 30
Text books: 1. Gaur R. K., Gu 2. Avadhanulu M New Delhi, 20 References: 1. Serway and Jev	 - industrial applications - NDT. - industrial applicat	lications, 2 ng Physics	New De s", S.Ch	Total Period Ethi (2016) and and comp	ls 30

Course Outcomes				I	Progr	am O	utcoi	nes (I	POs)				Program Specific Outcomes (PSOs)				
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	
CO1	2	2	1		2		3					2	1	1			
CO2	3	2	2	2			3					2	1	1			
CO3	2	2					3					1	1	1			
CO4	3	2	2	2			2					2	1	1			
CO5	3	2	2				2					2	1	1			
CO6	3	2	2	2			2					2	1	1			

191HS14	ENGINEERING CHEMISTI	RY			L-T-P	С					
					2-0-0	2					
Programme:	B.E./B.Tech. (Common to all Branches)	Sem:	Ι	Cat	egory:	BSC					
Prerequisites:	Basic Science										
Aim:	To impart a sound knowledge on the principles application oriented topics required for all engi				g the diffe	rent					
Course Outcom	es:										
At the end of the	course the student will be able to										
CO1: Demonstra	te the essential concept of water and their proper	ties and ap	plicatio	ons.							
CO2: The treatm	ent of water for potable and industrial purposes	•	-								
CO3: Understand	d the operating principles and the reaction involve	ed in electr	ochemi	istry.							
	Know the principles and application of spectroscopy										
	basic ingredients required for paint formulation										
CO6: Know the	preparation techniques of consumer products										

UNIT 1 WATER TECHNOLOGY	6
Hardness -Types and Estimation by EDTA method- alkalinity -types of alkalinity and determination	on
-Domestic water treatment -disinfection methods - Boiler feed water- internal conditionin	g– external
conditioning – desalination and reverse osmosis.	
UNIT 1I ELECTROCHEMISTRY	6
Electrochemical cells - reversible and irreversible cells - EMF -measurement of emf - Sing	gle electrode
potential – Nernst equation- reference electrodes –Standard Hydrogen electrode –	
Calomel electrode - Ion selective electrode - glass electrode and measurement of pH - electroche	mical series
UNIT 111 SPECTROSCOPIC TECHNIQUES AND APPLICATIONS	6
Introduction of UV-Visible and IR spectroscopy and selection rules- principles and instrumenta	ation of UV-
Visible (electronic) spectroscopy - IR (vibrational) spectroscopy - its applications. Fluorescence	spectroscopy
and its applications in medicine-colorimetry – estimation of iron by colorimetry .	
UNIT 1V INORGANIC & ORGANIC COATINGS	6
Paint-Definition-Components of Paints and their functions-Varnish-Definition-Preparation of C	Dil Varnish–
Differences between Paint and Varnish-Special Paints-Luminescent Paints, Fire Retardant Paints-	Aluminium
Paints - Distemper. corrosion control-electroplating (Au) and electroless (Ni) plating.	
UNIT V PREPARATION OF CONSUMER PRODUCTS	6
Washing Powder- Cleaning powder - phenoyls (white, Black & coloured)- Shampoo- liquid blu	e- inks - blue
-red - green inks - Soap - bathing & detergent - oils - Face powder and bleaching powder.	
Total Periods:	30

Text books:

- 1. P. Kannan, A. Ravikrishnan, "Engineering Chemistry", Sri Krishna Hi-tech Publishing Company Pvt. Ltd. Chennai, 2009.
- 2. P.C.Jain and Monica Jain, "Engineering Chemistry" Dhanpat Rai Pub, Co., New Delhi (2002)

References:

- 1. S.S. Dara, S.S. Umare, "Engineering Chemistry", S. Chand & Company Ltd., New Delhi 2010.
- 2. B.K.Sharma, "Engineering chemistry" Krishna Prakasan Media (P) Ltd., Meerut (2001).
- 3. B.Sivasankar, "Engineering chemistry" Tata McGraw Hill Publishing Company (P) Ltd., New Delhi, 2006

Course Outcomes				I	Progr	am O	utcoi	nes (I	POs)				Program Specific Outcomes (PSOs)				
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	
CO1	3	3	3	2		2	3			2		3	1	3		2	
CO2	3	2		2	2	3		1	2		2	2	2	2		3	
CO3				2			2					2	3	3		3	
CO4	2	1	2	2	1		2					1	2	2			
CO5	3	2	2	1	2	1			2			2	3	3		2	
CO6	3	3	3	2		2	3			2		3	2	3		3	

191CS21	PROGRAMMING FOR PROBLEM SC	OLVIN	G		L 3	Т 0	P 0	C 3
Programme:	B.E./B.Tech. Common to all Branches	Sem:	1	Categ	_	U	U	ES
8	vide an awareness to Computing and Programming.			8	- 5 -			
Course Objecti								
Learn th	ne organization of a digital computer.							
• Gain kn	owledge of software types and development steps.							
	think logically and write pseudo code or draw flow cl	harts for	r pro	oblems.				
• Exposed	d to the syntax of C.		•					
• Be fami	liar with programming in C.							
	o use arrays, strings, functions, pointers, structures and	l unions	in C	2.				
	nes: The Students will be able to							
CO1: Understat	nd the basic terminologies of Computer and various Pr	oblem-s	solvi	ing tech	nique	S.		
	mpile and debug programs in C language.			ing teen	inque			
	rent data types in a computer program.							
	ograms involving decision structures, loops and functi	ions.						
	nd the dynamics of memory by the use of pointers.							
	rent data structures and create/update basic data files.							
UNIT 1	INTRODUCTION							9
	Classification of Computers - Basic Organization of a	a Compi	uter	- Numb	er Sy	stem	1 - B	-
	version - Problems. Software - Types, Development S	-			-			•
	formulation - Problem Solving.	1	0					
UNIT 1I	C PROGRAMMING BASICS							9
in 'C' - Managin	ilation and linking processes - Constants, Variables - D ng Input and Output operations - Decision Making and E e and statistical problems. ARRAYS AND STRINGS	• 1		-				
	zation - Declaration - One dimensional and Two-dimen	nsional	arra	ve Strin	a St	ring	one	
•	Simple programs – Bubble Sort – Linear Search - Mat		-	-	ig - 51	ing	ope	1410115
UNIT 1V	FUNCTIONS AND POINTERS							9
Function - Defin	nition of function - Declaration of function - Pass by	value -	Pas	s by ref	erenc	e - I	Recu	rsion -
Pointers - Defin	ition - Initialization - Pointers arithmetic - Pointers and	d arrays	- Ez	kample	Probl	ems.		
UNIT V	STRUCTURES AND FILES							9
	eed for structure data type - structure definition - St							
	n - Programs using structures and Unions - File Manip	oulation	- Sto	orage cl	asses	- Pre	e-pro	ocessor
directives.								
				Tot	al Pe	riod	S	45
Text Books:								
	A in Mittal "Commune For I and I b			2 D	~ V.	1	1	$(\mathbf{L}_{n}, \mathbf{L}_{n})$
D-+ I + J D.	and Ajay Mittal, "Computer Fundamentals and Program	mming i	n C'	', Dorlir	ng Kin	nders	sley	(India)
	earson Education in South Asia, 2017.	C			ıg Kiı	nders	sley	(India)
2. Balagurusar	earson Education in South Asia, 2017. ny E, "Programming in ANSI C", Tata Mcgraw-Hill E	Educatio	on, 2	016	0		•	
 Balagurusar Reema Thar 	earson Education in South Asia, 2017.	Educatio	on, 2	016	0		•	
 Balagurusar Reema Thar References:	earson Education in South Asia, 2017. ny E, "Programming in ANSI C", Tata Mcgraw-Hill E reja, "Computer Fundamentals and Programming in C"	Educatio ", 2e, O	on, 2 xfor	016 d Unive	rsity	Pres	s, 2(
 2. Balagurusar 3. Reema Than References: 1. Byron S Go 	earson Education in South Asia, 2017. ny E, "Programming in ANSI C", Tata Mcgraw-Hill E	Educatio ", 2e, O	on, 2 xfor n, M	016 d Unive IcGraw-	rsity	Pres	s, 2(

Course Outcomes					Progr	am O	outcor	nes (P	Os)				Program Specific Outcomes (PSOs)				
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	
CO1	3	2											3				
CO2	3	2											3	3			
CO3	3	3	2	1						1				3			
CO4	3	2	1										2				
CO5	2	2	3	2										2			
CO6	2	2			1									2	2		
CO7	2	2	2	2	1									3		1	

191ME17	MECHANICAL WORKSHOP	L-T-P	С
		1-0-3	2
Programme:	B.E./B.Tech. Common to all branches Sem: I / II Cate	gory:	ES
Prerequisites:	Nil		
Aim:	To Provide exposure to the students with hands on exper- Engineering Practices	ience on vari	ous basic
Course Outcomes:	6 6		
The students will be	able to		
	are fitting, vee & step fitting		
-	le wooden joints using wood working tools		
-	and funnel in sheet metal		
•	lap, butt and tee joints using arc welding equipments		
CO5. Identify the va			
CO6. Make the pipe			
UNIT 1	FITTING OPERATIONS & POWER TOOLS		12
	e fitting, vee & step – fitting models		
UNIT 1I	CARPENTRY		12
Study of the joints in	n roofs, doors, windows and furniture; Hands-on-exercise: Disma	untling & Asse	mbling o
5 5	niture; Preparation of T Joint, dove tail joint	8	0
UNIT 1II	SHEET METAL FORMING		12
Preparation of tray a			12
UNIT 1V	WELDING		12
Preparation of arc w	elding of butt joints and lap joints		
UNIT V	PLUMBING		12
Study of pipeline j	oints, its location and functions: valves, taps, couplings, unio	ns, reducers,	elbows in
household fittings;	Hands-on-exercise - basic pipe connections - Mixed pipe	material con	nection -
Connections with di	fferent joining components		
		Fotal Periods:	60
LIST OF EQUIPME	ENTS (For a batch of 30 students)		
1. Fitting vice (fit	ted to work bench) - 15Nos		
	,		
•	15 set		
2. Fitting Tools –			
 Fitting Tools – Carpentry vice 	(fitted to work bench) - 15 Nos.		
 Fitting Tools – Carpentry vice Models of indu 	(fitted to work bench) - 15 Nos. strial trusses, door joints, furniture joints - 5 Nos.		
 Fitting Tools – Carpentry vice Models of indu 	(fitted to work bench) - 15 Nos. strial trusses, door joints, furniture joints - 5 Nos. working tools - 15 Sets		
 Fitting Tools – Carpentry vice Models of indu Standard wood Hand Shear - 0 	(fitted to work bench) - 15 Nos. strial trusses, door joints, furniture joints - 5 Nos. working tools - 15 Sets 1		
 Fitting Tools – Carpentry vice Models of indu Standard wood Hand Shear - 0 Standard tools a 	(fitted to work bench) - 15 Nos. strial trusses, door joints, furniture joints - 5 Nos. working tools - 15 Sets 1 and calipers for sheet metal work - 05		
 Fitting Tools – Carpentry vice Models of indu Standard wood Hand Shear - 0 Standard tools a Arc welding transition 	(fitted to work bench) - 15 Nos. strial trusses, door joints, furniture joints - 5 Nos. working tools - 15 Sets 1 and calipers for sheet metal work - 05 unsformer with cables and holders - 5Nos.		
 Fitting Tools – Carpentry vice Models of indu Standard wood Hand Shear - 0 Standard tools a Arc welding training Welding booth 	(fitted to work bench) - 15 Nos. strial trusses, door joints, furniture joints - 5 Nos. working tools - 15 Sets 1 and calipers for sheet metal work - 05 unsformer with cables and holders - 5Nos. - 5 Nos.	Sets	
 Fitting Tools – Carpentry vice Models of indu Standard wood Hand Shear - 0 Standard tools a Arc welding tra Welding booth Welding access 	(fitted to work bench) - 15 Nos. strial trusses, door joints, furniture joints - 5 Nos. working tools - 15 Sets 1 and calipers for sheet metal work - 05 unsformer with cables and holders - 5Nos.		coupling

Course Outcomes				I	Progr	am O	utcor	nes (I	POs)				Program Specific Outcomes (PSOs)				
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	
CO1	2	2	3	3	3				3				2			3	
CO2	2	2	3	3	3				3				2			3	
CO3	2	2	3	3	3				3				2			3	
CO4	2	2	3	3									2			3	
CO5	2	2	3	3									2			3	
CO6	2	2	3	3	3				3							1	

191HS17	PHYSICS AND CHEMISTRY LAB	ORATO	RY-I		L-T-P		С					
		E (D. Task (Commune to all Describer) Some I										
Programme:	B.E./B.Tech. (Common to all Branches)	Sem:	Ι	C	Category:	BS	Ċ					
Pre/Corequisites:	Engineering Physics & Engineering Chemistry											
AIM:	To introduce the basic Physics concepts through experiments and to impart the basic analysis in chemistry.											
Course Outcomes:												

The Students will be able to

CO1: Understand the laser light propagation in optical fibre and the rigidity modulus of the materials

CO2: Understand the velocity of sound in liquid and propagation light in the medium

CO3: know about the stress analysis and thermal conductivity of the material

CO4: Gain knowledge of water quality parameter of potable water

CO5: Determine the unknown concentrations of chemicals

CO6: Apply the instrumental technique for calculating the amount of unknown substance

	LIST OF EXPERIMENTS - PHYSICS PART (A minimum of five experiments shall be offered)	
S.No	NAME OF THE EXPERIMENT	
1)	(a) Determination of Particle Size using Diode LASER.	
-	(b) Determination of wavelength of the LASER source.	3
	(c) Determination of Acceptance angle and Numerical aperture of an optical fibre.	
2)	Torsional pendulum – Determination of rigidity modulus	3
3)	Determination of Velocity of sound and compressibility of liquid - Ultrasonic	3
	Interferometer.	
4)	Determination of Dispersive power of a prism using Spectrometer.	3
5)	Determination of Young's modulus of the material - Non uniform bending	3
6)	Determination of thermal conductivity of a bad conductor - Lee's Disc method	3

	LIST OF EXPERIMENTS – CHEMISTRY PART	
S.No	NAME OF THE EXPERIMENT	
1)	Estimation of Total Hardness of their home town Water by EDTA method.	3
2)	Estimation of Alkalinity of Water sample	3
3)	Estimation of Chloride ion in water sample by Argentometric method.	3
4)	Estimation of Ferrous Ion by Potentiometric Titrations.	3
5)	Conductometric Titration of strong acid Vs strong base	3

References

- 1) Text book of Quantitative Inorganic Analysis, A.I.Vogel, ELBS, London, (2006)
- 2) "Practical A. Ravikrishnan Engineering Chemistry", Sri Krishna Publications, Chennai (2002)
- 3) Engineering Physics Laboratory Manual
- 4) Engineering Chemistry Laboratory Manual

Course Outcomes				I	Progr	am O	utcor	nes (I	POs)			Pr Ou	ogram itcome	Specif s (PSC	fic (s)
Outcomes	PO1	PO2	PO3	PO4	PO12	PSO1	PSO2	PSO3	PSO4						
CO1	3	2	1		2		1				1	1	1		
CO2	1	2	2				1				1	1	1		
CO3	2	1	3		2		2				2	1	1		
CO4	2	1	3		2		2				2				
CO5	2	2	1		1		2				1				
CO6	3	2	1	2	2		1				2				

91CS27		C PROG	GRAMMI	ING LABC	ORATO	RY			L T 0 0	P 2	(
Programme:	B.E./B.Tech	n. Common t	to all Bra	nches		Sem:	1	Cat	egory:		S
Prerequisites											
Aim To prov	vide practical kn	nowledge in	developi	ng C Progra	amming.		I	1			
Course Object	ves:										
• Be fam	iliar with the use	e of Office s	software.								
• Be expo	osed to presenta	tion and visu	ualization	tools.							
• Gain kr	lowledge of soft	tware types a	and devel	lopment ste	ps.						
• Be fam	iliar with progra	amming in C	2.								
• Learn to	o use Arrays, str	rings, functio	ons, struc	tures and u	nions.						
	nes: The Studer										
CO1: Able to h	ave fundamenta	al concept or	n basics c	ommands i	n Linux.						
	rite, compile ar										
CO3: Able to f	ormulate proble	ms and impl	lement alg	gorithms in	C.						
CO4: Able to e	ffectively choos	se programn	ning com	ponents that	at efficie	ently sol	ve co	omputi	ng prob	lems	i
real-world.											
CO5: Able to d	esign applicatio	n-oriented p	orograms	in C.							
CO6: Structure	s and unions thr	ough which	derived of	data types c	an be fo	rmed.					
LIST OF EXP	ERIMENTS:										
1. Draw a	flowchart for va	arious algori	ithms usi	ng Raptor							
2. C Progr	camming using S	Simple state	ements an	d expressio	ns.						
3. Scienti	fic problem-solv	ving using de	ecision m	aking and l	looping.						
4. Simple	programming for	or one dime	nsional ai	nd two-dim	ensional	arrays.					
-	problems using					5					
	ns with user def			ides Param	eter Pass	sing.					
	n using Recursi					-	to fl	ow cha	art.		
-	ns using pointer										
e	n using structur		ns.								
ę	n using files.										
U]	Fotal F	Periods	60	
LIST OF EQU	IPMENT FOR	A BATCH	I OF 30 S	STUDENT	S:					1	
Standalone desl											
standalone desl	tops with C cor	mpiler 30 No		or)							

Server with C compiler supporting 30 terminals or more.

Course Outcomes				I	Progr	am O	utcor	nes (I	POs)						Specif s (PSC	
Outcomes	PO1	PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 1 2 </th <th>PSO1</th> <th>PSO2</th> <th>PSO3</th> <th>PSO4</th>											PSO1	PSO2	PSO3	PSO4
CO1	3	1	2						2				3	1	1	
CO2	3	2	2						2				3	2	2	
CO3	3	2	3						2				3	3	2	
CO4	2	3	2						2				3	2	2	2
CO5	3		2						2				3	2	1	
CO6	2		2										2	2	1	

Prerequisites: Acquire Proficiency in Technical Communication Aim: To develop the students' intellectual, personal & Professional abilities. Course Outcomes: Course Outcomes: The Students will be able to CO1: Remember words and its meanings for the specific purpose. CO2: Understand the basic nuances of language CO3: Apply written communication methodologies at workplace. CO4: Develop Listening skill to respond and to gather information. CO5: Interpret the text using comprehending skill. CO5: Involve in professional correspondences confidently. INTRODUCTION TO TECHNICAL ENGLISH 6 Listening Listening to talks mostly of a scientific/technical nature and completing information-gap exercises Speaking – Asking for and giving directions. Reading – reading short technical texts, Newspapers. Writing Purpose statements, Extended definitions, Writing Instructions & Recommendations, Checklists. Vocabula 6 Development - Technical Vocabulary. Language Development – Subject Verb Agreement. 6 UNIT 11 READING AND STUDY SKILLS 6 Distening - Listening to longer technical texts, Newspapers identifying various transitions in a tex paragraphing. Writing - Techniques for writing Precisely. Vocabulary Development -vocabulary used in form tetrs/emails and reports. Language Development - Personal & Impersonal Passive voice, Numeric adjectives. UNIT 11 TECHNICAL WRITING AND GR	191HS21	TECHNICAL ENGLISH			L-T-P	•	С
Prerequisites: Acquire Proficiency in Technical Communication Aim: To develop the students' intellectual, personal & Professional abilities. Course Outcomes: Course Outcomes: The Students will be able to CO2: Understand the basic nuances of language CO3: Inderstand the basic nuances of language CO3: Odd State nume of language CO3: Inderstand the basic nuances of language CO3: Odd State nume of language CO3: Inderstand the basic nuances of language CO3: Odd State nume of language CO4: Develop Listening skill to respond and to gather information. CO5: Interpret the text using comprehending skill. CO6: Involve in professional correspondences confidently. 6 Listening: Listening to talks mostly of a scientific/technical nature and completing information-gap exercises Speaking – Asking for and giving directions. Reading – reading short technical texts, Newspapers. Writing Purpose statements, Extended definitions, Writing Instructions & Recommendations, Checklists. Vocabula Development - Technical Vocabulary. Language Development – Subject Verb Agreement. UNIT 11 READING AND STUDY SKILLS 6 A argaraphing. Writing - Techniques for writing Precisely. Vocabulary Development - vocabulary used in form etters/emails and reports. Language Development - Personal & Impersonal Passive voice, Numeric algeetives. 6 UNIT 111 TECHNICAL WRITING AND GRAMMAR 6 L					2-0-0		
Aim: To develop the students' intellectual, personal & Professional abilities. Course Outcomes: The Students will be able to CO1: Remember words and its meanings for the specific purpose. CO2: Understand the basic nuances of language CO3: Apply written communication methodologies at workplace. CO4: Develop Listening skill to respond and to gather information. CO5: Interpret the text using comprehending skill. CO6: Involve in professional correspondences confidently. UNIT 1 INTRODUCTION TO TECHNICAL ENGLISH Co6: Involve in professional correspondences confidently. UNIT 1 INTRODUCTION TO TECHNICAL ENGLISH Development - Technical vocabulary. Language Development – Subject Verb Agreement. UNIT 11 READING AND STUDY SKILLS Objectives. 6 UNIT 11 READING AND STUDY SKILLS Or cases. 6 Listening - Listening to longer technical talks and completing exercises based on them. Speaking – Describin a process. Reading – Reading longer technical texts, Newspapers identifying various transitions in a tex paragraphing. Writing - Techniques for writing Precisely. Vocabulary Development -vocabulary used in form etters/emails and reports. Language Development - Personal & Impersonal Passive voice, Numerici digectives. <t< th=""><th>Programme:</th><th>B.E./B.Tech. (Common to all Branches) Sem</th><th>: II</th><th>Cat</th><th>tegory:</th><th>Η</th><th>SMC</th></t<>	Programme:	B.E./B.Tech. (Common to all Branches) Sem	: II	Cat	tegory:	Η	SMC
Course Outcomes: The Students will be able to CO1: Remember words and its meanings for the specific purpose. CO2: Understand the basic nuances of language CO3: Apply written communication methodologies at workplace. CO4: Develop Listening skill to respond and to gather information. CO5: Interpret the text using comprehending skill. CO6: Involve in professional correspondences confidently. UNIT 1 INTRODUCTION TO TECHNICAL ENGLISH 6 Listening- Listening to talks mostly of a scientific/technical nature and completing information-gap exercise. Speaking – Asking for and giving directions. Reading – reading short technical texts, Newspapers. Writing Purpose statements, Extended definitions, Writing Instructions & Recommendations, Checklists. Vocabula Development - Technical Vocabulary. Language Development – Subject Verb Agreement. UNIT 11 READING AND STUDY SKILLS 6 Listening - Listening to longer technical talks and completing exercises based on them. Speaking – Describin a process. Reading – Reading longer technical texts, Newspapers identifying various transitions in a tex saragraphing. Writing - Techniques for writing Precisely. Vocabulary Development -vocabulary used in form etters/emails and reports. Language Development - Personal & Impersonal Passive voice, Numeric adjectives. 6 Listening - Listening to classroom lectures on Engineering / Technology. Speaking – Introduction to Technic r	Prerequisites:	Acquire Proficiency in Technical Communication					
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UNIT 1 INTRODUCTION TO TECHNICAL ENGLISH 6 Listening - Listening to talks mostly of a scientific/technical nature and completing information-gap exercise Speaking – Asking for and giving directions. Reading – reading short technical texts, Newspapers. Writing Purpose statements, Extended definitions, Writing Instructions & Recommendations, Checklists. Vocabula Development - Technical Vocabulary. Language Development – Subject Verb Agreement. UNIT 11 READING AND STUDY SKILLS 6 Listening - Listening to longer technical talks and completing exercises based on them. Speaking – Describin a process. Reading – Reading longer technical texts, Newspapers identifying various transitions in a texparagraphing. Writing - Techniques for writing Precisely. Vocabulary Development -vocabulary used in form etters/emails and reports. Language Development - Personal & Impersonal Passive voice, Numeric adjectives. 6 UNIT 11 TECHNICAL WRITING AND GRAMMAR 6 Listening - Listening to classroom lectures on Engineering / Technology. Speaking – Introduction to Technic presentations. Reading – Reading longer texts both general and Technical, practice in rapid reading. Writin Describing a process, Use of sequence words, Causes and Effects Vocabulary Development - Sequence word Nomial compounds, Misspelled words. Language Development - Embedded sentences. 6 UNIT 11 REPORT WRITING 6 Listening - Listening to documentaries and Making notes. Speaking – Mechanics of presentations. Reading Reading for detailed comprehension. Writing - Job app	CO1: Remember CO2: Understand CO3: Apply writt CO4: Develop Li CO5: Interpret th	words and its meanings for the specific purpose. I the basic nuances of language ten communication methodologies at workplace. stening skill to respond and to gather information. e text using comprehending skill.					
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UNIT 11 READING AND STUDY SKILLS 6 Listening - Listening to longer technical talks and completing exercises based on them. Speaking – Describin a process. Reading – Reading longer technical texts, Newspapers identifying various transitions in a tex paragraphing. Writing - Techniques for writing Precisely. Vocabulary Development -vocabulary used in form etters/emails and reports. Language Development - Personal & Impersonal Passive voice, Numeric adjectives. 6 UNIT 111 TECHNICAL WRITING AND GRAMMAR 6 Listening - Listening to classroom lectures on Engineering / Technology. Speaking – Introduction to Technic presentations. Reading – Reading longer texts both general and Technical, practice in rapid reading. Writin, Describing a process, Use of sequence words, Causes and Effects Vocabulary Development - Sequence words. Nominal compounds, Misspelled words. Language Development - Embedded sentences. 6 UNIT 1V REPORT WRITING 6 Listening to documentaries and Making notes. Speaking – Mechanics of presentations. Reading Pevelopment - Finding suitable synonyms, Paraphrasing. Language Development – Clauses, If conditionals. 6 Listening - TED/Ink talks. Speaking – Participating in a Group discussion. Reading – Reading an Understanding Technical articles. Writing – Writing reports, Minutes of Meeting, Introduction and Conclusio Vocabulary Development - Verbal analogies. Language Development - Reported speech.	Purpose statemen	ts, Extended definitions, Writing Instructions & Recom	mendati	ons, C	Checklists.		-
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UNIT 1II TECHNICAL WRITING AND GRAMMAR 6 Listening - Listening to classroom lectures on Engineering / Technology. Speaking – Introduction to Technic presentations. Reading – Reading longer texts both general and Technical, practice in rapid reading. Writin Describing a process, Use of sequence words, Causes and Effects Vocabulary Development - Sequence words Nominal compounds, Misspelled words. Language Development - Embedded sentences. 6 UNIT 1V REPORT WRITING 6 Listening - Listening to documentaries and Making notes. Speaking – Mechanics of presentations. Reading for detailed comprehension. Writing - Job application, cover letter, Resume preparation. Vocabula Development - Finding suitable synonyms, Paraphrasing. Language Development – Clauses, If conditionals. UNIT V GROUP DISCUSSION AND JOB APPLICATIONS 6 Listening - TED/Ink talks. Speaking – Participating in a Group discussion. Reading – Reading an Understanding Technical articles. Writing – Writing reports, Minutes of Meeting, Introduction and Conclusio Vocabulary Development - Verbal analogies. Language Development - Reported speech.	Listening - Listen	ing to longer technical talks and completing exercises ba					escribing
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1. Sudharshana, N.P. and C.Savitha. English for Technical Communication. New Delhi: Oxford University Press, 2017.

References:

- 1. www.bbc.co.uk/learning english
- 2. www.bec cambridge english.org
- 3. www.englishenglish101.com
- 4. www.islcollective.com

Extensive Reading

Course Outcomes					Prog	am O	utcor	nes (P	'Os)				Pr Ot	ogram utcome	Specif s (PSO	ic s)
Outcomes	PO1													PSO2	PSO3	PSO4
CO1		2		3		1		2	3	3	3	3				
CO2						2		3	3	3	3	3				3
CO3		3		2	3	2	3	2	3	3	2	3				
CO4										2		3				
CO5									3	3	2	3				
CO6			2	2								3				

1. Kalam, Abdul. The Wings of Fire. Hyderabad: UP, 1999. Print.

191HS2	22	DIFFI	ERENTIAL EQ	UATIONS ANI) NUMER	ICAL	METHO	DS	L-T-P	C
Programm	ne: Bl	E. / B.Te	ch. (Common to	all branches)	Sem:	II		Cat	3-1-0 tegory:	4 BSC
Prerequisi		2.7 D .10	Calculus and Li	,	Sem			Ca		Doe
Aim:			To analyze the	engineering prob dying ODE and 1					athematical s	kills
	Course (Jutcome	· ·							
	The	students	will be able to							
			method to solve	-		quatior	ıs			
			method to solve	-						
		-	iscrete data by m							
			merical integrati	• •		•				
			tion for the IVPs	•	•		•	thods		
	CO6 : Fin	d the solu	tion of BVPs in	PDE using finite	e difference	metho	ods			
	UNIT 1			ORDINARY			-			12
	•		r differential equ						-	rameters
	Cauchy's	and Leg	endre's linear equ	uations – Simult	aneous first	order	linear equa	ations wi	th constant c	oefficient
	UNIT 1I			PARTIAL			-			12
		-	ial differential eq		-	-			• •	
	-		ferential equati		-			– Linea	ir homogeno	ous parti
			ons of second and							
	UNIT 11 DIFFER		TION OF EQUATION	ATION & INTI	ERPOLAT	ION, I	NUMERI	CAL		12
			omial and transco	endental equation	ns – Newton	n Raph	son metho	d - Interr	olation using	2 Newton
		•	vard difference f	•		-		-	•	-
	and Lagr	ange's fo	rmulae - Numeri	cal differentiation	n using Ne	wton's	forward a	nd backv	vard differen	ce formu
	- Numeri	cal Integr	ation – Trapezoi	dal rule and Sim	pson's 1/3 rd	ⁱ rule.				
	UNIT 1V		MERICAL SO					-		12
	-		ethod – Euler's r						-	
	Milne's p	oredictor	- corrector meth	ods for solving	first order e	equatio	ons – Finite	e differer	nce methods	for solvir
	second or	-								
	UNIT V	BOUND	ARY VALUE P	ROBLEMS OF	PARTIA	L DIF	FERENTI	AL EQU	JATIONS	12
			solution of one d two dimensiona			•	cit and imp	licit metl	nods – One d	imension
								Т	otal Periods	60
	Text boo		T' 1 T ' ' '		T1:	4	/' T71	D 11	1	2007
			Higher Engineerin	•	•					2005.
			d Grewal J. S., "		oas in Engi	neerin	g and Scie	nce≃, Kh	anna	
			w Delhi, (2004)	•						
1	Reference		1D "1 dream 11	Enginearie - M-4	homotice (10000001	Edition	oomeen F	durantian In .	2002
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			n. M.K., "Engine	-	ics, volum	ie i an	u 11 Kevise	eu eniarg	eu rourth Eo	muon, Th
			ishing Company,		tion 041 1	tion T	ahn 117:1	Sec. 20	0.1	
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	-		nd Canale R.P., '			-				111, 2007.
			nd Wheatley P.C	., Applied Nur	nerical Ana	1ys1s",	rearson E	aucation	Asia,	
	INEW	Delhi, (2	.000).							

Course Outcomes					Prog	ram O	utcon	nes (P	Os)			Pi Ot	ogram utcome	Specif s (PSO	ic s)
Outcomes	PO1	PO2	PO3	PO4	PO5	PO12	PSO1	PSO2	PSO3	PSO4					
CO1	2	3		3							3		2	1	
CO2	2	3		3							3				1
CO3	1	2		3							3	2			
CO4	1	1		1									2	2	
CO5	1	1									1				
CO6	2	2										2			2

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191HS24	APPLIED MATERIALS SCIENCE	£			L-T-P		С							
					2-0-0		2							
Programme:	B.E/B. Tech. (MECH, CIVIL & BIO-TECH) Sem: II Category: BSC													
Prerequisites:	Engineering Physics													
AIM:	To endow the students with the fundamentals of physics, materials and apply new ideas in the field of Engineering and Technology.													
Course Outcon	ourse Outcomes:													

The Students will be able to

CO1: Understand the theory and processing of conducting, superconducting materials.

CO2: Acquire knowledge of polymer and ceramic materials.

CO3: Gain knowledge about composites materials and applications.

CO4: Enhance the knowledge new materials.

CO5: Understand about some exciting properties of nanomaterials

CO6: Know about Characterization Techniques of materials

CONDUCTING MATERIALS

Conductors: classical free electron theory of metals – Electrical and thermal conductivity – Wiedemann – Franz law – Lorentz number – Draw backs of classical theory –Fermi distribution function – Effect of temperature on Fermi Function – Density of energy states – carrier concentration in metals.

Super Conductors: properties - Types of super conductors - Applications of superconductors - SQUID, cryotron, magnetic levitation.

UNIT 1I

UNIT 1

POLYMER AND CERAMIC MATERIALS

Polymers–Types of polymers–Thermal, Mechanical and Electrical Properties–Conducting Polymers, Bio-Polymers and High temperature polymers - applications

Ceramics-Properties and applications-ZrO2, Al2O3, SiC,

UNIT 1II

COMPOSITE MATERIALS

Definition-function of matrix and reinforcement in composites-classification of composites based on reinforcement-types of composite materials-polymers, metallic and ceramic matrix composites. Law of mixtures. Comparison with conventional materials. Fabrication of metal matrix and ceramic matrix composites-properties and uses

UNIT 1V

NEW MATERIALS

Metallic glasses: Preparation, properties and applications. **Shape memory alloys (SMA):** Characteristics - Properties of NiTi alloy – Applications -Advantages and disadvantages of SMA. **Bio Materials :** Classification – Properties – Applications

UNIT V

NANO MATERIALS AND CHARACTERISATION TECHNIQUES

Nanomaterials: synthesis – chemical vapour deposition– ball milling - properties of nanoparticles and applications- Carbon nanotubes- types

Characterization: Principle, Characterization and applications of X- Ray diffraction – Scanning Electron Microscope – Transmission Electron Microscope.

Total Periods 30

Text books:

1. William D. Callister, Jr., "Material Science and Engineering", John Wiley & Sons Inc., Seventh Edition, New Delhi (2017).

2. Ragavan, V., "Material science and Engineering", Prentice Hall of India (2004).

References:

- 1. Koch C., "Nanostructured materials: processing, properties and applications", William Andrew Pub (2011).
- 2. Charles P. Poole and Frank J.Ownen., "Introduction to Nanotechnology", Wiley India (2007)
- 3. Charles Kittel., "Introduction to solid state Physics", John Wiley & Sons, 7th editions, Singapore (2012)
- 4. Kasap, S.O. "Principles of Electronic Materials and Devices", McGraw -Hill Education, 2016.
- 5. Umesh K Mishra & Jasprit Singh, "Semiconductor Device Physics and Design", Springer, 2014.

Course Outcomes				I	Progr	am O	utcor	nes (I	POs)				Pr Ou	ogram Itcome	Specif s (PSC	fic Ds)
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3	1	1	1	1		1					1	1	1	1	1
CO2	3	1	2	1	1		1					1	1	1	1	1
CO3	3	1	1	2	1		1					1	1	1	1	1
CO4	3	2	2	2	2		2					1	1	1	1	1
CO5	3	2	2	3	2		1					2	1	1	1	2
CO6	3	2	2	1	2		1					2	2	1	1	2

191HS25	ENVIRONMENTAL SCIEN	ENVIRONMENTAL SCIENCE										
	<u>.</u>			2-0-0	2							
Programme:	B.E. / B.Tech. (Common to all branches)	oranches) Sem:		Category:	BSC							
Prerequisites:	Basic Science											
Aim:	To Impart the social groups and individuals to environmental degradation	acquire kn	owled	ge of pollution	and							
Course Outcom	es:											
At the end	of the course the student will be able to											
CO1: Understan	d the basic concepts of environment and energy re	sources										
CO2: Get knowl	edge about the ecosystem											
CO3: Identify an	analyze causes, effects and control measures of	various ty	pes of	pollution.								
CO4: Get the kn	owledge about types of disaster and mitigation me	easures	_	_								
	the impact of assist issues and alimete shares											

CO5: Understand the impact of social issues and climate change

CO6: Understand to create the green environment.

UNIT 1	ENVIRONMENT AND ENERGY RESOURCES	6
Environment- defini	ition, scope and importance – Need for public awareness – Forest resources-de	eforestation-
Energy resources: G	rowing energy needs, renewable (solar energy and wind energy) and non-renew	vable energy
sources- Nuclear en	ergy – fission and fusion reactions and light water nuclear reactor for powe	er generation
(block diagram only), Petroleum processing and fractions	-
UNIT 1I	ECOSYSTEM	6
Concept of an ecosy	ystem - Structure and function of an ecosystem: Producers, consumers and d	ecomposers,
Energy flow in the e	cosystem-Nitrogen cycle, Food chains, food webs and ecological pyramids - l	Introduction,
types, characteristic	features, structure and function of the Forest ecosystem and Aquatic ecosystem	ms (lake and
rivers)		
UNIT 111	ENVIRONMENTAL POLLUTION	6
Definition – Causes	, effects and control measures of: (a) Air pollution (b) Water pollution (c) Mar	rine
	pollution. Solid waste Management: Causes, effects and control measures of u	
industrial wastes. R	ole of an individual in prevention of pollution –Disaster management: floods-	landslides.
UNIT 1V	SOCIAL ISSUES AND EARTH'S CLIMATE SYSTEM	6
Population-variation	among nation-Unsustainable to Sustainable development – Urban problen	ns related to
-	servation, rain water harvesting– climate change, global warming, acid rain,	
depletion.	, 6 6,6 6, ,	5
UNIT V	GREEN CHEMISTRY	6
Introduction to green	n chemistry- 12 principles of green chemistry-toxicology and green chemistry	- energy and
green chemistry-edu	acation in green chemistry. Reuse and recycling technologies-material selecti	an fan anaan
0 •································	······································	on for green
design- recycled war		on for green
• •		30
design- recycled wa Text books:	ter technology. Total Periods:	-
design- recycled war Text books: 1. A. Ravikrishnan	ter technology. Total Periods: , "Environmental Science and Engineering, Sri Krishna Hitech Publishing	-
design- recycled wa Text books: 1. A. Ravikrishnan Company Private	ter technology. Total Periods: , "Environmental Science and Engineering, Sri Krishna Hitech Publishing e Limited, 2010.	30
design- recycled wa Text books: 1. A. Ravikrishnan Company Private 2. Benny Joseph, "H	ter technology. Total Periods: , "Environmental Science and Engineering, Sri Krishna Hitech Publishing	30
design- recycled wat Text books: 1. A. Ravikrishnan Company Private 2. Benny Joseph, "H References:	ter technology. Total Periods: , "Environmental Science and Engineering, Sri Krishna Hitech Publishing e Limited, 2010. Environmental Science and Engineering", Tata McGraw-Hill, New Delhi, 200	30 16.
design- recycled wa Text books: 1. A. Ravikrishnan Company Private 2. Benny Joseph, "F References: 1. Anubha Kaushi	ter technology. Total Periods: , "Environmental Science and Engineering, Sri Krishna Hitech Publishing e Limited, 2010. Environmental Science and Engineering", Tata McGraw-Hill, New Delhi, 200 ik, C.P. Kaushik, "Environmental Science and Engineering", New Age	30 16.
design- recycled wa Text books: 1. A. Ravikrishnan Company Private 2. Benny Joseph, "H References: 1. Anubha Kaushi Publishers, 2016	ter technology. Total Periods: , "Environmental Science and Engineering, Sri Krishna Hitech Publishing e Limited, 2010. Environmental Science and Engineering", Tata McGraw-Hill, New Delhi, 200 ik, C.P. Kaushik, "Environmental Science and Engineering", New Age 1 5.	30 16. International
design- recycled wa Text books: 1. A. Ravikrishnan Company Private 2. Benny Joseph, "F References: 1. Anubha Kaushi Publishers, 2016 2. Benny Joseph, E	ter technology. Total Periods: , "Environmental Science and Engineering, Sri Krishna Hitech Publishing e Limited, 2010. Environmental Science and Engineering", Tata McGraw-Hill, New Delhi, 200 k, C.P. Kaushik, "Environmental Science and Engineering", New Age 1 5. Environmental Science and Engineering, Tata McGraw-Hill Publishing Compa	30 16. International
design- recycled wa Text books: 1. A. Ravikrishnan Company Private 2. Benny Joseph, "H References: 1. Anubha Kaushi Publishers, 2016 2. Benny Joseph, E Delhi, ISBN: 00	ter technology. Total Periods: , "Environmental Science and Engineering, Sri Krishna Hitech Publishing e Limited, 2010. Environmental Science and Engineering", Tata McGraw-Hill, New Delhi, 200 ik, C.P. Kaushik, "Environmental Science and Engineering", New Age 1 5. Environmental Science and Engineering, Tata McGraw-Hill Publishing Compa 070601690, 2006.	30 06. International .ny Ltd, New
design- recycled wa Text books: 1. A. Ravikrishnan Company Private 2. Benny Joseph, "H References: 1. Anubha Kaushi Publishers, 2016 2. Benny Joseph, E Delhi, ISBN: 00	ter technology. Total Periods: , "Environmental Science and Engineering, Sri Krishna Hitech Publishing e Limited, 2010. Environmental Science and Engineering", Tata McGraw-Hill, New Delhi, 200 ik, C.P. Kaushik, "Environmental Science and Engineering", New Age 1 6. Environmental Science and Engineering, Tata McGraw-Hill Publishing Compa 070601690, 2006. har, Introduction to Environmental Science and Engineering, Tata McGraw Hill	30 06. International .ny Ltd, New

Course Outcomes	Program Outcomes (POs)									Program Specific Outcomes (PSOs)						
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3	1	3	1	1			1		2		1	2	2		
CO2		2	1	1			1	1	1	2	1	1	2	2		
CO3	2	1		2				1		1		1	3	3		3
CO4	1	2	1		2							1	1			
CO5	2	3	2		2			2		2	1	2	2			2
CO6	3	2	3		2			2		2	1	3	3	2		3

	BASIC ELECTRICAL AND ELEC	FRONICS	5	L-T-P	С		
	ENGINEERING			3-0-0	3		
Programme:	B.E., (CIVIL, MECH, BIO-TECH)	Sem:	II	Category:	ES		
Prerequisites:	Algebra, calculus and electrostatics	Sem.		Category.	ES		
<u>i rerequisites.</u>	To provide comprehensive idea about AC and	d D C circ	uit analy	sis working prir	ciples and		
Aim:	applications of basic machines in electrical of system.						
Course Outcom							
The Students wil	l be able to						
CO1: Analyze I	DC circuits using basic laws.						
	AC circuits using basic laws.						
	d the operation of DC machines and its applica	tions.					
	ate about AC machines and its applications.						
	construction, working and characteristics of the	e semiconc	luctor de	evices.			
CO6: Design ba	sic combinational and sequential logic circuits.						
UNIT 1	ELECTRICAL C	IRCUITS			9		
	irchhoff's Laws -Reduction of series and para			and Nodal Analy	sis of DC		
	uction to AC Circuits - RMS Value, Average			•			
	Single Phase AC series circuits with R, RL, R			•	•		
*	its- Star and delta connected balanced load.						
*							
UNIT 1I	DC MACHINES &	TRANSF	ORME	R	9		
DC Generators -	construction, principle of operation, Types, E	MF equati	ons and	applications. DO	C Motors -		
DC Generators - operation, Types	construction, principle of operation, Types, E , Speed and torque equation – speed control of	MF equati DC shunt	ons and motors.	applications. DO	C Motors -		
DC Generators - operation, Types	construction, principle of operation, Types, E , Speed and torque equation – speed control of etails and operation, Types, EMF equation, tran	MF equati DC shunt	ons and motors.	applications. DO	C Motors -		
DC Generators - operation, Types Constructional d UNIT 111	construction, principle of operation, Types, E , Speed and torque equation – speed control of etails and operation, Types, EMF equation, tran AC MACHINES	MF equati DC shunt sformation	ons and motors. 1 ratio.	applications. DC Single Phase Tra	C Motors - nsformer - 9		
DC Generators - operation, Types Constructional d UNIT 111 Single phase indu	construction, principle of operation, Types, E , Speed and torque equation – speed control of etails and operation, Types, EMF equation, tran AC MACHINES uction motor - construction, operation and applied	MF equati DC shunt sformation cations, Th	ons and motors. n ratio. nree pha	applications. DC Single Phase Tra se induction moto	C Motors - nsformer - 9 pr – Types,		
DC Generators - operation, Types Constructional de UNIT 111 Single phase indu Construction and	construction, principle of operation, Types, E , Speed and torque equation – speed control of etails and operation, Types, EMF equation, tran <u>AC MACHINES</u> uction motor - construction, operation and appli- l operation, Torque equation, slip torque character	MF equati DC shunt a sformation cations, The eristics, Sy	ons and motors. n ratio. nree pha nchronc	applications. DC Single Phase Tra se induction moto	C Motors - nsformer - 9 pr – Types,		
DC Generators - operation, Types Constructional d UNIT 1II Single phase indu Construction and and operation, El	construction, principle of operation, Types, E , Speed and torque equation – speed control of etails and operation, Types, EMF equation, tran <u>AC MACHINES</u> uction motor - construction, operation and applied operation, Torque equation, slip torque characted MF equation - Synchronous motors – principle	MF equati DC shunt sformation cations, Th eristics, Sy of operatic	ons and motors. n ratio. nree pha nchronc	applications. DC Single Phase Tra se induction moto	C Motors - nsformer - 9 or – Types onstruction		
DC Generators - operation, Types Constructional d UNIT 111 Single phase indu Construction and and operation, E UNIT 1V	construction, principle of operation, Types, E , Speed and torque equation – speed control of etails and operation, Types, EMF equation, tran <u>AC MACHINES</u> uction motor - construction, operation and appli- l operation, Torque equation, slip torque character MF equation - Synchronous motors – principle <u>SEMICONDUCTOR D</u>	MF equati DC shunt a sformation cations, Th eristics, Sy of operation DEVICES	ons and motors. n ratio. nree pha nchroncon.	applications. DC Single Phase Tra se induction moto us generators - co	C Motors - nsformer - 9 or – Types onstruction 9		
DC Generators - operation, Types Constructional de UNIT 1II Single phase indu Construction and and operation, E UNIT 1V Introduction to se	construction, principle of operation, Types, E , Speed and torque equation – speed control of etails and operation, Types, EMF equation, tran <u>AC MACHINES</u> uction motor - construction, operation and applied operation, Torque equation, slip torque characted MF equation - Synchronous motors – principle <u>SEMICONDUCTOR D</u> emiconductors-PN Junction Diode – characteris	MF equati DC shunt sformation cations, Th eristics, Sy of operatic EVICES tics, break	ons and motors. n ratio. nree pha nchronc on. down et	applications. DC Single Phase Tra se induction moto us generators - co ffect and application	C Motors - nsformer - 9 or – Types, onstruction 9 ions - Half		
DC Generators - operation, Types Constructional d UNIT 111 Single phase indu Construction and and operation, E UNIT 1V Introduction to so wave and Full wa	construction, principle of operation, Types, E , Speed and torque equation – speed control of etails and operation, Types, EMF equation, tran <u>AC MACHINES</u> uction motor - construction, operation and applied operation, Torque equation, slip torque characted MF equation - Synchronous motors – principle <u>SEMICONDUCTOR D</u> emiconductors-PN Junction Diode – characteristics and	MF equati DC shunt sformation cations, Th eristics, Sy of operation EVICES ttics, break voltage rej	ons and motors. n ratio. nree pha nchroncon. down ef gulator.	applications. DC Single Phase Tra se induction moto us generators - co ffect and application	C Motors - nsformer - 9 or – Types, onstruction 9 ions - Half		
DC Generators - operation, Types Constructional de UNIT 111 Single phase indu Construction and and operation, E1 UNIT 1V Introduction to se wave and Full wa – operation of N	construction, principle of operation, Types, E , Speed and torque equation – speed control of etails and operation, Types, EMF equation, tran AC MACHINES uction motor - construction, operation and applied operation, Torque equation, slip torque character MF equation - Synchronous motors – principle SEMICONDUCTOR D emiconductors-PN Junction Diode – characteristics ave rectifiers, Zener Diode - characteristics and PN and PNP, characteristics of CB, CE, CC cor	MF equati DC shunt is sformation cations, The eristics, Sy of operatic DEVICES tics, break voltage rep figuration	ons and motors. n ratio. nree pha nchroncon. down ef gulator.	applications. DC Single Phase Tra se induction moto us generators - co ffect and application	C Motors - nsformer - 9 or – Types, onstruction 9 ions - Half		
DC Generators - operation, Types Constructional d UNIT 111 Single phase indu Construction and and operation, E UNIT 1V Introduction to se wave and Full wa – operation of NI UNIT V	construction, principle of operation, Types, E , Speed and torque equation – speed control of etails and operation, Types, EMF equation, tran <u>AC MACHINES</u> uction motor - construction, operation and applie operation, Torque equation, slip torque characted MF equation - Synchronous motors – principle <u>SEMICONDUCTOR D</u> emiconductors-PN Junction Diode – characterist ave rectifiers, Zener Diode - characteristics and PN and PNP, characteristics of CB, CE, CC cor DIGITAL ELECTE	MF equati DC shunt sformation cations, Th eristics, Sy of operatic EVICES tics, break voltage re afiguration RONICS	ons and motors. n ratio. nree pha nchroncon. down et gulator. s.	applications. DC Single Phase Tra se induction moto us generators - co ffect and applicati Bipolar Junction	C Motors - nsformer - 9 or – Types onstruction 9 ions - Half Transistor 9		
DC Generators - operation, Types Constructional de UNIT 111 Single phase indu Construction and and operation, E1 UNIT 1V Introduction to se wave and Full wa – operation of NI UNIT V Number System	construction, principle of operation, Types, E , Speed and torque equation – speed control of etails and operation, Types, EMF equation, tran AC MACHINES uction motor - construction, operation and appli- loperation, Torque equation, slip torque character MF equation - Synchronous motors – principle SEMICONDUCTOR D emiconductors-PN Junction Diode – characteristics ave rectifiers, Zener Diode - characteristics and PN and PNP, characteristics of CB, CE, CC cor DIGITAL ELECTE – Binary, octal, hexadecimal, Logic Gates, Half	MF equati DC shunt a sformation cations, The eristics, Sy of operatic EVICES tics, break voltage re- afiguration RONICS F and Full 2	ons and motors. n ratio. nree pha nchroncon. down ei gulator. s.	applications. DC Single Phase Tra se induction moto us generators - co ffect and applicati Bipolar Junction - Flip-Flops –RS,	C Motors - nsformer - 9 or – Types onstruction 9 ions - Half Transiston 9 JK, T and		
DC Generators - operation, Types Constructional d UNIT 111 Single phase indu Construction and and operation, E UNIT 1V Introduction to se wave and Full wa – operation of N UNIT V Number System D - Counters – s	construction, principle of operation, Types, E , Speed and torque equation – speed control of etails and operation, Types, EMF equation, tran AC MACHINES uction motor - construction, operation and applied operation, Torque equation, slip torque character MF equation - Synchronous motors – principle SEMICONDUCTOR D emiconductors-PN Junction Diode – characteristics and PN and PNP, characteristics of CB, CE, CC cor DIGITAL ELECTE – Binary, octal, hexadecimal, Logic Gates, Half ynchronous up counter, synchronous down counter	MF equati DC shunt a sformation cations, The eristics, Sy of operatic EVICES tics, break voltage re- afiguration RONICS F and Full 2	ons and motors. n ratio. nree pha nchroncon. down ei gulator. s.	applications. DC Single Phase Tra se induction moto us generators - co ffect and applicati Bipolar Junction - Flip-Flops –RS,	C Motors - nsformer - 9 or – Types onstruction 9 ions - Half Transiston 9 JK, T and		
DC Generators - operation, Types Constructional d UNIT 111 Single phase indu Construction and and operation, E UNIT 1V Introduction to se wave and Full wa – operation of N UNIT V Number System D - Counters – s	construction, principle of operation, Types, E , Speed and torque equation – speed control of etails and operation, Types, EMF equation, tran AC MACHINES uction motor - construction, operation and appli- loperation, Torque equation, slip torque character MF equation - Synchronous motors – principle SEMICONDUCTOR D emiconductors-PN Junction Diode – characteristics ave rectifiers, Zener Diode - characteristics and PN and PNP, characteristics of CB, CE, CC cor DIGITAL ELECTE – Binary, octal, hexadecimal, Logic Gates, Half	MF equati DC shunt a sformation cations, The eristics, Sy of operatic EVICES tics, break voltage re- afiguration RONICS F and Full 2	ons and motors. n ratio. nree pha nchroncon. down ei gulator. s.	applications. DC Single Phase Tra se induction moto us generators - co ffect and applicati Bipolar Junction - Flip-Flops –RS,	C Motors - nsformer - 9 or – Types onstruction 9 ions - Half Transiston 9 JK, T and nchronous		

Text books:

1. Muthusubramanian R, Salivahanan S, "Basic Electrical, Electronics and Computer Engineering", McGraw Hill, New Delhi, 2009.

2. B L Theraja, AK Theraja, 'A Text book of Electrical Technology: Volume 2 AC and DC Machines', S.Chand; Twenty Third edition, 2006.

References:

- 1. V N Mittle, Arvind Mittle "Basic Electrical Engineering", McGraw Hill, New Delhi, 2005.
- 2. Nagsarkar T K and Sukhija M S, "Basics of Electrical Engineering", Oxford University press (2012).
- 3. V K Mehta, Rohitmehta "Principles of Electronics", S.Chand& Company Ltd, (2015).
- 4. Mahmood Nahvi and Joseph A. Edminister, "Electric Circuits", Schaum' Outline Series, McGraw Hill, (2014).
- 5. R.S. Sedha, "A Textbook of Applied Electronics" S. Chand & Co., 2008.

Course Outcomes	Program Outcomes (POs)									Program Specific Outcomes (PSOs)						
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3	2	2	1	2	1							3	2		
CO2	2	2		2		2								1	2	3
CO3	2	2		2									2		2	
CO4	2	2	3		1											2
CO5	2	2	3		1											2

191HS27	PHYSICS AND CHEMISTRY LABOR	II	L-T-P	С					
				0-0-2	1				
Programme:	B.E/B.Tech (Common to all Branches)	B.Tech (Common to all Branches) Sem: II Category: BS							
Prerequisites:	Engineering Physics & Engineering Chemistry								
AIM: To introduce the basic Physics concepts through experiments and to impart knowledge on the application of chemistry in engineering branches.									
Course Outcomes:									
The Students will be a	ble to								
CO1: Learn the interf	erence of light and young's modulus of the mate	erials							
CO2: Understand the	properties of flow of the liquid.								
CO3: Know the band	gap of material and resistance of the given coil.								
CO4: Determine the c	juantity of unknown solution by instrumental tee	chnique.							
CO5: Determine the c	concentration of an identified analyte by volume	tric analys	sis						
CO6: Analyze the characteristics of water.									

	LIST OF EXPERIMENTS - PHYSICS PART (A minimum of five experiments shall be offered)	
S.No	NAME OF THE EXPERIMENT	
1)	Determination of thickness of thin wire – Air wedge method	3
2)	Determination of Young's modulus of the material – Uniform bending	3
3)	Determination of viscosity of liquid – Poiseuille's method.	3
4)	Determination of wavelength of mercury spectrum- Spectrometer Grating.	3
5)	Determination of Band Gap of a semiconductor material.	3
6)	Determination of specific resistance of a given coil of wire – Carey Foster Bridge.	3

	LIST OF EXPERIMENTS – CHEMISTRY PART	
S.No	NAME OF THE EXPERIMENT	
1)	Estimation of HCl by pH metry	3
2)	Estimation of Copper in brass by EDTA method.	3
3)	Estimation of iodine in iodized salt with thiosulfate	3
4)	Determination of percentage of calcium in limestone by EDTA method	3
5)	Determination of DO in water (Winkler's method)	3

191EE17	ELECTRICAL AND ELECTRONICS ENGI	NEERIN	G	L-T-P	С
	LABORATORY			0-0-4	1
Programme:	B.E. Electrical and Electronics Engineering	Sem:	II	Category:	ES
AIM:	To expose the students to basic laws, characterist machines and transformers and give them experimer	ics of di	odes		of D.C.
Course Outcon					
The Students wi	ll be able to				
CO1. Apply the	circuit theory concepts and analyze the outcome.				
· · ·	he characteristics of diodes.				
CO3. Analyse c	haracteristics of transistor.				
	e operation of rectifiers.				
•	rious characteristics of DC Machines.				
CO6. Obtain va	rious characteristics of AC Machines.				
LIST OF EXP	ERIMENTS				
1.	Verification of Ohms law				
2.	Verification of Kirchhoff's voltage and current laws				
3.	V – I characteristics of P-N Junction Diode and Zener I	Diode			
4.	Input and Output characteristics of CE configuration of	NPN trai	nsistoi	•	
	Half wave Rectifier				
6.	Full wave Rectifier				
7.	Speed Control of D.C. Shunt Motor				
	Load Test on Single phase transformer				
	Load Test on three phase squirrel cage induction motor				
	Open Circuit characteristic of an Alternator				
	*		T	otal Periods	45

Course Outcomes	8 ()								Program Specific Outcomes (PSOs)							
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	1	2		2					2				2	3	3	3
CO2		2	3	2					2					2		3
CO3	2	2		2					2				2	3	3	
CO4	2	2		2					2				1	2	3	
CO5	1	2		2					2				1	2	3	
CO6		2	3	2					2					2		3

9

9

9

9

9

191HS31	TRANSFORMS AND DISCRETE MATHEMATICS L-T-P									
			3-0-	0	3					
Programme:	B.E. / B.Tech. (Common to all branches)	Sem:	III	Cat	egory:	BSC				
Aim:	To introduce basic mathematical ideas such as reasoning techniques, basic counting techniques and their applications.									
Course Outeen	2051									

Course Outcomes:

The students will be able to

CO1: Apply Laplace transform to solve first and second order differential equations with elementary function.

CO2: Explain the Fourier transform and with their properties.

CO3: Determine Z-inverse transform using convolution theorem and partial fraction method.

CO4: Apply mathematical induction and prove a relation.

CO5: Invent Eulerian and Hamiltonian paths to find shortest paths

CO6: Make use of graph theoretic models to solve basic problems in networks.

LAPLACE TRANSFORMS

FOURIER TRANSFORMS

Laplace transform — Properties of Laplace Transforms – Laplace Transform of periodic functions – Inverse Laplace transforms by partial fraction method and Convolution theorem (excluding proof) – Solving ODE using Laplace transformation techniques.

UNIT 1I

UNIT 1

Fourier integral theorem (without proof) – Fourier transform pair – Sine and Cosine transforms – Properties – Transforms of simple functions – Convolution theorem – Parseval's identity.

UNIT 1II

Z-TRANSFORMS

Z-transforms – Elementary properties – Inverse Z-transform – Convolution theorem – Formation of difference equations – Solution of difference equations using Z-transform.

UNIT 1V

INTRODUCTION TO COUNTING

Decision problems on Propositional logic – Basic counting techniques – inclusion & exclusion- Pigeonhole principle –Permutations and combinations-Recurrence relations-Solving Linear recurrence relations and generating functions

UNIT V

INTRODUCTION TO GRAPHS

Graphs and their basic properties – Graph terminology and special types of graphs - Representing graphs and graph isomorphism – Euler and Hamilton paths.

Total Periods: 45

Text Book

- 1. B.S. Grewal, 'Higher Engineering Mathematics', Thirty Sixth Edition, Khanna Publishers, Delhi, 2005.
- 2. Grewal B.S. and Grewal J. S., "Numerical Methods in Engineering and Science", Khanna Publishers, New Delhi, (2004).

Reference

- 1. Greenberg. *M.D.* "Advanced Engineering Mathematics, Second Edition, Pearson Education Inc. (First Indiar reprint), 2002
- 2. Venkataraman. M.K., "Engineering Mathematics", Volume I and II Revised enlarged Fourth Edition, The National Publishing Company, Chennai, 2004.

3. Trembly J. P and Manohar R, "Discrete Mathematical Structures with Applications to Computer Science",

Tata McGraw–Hill Pub. Co. Ltd, NewDelhi, 30thRe-print (2007).

4 Dr.P.Kandasamy,Dr.K.Thilagavathy,Dr.K.Gunavathy, "Transforms and Partial Differential Equation", S.Chand & Company Ltd. Ram Nagar,New Delhi.

Course Outcomes					Prog	ram O	utcor	nes (P	Os)					ogram itcomes		
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
C01	1	2		2					2				2	3	3	3
CO2		2	3	2					2					2		3
CO3	2	2		2					2				2	3	3	
CO4	2	2		2					2				1	2	3	
CO5	1	2		2					2				1	2	3	
CO6		2	3	2					2					2		3

191BT31	BIOLOGY FOR ENGINEER	S		L-T-P	$\frac{C}{100}$
		n		Regulat	5
Programme:	B.E./B.Tech. (Common to all Branches)	Sem:	3	Category:	BSC
Prerequisites:	Basic science				
Aim:	To understand basic and fundamental engin	neering k	nowl	edge from bi	ology.
Course Outcomes:					
The Students will be abl	e to				
CO1: Understand vario molecules	us biochemical interactions and the structure and	l function	of va	rious biologic	al
	ncepts of thermodynamics and energy transaction	ıs.			
	t aspects of molecular computing				
CO4: Demonstrate an u	inderstanding of Mendelian laws of inheritance.				
	architecture and utilize these concepts to design	0	<u> </u>	•	
CO6: Understand funda	mental concepts in sensory physiology analogy	with com	nunic	ation systems	•
I UNIT 1	NTRODUCTION.				9
Biological analogy in	engineering science, Biological elements-C	Carbohyd	rate,	protein, am	ino
acids, lipids and nuclei	c acids structure and function. Primary, seco	ndary, te	rtiary	and quaterna	ary
structure of protein. Pr	otein as enzymes, transporter, receptors and	structura	l elen	nents.	

METABOLISM AND ENGINEERING

9

9

45

Total Periods:

Engineering aspects in thermodynamics of energy transactions, exothermic and endothermic versus endergonic and exergonic reactions. ATP as an energy source, glycolysis, Krebs cycle and photosynthesis. Energy yielding and energy consuming reactions. Enzymes classification, mechanism of enzyme action, enzyme kinetics and kinetic parameters

UNIT 1IIGENETICS AND TRANSFORMATION TECHNOLOGY9Molecular basis of information transfer. DNA as a genetic material. Concept of genetic code.Mendal's laws, concept of segregation and independent assortment. Concept of allele, Genemapping, Gene interaction, Epistasis, concepts of recessiveness and dominance and theirrelativeness to programming. Cell multiplication. Phenotype and genotype. Single gene disordersin humans and human genetics.

UNIT 1VCLASSIFICATION AND SYSTEM ENGINEERING9Structure, function and relativeness to engineering of prokaryotes and eukaryotes. Habitats- aquatic or
terrestrial. Molecular taxonomy-three major kingdoms. Microbial species and strains. Identification
and classification of microorganisms. Industrial application of microorganisms. Sterilization and media
compositions. Growth kinetics.

SENSOR BIOLOGY AND COMMUNICATION SYSTEMS

Sensory system, circulatory system and excretory system and their relativeness to communication engineering. Hormonal regulation. General defense mechanism in human. Major human disorder and diseases.

Text Book

UNIT V

UNIT 1I

- 1. Arthur T. Johnson, "Biology for Engineers", CRC Press, New York2011
- 2. Thyagarajan.S. et.al., "Biology for Engineers", Tata McGraw-Hill, New Delhi, 2012

References

- 1. Rajiv Singal, Gaurav Agarwal, Ritu Bir, Biology for Engineers, CBS Publisher, 2019
- 2. Raven Johnson, Biology, 11th Edition, Mc Graw Hill Publication, 2017
- 3. Charles Molnar.et.al. Concepts of Biology-1st Canadian Edition, Opens tax Publication, 2013

Course Outcomes]	Progr	am O	utcom	es (PC	Ds)				Pr Ot	ogram utcome	Specif s (PSO	ic s)
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
C01	1	2		2					2				2	3	3	3
CO2		2	3	2					2					2		3
CO3	2	2		2					2				2	3	3	
CO4	2	2		2					2				1	2	3	
CO5	1	2		2					2				1	2	3	
CO6		2	3	2					2					2		3

191ME31	ENGINEERING MECHA	ANICS		L-T-P	С
				3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:	III	Category:	ES
Prerequisites:	Engineering Physics				
	To impart a sound knowledge on the	applied phy	vsics law	s in different	engineering
Aim:	applications	11 1 -			0 0
Course Outcom					
The students will					
CO1. Recite the	e laws of forces and principle of transmissib	oility			
	the types of supports and equilibrium of rig		three din	nensions	
	he parallel axis theorem and perpendicular a				
—	e moment of inertia and polar moment of ir			ns	
	e displacement, velocity and acceleration p				work energy
	of particles	ioorenis and		ationship with	work energy
•	he various Frictional forces and general pla	ne motion of	rigid bo	lies	
UNIT 1	BASICS & STATI		e e		9
					-
	nits and Dimensions – Laws of Mechanics			÷	•
	Vectors – Vectorial representation of forc			•	
	product, cross product – Coplanar Force			-	
-	particle – Forces in space – Equilibrium of	a particle in	space – E	equivalent syste	ms of forces
-	nsmissibility – Single equivalent force			~	
UNIT 1I	EQUILIBRIUM				9
	m – Types of supports and their reactions				
-	oment of a force about a point and about a		-		
-	components of a moment - Varignon's		_	um of Rigid bo	odies in two
	ulibrium of Rigid bodies in three dimension				
UNIT 1II	PROPERTIES OF				9
	Areas and Volumes – First moment of area				-
triangle from inte	egration – T section, I section, - Angle sect	tion, Hollow	section b	y using standa	rd formula –
1	uct moments of plane area -Parallel axis t		I I		
moment of inerti	a – Principal moments of inertia of plane	areas – Prin	cipal axe	s of inertia - M	lass moment
inertia of circular	plate, Cylinder, Cone, Sphere, Hook.				
UNIT IV	DYNAMICS O	F PARTIC	LES		9
Displacements, V	velocity and acceleration, their relationship	– Relative m	otion – C	Curvilinear moti	on –
Newton's law – V	Work Energy Equation of particles				
UNIT V	FRICTION AND ELEMENTS (OF RIGID I	BODY D	YNAMICS	9
Frictional force -	- Laws of Coloumb friction - simple con	tact friction	– Rolling	g resistance – I	Belt friction.
	Rotation of Rigid Bodies – Velocity and acc				
I ranslation and F	0				
I ranslation and F				Total Periods	: 45
				Total Periods	: 45
Text books	and Johnson Jr. E.R., "Vector Mechanics for Eng	gineers", Vol.	1 Statics a		
Text books 1. Beer F.P.	and Johnson Jr. E.R., "Vector Mechanics for Eng national Edition, (2012)	gineers", Vol.	1 Statics a		
Text books 1. Beer F.P. Hill Intern	-	-		nd Vol. 2 Dynam	ics, McGraw-
Text books 1. Beer F.P. Hill Intern	national Edition, (2012)	-		nd Vol. 2 Dynam	ics, McGraw-
Text books 1. Beer F.P. Hill Intern Hill Intern 2. Palanicha References 1. Hibbeller	national Edition, (2012) my M.S., Nagam S., "Engineering Mechanics–S R.C., "Engineering Mechanics", Pearson Educa	Statics & Dyna ition Asia Pvt.	amics", Ta Ltd., (20	nd Vol. 2 Dynam ata McGraw-Hill 10)	ics, McGraw- , (2004)
Text books1.Beer F.P.Hill Intern2.PalanichaReferences1.Hibbeller2.Irving H.	national Edition, (2012) my M.S., Nagam S., "Engineering Mechanics–S R.C., "Engineering Mechanics", Pearson Educa Shames, "Engineering Mechanics – Statics and	Statics & Dynation Asia Pvt. Dynamics", P	amics", Ta Ltd., (20 earson Ed	nd Vol. 2 Dynam ata McGraw-Hill 10) ucation Asia Pvt	ics, McGraw- , (2004)
Text books 1. Beer F.P. Hill Interr Palanicha 2. Palanicha References Interr 1. Hibbeller 2. Irving H. 3. Kottiswar	national Edition, (2012) my M.S., Nagam S., "Engineering Mechanics–S R.C., "Engineering Mechanics", Pearson Educa Shames, "Engineering Mechanics – Statics and an N., "Engineering Mechanics Statics & Dynam	Statics & Dyna ition Asia Pvt. Dynamics", P mics", Balaji I	amics", Ta Ltd., (20 earson Ed Publication	nd Vol. 2 Dynam ata McGraw-Hill 10) ucation Asia Pvt ns (2016)	ics, McGraw- , (2004) . Ltd., (2006)
Text books 1. Beer F.P. Hill Interr Palanicha 2. Palanicha References Interr 1. Hibbeller 2. Irving H. 3. Kottiswar	national Edition, (2012) my M.S., Nagam S., "Engineering Mechanics–S R.C., "Engineering Mechanics", Pearson Educa Shames, "Engineering Mechanics – Statics and an N., "Engineering Mechanics Statics & Dynam an S., Sankarasubramanian G., "Fundamentals	Statics & Dyna ition Asia Pvt. Dynamics", P mics", Balaji I	amics", Ta Ltd., (20 earson Ed Publication	nd Vol. 2 Dynam ata McGraw-Hill 10) ucation Asia Pvt ns (2016)	ics, McGraw- , (2004) . Ltd., (2006)

Course Outcomes]	Progr	am O	utcom	es (PC	Ds)				Pr Ot	ogram utcome	Specif s (PSO	ic s)
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
C01	1	2		2					2				2	3	3	3
CO2		2	3	2					2					2		3
CO3	2	2		2					2				2	3	3	
CO4	2	2		2					2				1	2	3	
CO5	1	2		2					2				1	2	3	
CO6		2	3	2					2					2		3

191ME32	ENGINEERING THERMODYNA	MICS			L-T-P	С
					3-1-0	4
Programme:	B.E. Mechanical Engineering	Sem:	III	(Category:	PC
Prerequisites:	Engineering Physics				8 .	
Aim:	To learn the basic concepts of Thermodynamics a	and its an	oplicat	tion		
Course Outcome		1	1			
The students will	be able to					
CO1. Describe the	thermodynamics basic principles and different pro	ocesses				
CO2. Explain the	laws of thermodynamics					
CO3. Introduce th	e engines, refrigeration and air conditioning conce	pts				
CO4. Ensure the v	vorking principle of Steam power cycles	-				
CO5. Realize the	deal, real gases concepts and thermodynamic relat	ions				
	principles of psychrometric processes and cooling		culatio	on iı	n Air conditio	ner
UNIT 1	BASIC CONCEPT AND FIRST LAW O					12
Basic concepts –	concept of continuum, macroscopic approach,	Thermo	lynam	nic s	systems – clo	sed, open
—	perty, state, path and process, quasi-static process					_
-	- concept of temperature and heat. Concept of					
•	application to closed and open systems, internal e				e	
•	s with reference to various thermal equipments	6, , ,	L		I ,	1.57
UNIT 1I	SECOND LAW AND THIRD LAW OF	THERN	AOD	YN/	AMICS	12
	nermodynamics – Kelvin's and Clausius statem					
	arnot theorem, Carnot cycle, reversed carnot cyc					•
	Clausius inequality, Third law of thermodynamic					
	and Anergy: Available (Exergy) and Unavailable		•		* *	· •
UNIT 1II	PROPERTIES OF PURE SUBSTANCE AND	STEAM	I POV	VE	R CYCLE	12
Properties of pure	substances - Thermodynamic properties of pure	e substar	nces in	n so	olid, liquid ar	nd vapour
phases, phase rule	, P-V, P-T, T-V, T-S, H-S diagrams, PVT surfac	es, ther	nodyr	nam	ic properties	of steam.
Estimation of wor	kdone and heat transfer in non-flow and flow proc	cesses –	Stand	lard	Rankine cycl	e, Reheat
and regenerative c	ycle					
UNIT 1V	IDEAL AND REAL GASES AND THERMO	DYNAN	AIC R	REL	ATIONS	12
Gas mixtures - pr	operties ideal and real gases, equation state, Avag	gadro's I	Law, V	Van	der Waal's ed	quation of
state, compressabi	lity factor, compressability chart – Dalton's law of	partial p	oressu	ıre,	exact differen	ntials, T-
D relations, Max	well's relations, Clausius Clapeyron equations, Jou	le – Tho	mson	coe	fficient	
UNIT V	PSYCHROMETRY					12
Psychrometry and	psychrometric charts, property calculations of air v	apour m	ixture	es. P	sychrometric	process -
• •	ange processes. Latent heat exchange processes. A	-			•	•
				•	tal Periods:	60
				10	ui i ci iousi	00
Text Books						
Text Books	"hermodynamics_An Engineering Approach" Tat	a McGra	w Hill	1 N	ew Delhi (20)	15)
1. Cengel, "	Thermodynamics–An Engineering Approach", Tata					15)
 Cengel, "7 Nag P.K., 	Thermodynamics–An Engineering Approach", Tata "Engineering Thermodynamics", Tata McGraw-Hi					15)
 Cengel, " Nag P.K., References	"Engineering Thermodynamics", Tata McGraw-Hi	ill, New	Delhi,	, (20)17)	
1.Cengel, "2.Nag P.K.,References1.Ganesan V	"Engineering Thermodynamics", Tata McGraw-Hi 7., "Thermodynamics – Basic and Applied", Tata M	ill, New	Delhi,	, (20)17)	
1.Cengel, "2.Nag P.K.,References1.Ganesan V2.Khurmi R.	"Engineering Thermodynamics", Tata McGraw-Hi 7., "Thermodynamics – Basic and Applied", Tata M S., "Steam Tables", S.Chand publication, New Delhi (McGraw 2014)	Delhi, Hill, I	, (20 New)17)	
1.Cengel, "2.Nag P.K.,References1.Ganesan V2.Khurmi R.3.Natarajan I	"Engineering Thermodynamics", Tata McGraw-Hi V., "Thermodynamics – Basic and Applied", Tata M S., "Steam Tables", S.Chand publication, New Delhi (E., "Engineering Thermodynamics", Anugraham Pu	ill, New McGraw 2014) ıblication	Delhi, Hill, I n, (20	, (20 New 15)	017) 7 Delhi, (2018	·
1.Cengel, "2.Nag P.K.,References1.Ganesan V2.Khurmi R.3.Natarajan I	"Engineering Thermodynamics", Tata McGraw-Hi 7., "Thermodynamics – Basic and Applied", Tata M S., "Steam Tables", S.Chand publication, New Delhi (ill, New McGraw 2014) ıblication	Delhi, Hill, I n, (20	, (20 New 15)	017) 7 Delhi, (2018	·

Course Outcomes				Pr	ogran	n Out	come	s (PO	s)					rogran utcom		
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3	3		1						2			3	2		
CO2	3	3		1						2			3			
CO3	3	3	2	3	2		2					2	3	3		2
CO4	2	2		3	2	1	1							2		1
CO5	3	3	1	2									2			
CO6	3	3	2	1	1							1		2		1

191ME33	ENGINEERING METROLOGY AND MEA	SUREM	IENT	S	L-T-P	С
					3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:	III	С	ategory:	РС
Prerequisites:	Nil	•			I	
Aim:	To understand the principles, methods and applic	ations of	measu	ıren	ents	
Course Outcomes:	1					
The students will be	able to					
CO1. Understand th	e basic concepts of measurements					
CO2. Classify vario	us linear, angular measuring equipments					
CO3. Compare the v	working principles of various form measuring equip	oments				
CO4. Explain the ap	pplications of laser in measurements					
CO5. Describe the u	uses of coordinate measuring instruments and comp	uter aide	d insp	ectio	n	
CO6. Analyze the m	nethods of measuring power, torque, flow and temp	erature				
UNIT 1	INTRODUCTI	ON				9
General concept – g	eneralized measurement system – units and standa	rds – me	asuring	g ins	truments –	sensitivity,
stability, range, accu	uracy and precision – static and dynamic response -	- repeatab	ility –	syst	ematic and ra	ndom errors
- correction, calibrati	ion – Introduction to Dimensional and Geometric To	lerance –	interc	hang	geability	
UNIT 1I	LINEAR MEASU					9
Definition of metro	ology – Linear measuring instruments – Verni	er calipe	er, mi	cron	neter, Slip g	gauges and
	Makers Microscope – interferometry – optical flats	-				
	rical comparators, applications –	1			00	
-						
UNIT 1II	ANGULAR AND FORM	MEASU	JREM	ΕN	Γ	9
	ANGULAR AND FORM nts – Sine bar, Sine center, bevel protractor and An					
Angular measureme		gle Dekk	or - M	easu	rement of sc	rew threads
Angular measureme – Thread gauges, flo	nts – Sine bar, Sine center, bevel protractor and An	gle Dekk tooth th	or - M icknes	easu s –	rement of sc constant choi	rew threads
Angular measureme – Thread gauges, flo tangent method – Gl	nts – Sine bar, Sine center, bevel protractor and An oating carriage micrometer – measurement of gear	gle Dekk tooth th	or - M icknes	easu s –	rement of sc constant choi	rew threads
Angular measureme – Thread gauges, flo tangent method – Gl	nts – Sine bar, Sine center, bevel protractor and An oating carriage micrometer – measurement of gear eason gear testing machine – radius measurements -	gle Dekk tooth th surface	or - M icknes finish	easu s – – eq	rement of sc constant chor uipment and	rew threads
Angular measureme – Thread gauges, flo tangent method – Gl straightness, flatness UNIT 1V	nts – Sine bar, Sine center, bevel protractor and An oating carriage micrometer – measurement of gear eason gear testing machine – radius measurements s and roundness measurements MEASUREMENT OF MECHAN	gle Dekk tooth th surface	or - M icknes finish ARAN	easu s — eq	Trement of sc constant chor uipment and TERS	rew threads rd and base parameters, 9
Angular measureme – Thread gauges, flo tangent method – Gl straightness, flatness UNIT 1V Force, torque, po	nts – Sine bar, Sine center, bevel protractor and An oating carriage micrometer – measurement of gear eason gear testing machine – radius measurements – s and roundness measurements <u>MEASUREMENT OF MECHAN</u> wer – Mechanical, pneumatic, hydraulic and e	gle Dekk tooth th surface	or - M icknes finish ARAN type	easu s – eq MET – Pr	Trement of sc constant choruipment and TERS essure measure	rew threads rd and base parameters 9 urement —
Angular measureme – Thread gauges, flo tangent method – Gl straightness, flatness UNIT 1V Force, torque, po	nts – Sine bar, Sine center, bevel protractor and An oating carriage micrometer – measurement of gear eason gear testing machine – radius measurements s and roundness measurements MEASUREMENT OF MECHAN	gle Dekk tooth th surface	or - M icknes finish ARAN type	easu s – eq MET – Pr	Trement of sc constant choruipment and TERS essure measure	rew threads rd and base parameters 9 urement —
Angular measureme – Thread gauges, flo tangent method – Gl straightness, flatness UNIT 1V Force, torque, por Temperature – bime	nts – Sine bar, Sine center, bevel protractor and An oating carriage micrometer – measurement of gear eason gear testing machine – radius measurements – s and roundness measurements <u>MEASUREMENT OF MECHAN</u> wer – Mechanical, pneumatic, hydraulic and e	gle Dekk tooth th surface IICAL P lectrical sistance t	or - M icknes finish ARAN type hermo	easu s – eq MET – Pr	Trement of sc constant choruipment and TERS essure measure	rew threads rd and base parameters 9 urement —
Angular measureme – Thread gauges, flo tangent method – Gl straightness, flatness UNIT 1V Force, torque, po Temperature – bime UNIT V	nts – Sine bar, Sine center, bevel protractor and An oating carriage micrometer – measurement of gear eason gear testing machine – radius measurements - s and roundness measurements MEASUREMENT OF MECHAN wer – Mechanical, pneumatic, hydraulic and e etallic strip, thermocouples, pyrometer, electrical re	gle Dekk tooth th - surface IICAL P electrical sistance t	or - M icknes finish ARAN type - hermo	easu s – eq MET – Pr	TERS Constant chore CERS CERS CERS CERS CERS CERS CERS CERS	rew threads rd and base parameters 9 urement — nistor 9
Angular measureme – Thread gauges, flo tangent method – Gl straightness, flatness UNIT 1V Force, torque, por Temperature – bime UNIT V Precision instrument	nts – Sine bar, Sine center, bevel protractor and An oating carriage micrometer – measurement of gear eason gear testing machine – radius measurements - s and roundness measurements <u>MEASUREMENT OF MECHAN</u> wer – Mechanical, pneumatic, hydraulic and e etallic strip, thermocouples, pyrometer, electrical re <u>ADVANCES IN METR</u>	gle Dekk tooth th surface IICAL P lectrical sistance t COLOGY – applica	or - M icknes finish ARAM type hermo	easu s – eq MET – Pr omet	Tement of sc constant chorul uipment and 'ERS essure measurements	rew threads rd and base parameters 9 urement — nistor 9 nd machine
Angular measureme – Thread gauges, flo tangent method – Gl straightness, flatness UNIT 1V Force, torque, por Temperature – bime UNIT V Precision instrument	nts – Sine bar, Sine center, bevel protractor and An oating carriage micrometer – measurement of gear eason gear testing machine – radius measurements - s and roundness measurements <u>MEASUREMENT OF MECHAN</u> wer – Mechanical, pneumatic, hydraulic and e etallic strip, thermocouples, pyrometer, electrical re <u>ADVANCES IN METR</u> ts based on laser – Principles – laser interferometer	gle Dekk tooth th surface IICAL P lectrical sistance t COLOGY – applica	or - M icknes finish ARAM type hermo	easu s – eq MET – Pr omet	Tement of sc constant chorul uipment and 'ERS essure measurements	rew threads rd and base parameters 9 urement — nistor 9 nd machine
Angular measureme – Thread gauges, flo tangent method – Gl straightness, flatness UNIT IV Force, torque, por Temperature – bime UNIT V Precision instrument tool metrology – C	nts – Sine bar, Sine center, bevel protractor and An oating carriage micrometer – measurement of gear eason gear testing machine – radius measurements - s and roundness measurements <u>MEASUREMENT OF MECHAN</u> wer – Mechanical, pneumatic, hydraulic and e etallic strip, thermocouples, pyrometer, electrical re <u>ADVANCES IN METR</u> ts based on laser – Principles – laser interferometer	gle Dekk tooth th surface IICAL P lectrical sistance t COLOGY – applica	or - M icknes finish ARAM type hermo tion in s, app	easu s – eq MET – Pr pmet	Tement of sc constant chorul uipment and 'ERS essure measurements	rew threads rd and base parameters 9 urement — nistor 9 nd machine
Angular measureme – Thread gauges, flo tangent method – Gl straightness, flatness UNIT IV Force, torque, por Temperature – bime UNIT V Precision instrument tool metrology – C	nts – Sine bar, Sine center, bevel protractor and An oating carriage micrometer – measurement of gear eason gear testing machine – radius measurements - s and roundness measurements <u>MEASUREMENT OF MECHAN</u> wer – Mechanical, pneumatic, hydraulic and e etallic strip, thermocouples, pyrometer, electrical re <u>ADVANCES IN METR</u> ts based on laser – Principles – laser interferometer	gle Dekk tooth th surface IICAL P lectrical sistance t COLOGY – applica	or - M icknes finish ARAM type hermo tion in s, app	easu s – eq MET – Pr pmet	irement of sc constant chorul uipment and `ERS essure measurements and therm assurements a ions – Comp	rew threads rd and base parameters, 9 urement — nistor 9 nd machine puter aided
Angular measureme – Thread gauges, flo tangent method – Gl straightness, flatness UNIT 1V Force, torque, por Temperature – bime UNIT V Precision instrument tool metrology – C inspection Text Books	nts – Sine bar, Sine center, bevel protractor and An oating carriage micrometer – measurement of gear eason gear testing machine – radius measurements - s and roundness measurements <u>MEASUREMENT OF MECHAN</u> wer – Mechanical, pneumatic, hydraulic and e etallic strip, thermocouples, pyrometer, electrical re <u>ADVANCES IN METR</u> ts based on laser – Principles – laser interferometer	gle Dekke tooth th - surface : IICAL P electrical sistance t COLOGY - applica on, types	or - M icknes finish ARAM type hermo tion in s, app	easu s – eq MET – Pr pmet	irement of sc constant chorul uipment and `ERS essure measurements and therm assurements a ions – Comp	rew threads rd and base parameters, 9 urement — nistor 9 nd machine puter aided
Angular measureme – Thread gauges, flo tangent method – Gl straightness, flatness UNIT 1V Force, torque, por Temperature – bime UNIT V Precision instrument tool metrology – C inspection Text Books 1. Jain R.K., "	nts – Sine bar, Sine center, bevel protractor and An oating carriage micrometer – measurement of gear eason gear testing machine – radius measurements - s and roundness measurements MEASUREMENT OF MECHAN wer – Mechanical, pneumatic, hydraulic and e etallic strip, thermocouples, pyrometer, electrical re ADVANCES IN METR ts based on laser – Principles – laser interferometer Coordinate measuring machine – need, constructi	gle Dekk tooth th - surface IICAL P lectrical sistance t COLOGY - applica on, types	or - M icknes finish ARAM type hermo tion in s, app	easu s – eq MET – Pr pmet	irement of sc constant chorul uipment and `ERS essure measurements and therm assurements a ions – Comp	rew threads rd and base parameters, 9 urement — nistor 9 nd machine puter aided
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Angular measureme – Thread gauges, flo tangent method – Gl straightness, flatness UNIT 1V Force, torque, por Temperature – bime UNIT V Precision instrument tool metrology – C inspection Text Books 1. Jain R.K., " 2. Gupta S.C, ' References	nts – Sine bar, Sine center, bevel protractor and An oating carriage micrometer – measurement of gear eason gear testing machine – radius measurements – s and roundness measurements <u>MEASUREMENT OF MECHAN</u> wer – Mechanical, pneumatic, hydraulic and e etallic strip, thermocouples, pyrometer, electrical re <u>ADVANCES IN METE</u> ts based on laser – Principles – laser interferometer Coordinate measuring machine – need, constructi Engineering Metrology", Khanna Publishers, (201 "Engineering Metrology", Dhanpat rai Publicatior	gle Dekk tooth th - surface IICAL P electrical sistance t COLOGY - applica on, types 2) as, (2013)	or - M icknes finish ARAN type thermo tion in s, app	easu s - eq MET - Pr omet licat	TERS essure measurements a ions – Compatibility of the second s	rew threads rd and base parameters, 9 urement — nistor 9 nd machine puter aided
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Course Outcomes				Pro	gram	Out	comes	s (PO	s)				Pr Ou	ogram itcome	Specif s (PSC	fic Ds)
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	2	1	1		3				2			3				3
CO2	2	2	2		2											3
CO3	2	2	1		1				3			2				3
CO4	2	2	2		2											3
CO5	2	2	2		2											3
CO6	2	2	2		2				3							2

191ME34	MANUFACTURING PROCE	SSES			L-T-P		С
					3-0-2		4
Programme:	B.E. Mechanical Engineering	Sem:	III	C	ategory:]	PC
Prerequisites:	Nil				0,		
Aim:	To introduce the basic concepts and methods of	of the produ	iction	/ fa	brication of	`a con	ponent
Course Outcomes:		1					1
The students will be al	ble to						
CO1. Do sand mouldi							
	ious types of joining processes used in engineeri	ng industrie	es				
CO3. Recall the latest		C					
	tween the hot working and cold working process	of metals					
CO5. Fabricate the va	rious products using sheet metal operations						
	nt moulding methods of plastics						
THEORY							
UNIT 1	METAL CASTING PRO	CESSES					9
				1	Duousutian	Carr	
	atterns & materials – Pattern allowances – Types ting – Steps involved in making a green sand mo						
	urnaces – Procedural steps and applications of						
	Ceramic mould casting. – Pressure die casting –						
defects - Inspection m		C		U			
UNIT 1I	JOINING PROC	CESSES					9
Fusion welding proce	esses - Types of Gas welding - Equipments	used – F	lame o	char	acteristics -	- Arc	welding
	des – Principles of Resistance, Spot/butt, se						
	g – Submerged arc welding – Electro slag weldi						-
Electron beam weldin	g – Friction welding – Diffusion welding – We	eld defects	– Bra		-		-
	ng – Friction welding – Diffusion welding – We uxes	eld defects	– Bra		-		-
Electron beam weldin Filler materials and flu UNIT 111					-		-
Filler materials and flu UNIT 111	BULK DEFORMATION	PROCES	SES	zinş	g and solde	ring p	rocess - 9
Filler materials and flu UNIT 111 Hot working and cold	BULK DEFORMATION Working of metals – Forging processes – Ope	PROCES on and clos	SES ed die	zinş	g and solde	ring p	rocess - 9 Forging
Filler materials and flu UNIT 111 Hot working and cold Machines – Typical fo	BULK DEFORMATION BULK DEFORMATION I working of metals – Forging processes – Ope orging operations – Rolling of metals – Types of F	PROCES on and close Rolling mill	SES ed die s – Fl	zing for at st	g and solde ging – Typ rip rolling -	ring p bes of - Shap	rocess - 9 Forging e rolling
Filler materials and flu UNIT 111 Hot working and cold Machines – Typical fo operations – Defects in	BULK DEFORMATION BULK DEFORMATION I working of metals – Forging processes – Ope orging operations – Rolling of metals – Types of F n rolled parts – Principle of rod and wire drawing	PROCES on and close Rolling mill	SES ed die s – Fl	zing for at st	g and solde ging – Typ rip rolling -	ring p bes of - Shap	rocess - 9 Forging e rolling
Filler materials and flu UNIT 111 Hot working and cold Machines – Typical fo operations – Defects in Types of Extrusion – H	BULK DEFORMATION BULK DEFORMATION I working of metals – Forging processes – Ope orging operations – Rolling of metals – Types of F n rolled parts – Principle of rod and wire drawin Hot and Cold extrusion	PROCES on and clos Colling mill g – Tube dr	SES ed die s – Fla rawing	zing for at st	g and solde ging – Typ rip rolling -	ring p bes of - Shap	9 Forging e rolling trusion -
Filler materials and flu UNIT 111 Hot working and cold Machines – Typical fo operations – Defects in Types of Extrusion – H UNIT 1V	BULK DEFORMATION A working of metals – Forging processes – Ope orging operations – Rolling of metals – Types of F n rolled parts – Principle of rod and wire drawin Hot and Cold extrusion SHEET METAL	PROCES en and clos Colling mill g – Tube de PROCESS	SES ed die s – Fla rawing ES	zinş e foi at st g —	g and solde ging – Typ rip rolling – Principles	ring p bes of - Shap of Ext	rocess - 9 Forging e rolling trusion - 9
Filler materials and flu UNIT 111 Hot working and cold Machines – Typical fo operations – Defects in Types of Extrusion – H UNIT 1V Sheet metal characte	BULK DEFORMATION I working of metals – Forging processes – Ope orging operations – Rolling of metals – Types of H n rolled parts – Principle of rod and wire drawin Hot and Cold extrusion SHEET METAL eristics – Typical shearing operations, bendir	PROCES on and clos Colling mill g – Tube dr PROCESS	SES ed die s – Fla rawing ES wing	zing c for at st g — ope	g and solde ging – Typ rip rolling – Principles rations – S	ring p bes of - Shap of Ext	rocess - 9 Forging e rolling trusion - 9 forming
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PRACTICAL LIST OF EXPERIMENTS								
LIST OF EXPERIMENTS PREPARATION OF SAND MOULD								
PREPARATION OF SAND MOULD								
Mould with solid, split patterns								
Mould with loose-piece pattern								
Mould with Core								
WELDING EXERCISES								
Demonstration on Horizontal, Vertical and Ove	erhead welding							
Hands on exercise: Vee joint, L-joint and Tee joint	-							
Hands on exercise: Vee joint, L-joint and Tee joint Demonstration on Gas Cutting, Gas Welding and Brazing								
SMITHY EXERCISES	8							
Round to square								
Hands on exercise: 'U' clamp								
*	Γ OF EQUIPMENTS							
	a batch of 30 students)							
1. Sand moulding Facility	,							
Moulding Table	05							
Moulding boxes, tools and patterns	05 sets							
2. Welding								
Arc welding machine	04							
Gas welding machine	01							
Brazing machine	01							
3. Smithy								
Hearth furnace	01							
Anvil	01							
Smithy tools	01 Set							

Course Outcomes					Prog	ram O	utcon	nes (P	Os)				P O	rogram utcome	Specifi s (PSOs	c 5)
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	2	1	1		3				2			3				3
CO2	2	2	2		2											3
CO3	2	2	1		1				3			2				3
CO4	2	2	2		2											3
CO5	2	2	2		2											3
CO6	2	2	2		2				3							2

191ME37	METROLOGY AND MEASUREMENTS	S LABORA	TORY	7	L-T-P	С
	<u>.</u>				0-0-2	1
Programme:	B.E. Mechanical Engineering	Sem:	III	C	ategory:	РС
Prerequisites:	Nil				•	
Aim:	To learn the methods of handling different mea	suring instru	iments			
Course Outcomes						
The students will b	be able to					
	near and angular measurement					
CO2. Check straig	ghtness, flatness using dial gauge					
	rew and gear parameters					
	ation and displacement measuring instrument					
	e and torque measuring tools					
CO6. Learn differ	ent temperature measuring techniques					
	LIST OF EXPERIMENT	S				
	n of Vernier, Micrometer and Dial Gauge					
	ents using linear measurement tools - Vernier,	Inside Micr	ometer	r, Do	epth gauge,	Height
- ·	necking Dimensions of part using slip gauges)					
	ents of Gear Tooth dimensions					
4. Measurem	ent of Angle using sine bar, sine center and tool n	maker's mic	roscop	e		
5. Measurem	ent of straightness and flatness					
6. Measurem	ent of thread parameters					
7. Inspection	using Mechanical comparators					
8. Measurem	ent of Temperature using Thermocouple					
9. Measurem	ent of Displacement					
10. Measurem	ent of Force Measurement of Torque Measureme	nt of Vibrat	ion / Sl	hock	ζ.	
					Total Peri	ods: 45
	LIST OF EQUIPMENTS (For a batch	of 30 stude	nts)			
1. Micrometer -						
2. Vernier Calip						
e	ht Gauge - 2 Nos.					
-	h Gauge - 2 Nos.					
5. Slip Gauge Se						
	/ernier - 1 No.					
7. Sine Bar - 2 N	Nos.					
8. Bevel Protrac	xtor - 1 No.					
e	riage Micrometer - 1 No.					
10. Profile Projec						
11. Mechanical C	Comparator - 1 No.					
12. Temperature	Measuring Setup - 1 No.					
13. Displacement	t Measuring Setup - 1 No.					
14. Force Measur	ring Setup - 1 No.					
15. Torque Meas	uring Setup - 1 No.					

Course Outcomes				Pr	ograr	n Out	come	s (PO	s)				Pr Ot	ogram utcome	Specif s (PSO	ic s)
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3												3			
CO2	2	1	3		2				1			1	3		1	1
CO3	2								1				3			1
CO4	1								1			1	2			
CO5	1								1			1	2			
CO6	2	1		2	2				1				3		2	1

191ME38	ME38 COMPUTER AIDED DRAFTING LABORATORY								
					0-0-	2	1		
Programme:	B.E. Mechanical Engineering	Sem:	III	Cate	gory:		ES		
Prerequisites:	Engineering Graphics								
Aim:	To gain more knowledge in 2D & 3D drav	vings by us	ing rel	evant s	oftware				
Course Outcomes									
The students will b									
	the fundamentals of drafting techniques								
	basic shapes and modeling								
CO3. Understand	the drawing from different perspective								
CO4. Convert Isor	netric to orthographic projections & from or	rthographic	to iso	metric	of simple	obje	cts		
CO5. Draw simple	e 3D models using extrude and revolve								
CO6. Assemble m	achine elements								
	Drawing Standar	ds							
Code of practice f	or Engineering Drawing, BIS specification	ns – Weldi	ng syn	nbols, r	iveted jo	ints,	keys and		
fasteners – Selectio	on of standard components like bolts, nuts,	screws, ke	ys etc.	with th	ne help of	f desi	ign data		
book									
	2-D Drawings								
Limits, Fits – Tol	erance of individual dimensions – Speci	fication of	f Fits	– Prep	aration o	f pro	duction		
drawings and readi	ng of part and assembly drawings.			-		-			
	Basic commands used in Dra	fting Pack	ages						
Drawing Editing	Plotting, Layering Concepts, Hatching, De	-	-	Solids	Render	ing S	Shading		
	GD&T (geometric dimensioning & tolerand	-				-	/indding		
basic principles of	ober (geometrie uniensioning & orerand	<i>c)</i> , i icpaiz		DIII UI	material	5.			
	List of Exercise	S							
• Drawing of cur	rves like parabola, spiral, involute of square	and circle							
 Drawing of fro 	nt view and top view of simple solids like b	olt & Nut,	welded	l joints					
e e	onal views of simple machine elements			5					
-	thographic view from Isometric view								
•	metric view from Orthographic view								
e	pple 3D objects using Extrude and Revolve	command							
÷		command							
•	ving – Sleeve and Cotter joint								
•	ving – Knuckle joint								
-	ving – Flange Coupling								
•	ving – Universal Coupling								
	examination duration is Three hours. Stud	ents will c	arry o	ut one	exercise	in as	ssembly		
drawing and one ex	kercise in simple objects.								
	SYSTEM REQUIREMENTS (For a	batch of 3	0 Stud	ents)					
Hardware:			• • -						
	e due processor with 4GB ram with 500GB	hard disk -	- 30 N	os.					
2. Laser Print	ter - 1 No.								
<u>Software:</u>									
1. Drafting pa	ackage – AutoCAD – Adequate license (Op	en source)							
1. Dratting pa	ackage – AutoCAD – Adequate license (Op	en source)			Total	Peri	0		

Total Periods: 45

Course Outcomes				ł	Progr	am O	utcoi	nes (l	POs)					ogram itcome		
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3	2	1		1				2			3			3	3
CO2	3	2	1		1				2			2			3	3
CO3	3	2	1		1				3			2			3	3
CO4	3	2	2		2				3	2		2			3	3
CO5	3	3	2		2				3	2		3			3	3
CO6	3	3	2		2				3	2		3			3	3

1: Slight (Low) 2: Moderate (Medium) 3: Substantial (High)

	1				1		
191HS42	PROBABILITY AND STATIST	FICS			L-T-		C 3
	B.E. / B.Tech. (CIVIL, CSE, EEE, MECH,				2-1-		
Programme:	BIO-TECH & BIO-MEDICAL)	Sem:	IV	Ca	tegory:]	BSC
Prerequisites:							
Aim:	To analyze the engineering problems using the acquired by studying ODE and PDE uses numeri			and the	e mather	natic	al skills
Course Outcom							
The students	will be able to						
CO1 : Classify t	he discrete and continuous random variables.						
CO2: Analyze	the binomial, Poisson, geometric, uniform, exp	ponenti	al and	l norm	nal distri	butic	on.
CO3: Understa	nding the Two-Dimensional Random Variable	es.					
	he differences between means & standard deviatio	ns					
	ndependence of attributes for small samples	-					
COO: Classify tr	ne tests for single variance and equality of variance	s					
UNIT 1	PROBABILITY AND RAND	OM V	ARIA	BLES	5		9
	es – Conditional probability – Bayes rule - Dis ment generating functions and their properties		nd con	tinuo	us rando	om va	ariables
UNIT 1I	DISCRETE AND CONTINOUS PRO	BABIL	ITY D	ISTR	IBUTIO	N	9
Binomial, Poisso Random Variabl	on, Geometric, Uniform, Exponential, Gamma e	and not	rmal c	listrib	utions –	Fun	ction of
UNIT 1II	TWO DIMENSIONAL RAN	DOM	ARI	BLES	5		9
Joint distribution	s - Marginal and conditional distributions - C	ovarian	ce - C	orrela	ation and	l Reg	gression
- Transformation	of random variables - Central limit theorem (for 2-D	rando	om va	riables)		
UNIT 1V	STATISTICS						9
curves – Test of si	e method of least squares – fitting of Straight lines, ignificance – Large sample test for single proportions and difference of standard deviations.						
UNIT V	TESTING OF HYPOT	HESIS					9
	utions – Testing of hypothesis for mean, varian quare and F distributions - Tests for independe						
				To	tal Perio	ods:	45
Text Book							
	Higher Engineering Mathematics', Thirty Sixth Ed ad Grewal J. S., "Numerical Methods in Engineerin						
Reference							
(First Indian r 2. Venkataramar	n. M.K., "Engineering Mathematics", Volume I an						ion, The
3. Kreyszig, E.,	ishing Company, Chennai, 2004. Advanced Engineering Mathematics, 8th edition, J nd Canale R.P., "Numerical Methods for Engineer					Delh	i,
(2007).	and Wheatley P.O., "Applied Numerical Analysis"						

Course Outcomes				Pro	gram	Oute	omes	(POs)					Pr Ot	ogram utcome	Specif s (PSO	ïc s)
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3	3		1								2		2	1	
CO2	2	3		2								1				1
CO3	3	3										3	2			
CO4	1	1													2	
CO5	3	2		1										2		
CO6	2	2		1								3	2			2

191ME41	FLUID MECHANICS AND N	IACHINER Y		L-T-P	С
				3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:	IV	Category:	PC
Prerequisites:	Engineering Mechanics				
Aim:	To understand the characteristics of fluids	and working c	f hydra	aulic machines	
Course Outcome	s:				
The students will	be able to				
	rious fluid properties and to apply control ve	•		-	
	concepts of mass and momentum conser	rvation and the	e Bern	oulli equation 1	o solve
problems					
	te the various losses that occur in fluid flow				d losses
	he hydraulic gradient and total energy lines				
-	e dimensional analysis for various fluid para				
	he various types, principle and working o	of positive dis	placem	ent machines a	nd roto
dynamic m			TIEG		
UNIT 1	BASIC CONCEPTS A			•	9
	ons – Properties of fluids – Specific gravity	· 1 · · ·	· ·	• · · ·	-
	face tension – Flow characteristics: concept	•			
	ne to continuity equation – energy equ	uation, momen	ntum	equation Pasca	l's law,
-	ressure, manometers, Hydrostatic law				0
UNIT 1I	FLOW THRO				9
	ough circular conduits and circular annuli aulic and energy gradient – Darcy, Weis			-	
	osses – Flow through pipes in series and in	-			
-	and stability of floating bodies	parallel – loss c	on energ	gy in pipes – Eq	uivaiciii
UNIT 1II	DIMENSIONA	I. ANALVSIS			9
	its – Buckingham's Π theorem – Discussio			arameters – Mo	
	cations of dimensionless parameters		ness p		ueis una
UNIT 1V	*	IC TURBINE	S		9
	noving plate vanes – Definition and classific			is. Propeller and	
	principles – Velocity triangle – Work done		·	· 1	
curve for turbines		1 1			
UNIT V	HYDRAUL	IC PUMPS			9
Definition and cl	assifications - Centrifugal and Reciproca	ting Pumps: W	orking	g principles – I	ndicator
diagram – Specifi	c speed – efficiency and performance curve	es – Cavitations	in pun	nps	
			,	Total Periods:	45
Text Books					1
1. Bansal R.	K., "A Text book of Fluid Mechanics and	d Hydraulics N	Aachin	es", Laxmi Pub	lication,
India, (20	15)				
2. Rajput R	K., "Fluid Mechanics and Hydraulic M	lachines", S.C	hand a	& Company Lte	1., New
Delhi, (20)13)				
References					
1. Modi P.N	., & Seth S.M., "Hydraulics and Fluid N	lechanics incl	uding	Hydraulic Ma	hines",
Standard	book house, (2012)				
2. Kumar K	L., "Engineering Fluid Mechanics", S. C.	hand Publishin	g (P) L	td., New Delhi,	(2014)
3. Streeter V	Y. L., and Wylie E.B., "Fluid Mechanics",	McGraw Hill,	(2008)		

Course Outcomes				Pr	ogran	n Out	come	s (PO	s)				Pr Ot	ogram itcome	Specif s (PSO	ic s)
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3	3		2	1					1		2	3	2		2
CO2	2	2		2	2					1		2	2	2		2
CO3	2	2		2	1					1		2	3	1		2
CO4	2	2		2	2					1		2	2	1		2
CO5	2	2		2	1					1	2	2	3	2		2
CO6	3	3		2	2					1	1	1	3	2		2

	MECHANICS OF MATER	RIALS		L-T-P	С
				3-1-0	4
Programme:	B.E. Mechanical Engineering	Sem:	IV	Category:	РС
Prerequisites:	Engineering Mechanics			L. L.	
A :	To understand the stresses developed in bar	rs, compound	s bars, b	eams, shafts, c	ylinders
Aim:	and spheres				
Course Outcome	5:				
The students will b	be able to				
CO1. Apply mathe	ematics to obtain analytical solutions in solid	mechanics			
CO2. Visualize the	e concept of stress, strain, bending of beams				
CO3. Calculate the	e torsion stress and deflections on the springs				
CO4. Recognize th	he deflection of beam when the stress is acted	1			
CO5. Analyze the	stress on columns & thin cylinders				
CO6. Know the ap	pplication of theories of failure				
UNIT 1	STRESS, STRAIN AND DEF	ORMATION	OF SC	DLIDS	12
Rigid bodies and d	leformable solids – Tension, Compression and				nple and
e	Thermal stresses – Elastic constants – Volum				•
principal stresses a	and principal planes – Mohr's circle of stress				-
UNIT 1	TRANSVERSE LOADING ON BEAMS	AND STRES	SES IN	BEAM	12
Beams – types tra	nsverse loading on beams – Shear force and	l bending mo	ment in	beams – Cant	ilevers –
• •	beams and over – hanging beams. Theory of s	•			
Load carrying cap	acity – Proportioning of sections – Flitched be	eams – Shear	stress di	stribution	
UNIT 1II	TORSION				12
	TORSION on stresses and deformation in circular and ho	ollows shafts -	- Steppe	d shafts – Defl	
Torsion formulation	on stresses and deformation in circular and ho		••		ection in
Torsion formulation		ection of helic	••		ection in
Torsion formulation shafts fixed at the UNIT 1V	on stresses and deformation in circular and ho both ends – Stresses in helical springs – Defle DEFLECTION OF	ection of helic F BEAMS	al spring	gs, carriage spri	ection in ings 12
Torsion formulation shafts fixed at the UNIT 1V Double Integration	on stresses and deformation in circular and ho both ends – Stresses in helical springs – Defle	ection of helic BEAMS ent Theorems	al spring	s, carriage springs, carriage	ection in ings 12
Torsion formulation shafts fixed at the UNIT 1V Double Integration deflections in bear	on stresses and deformation in circular and ho both ends – Stresses in helical springs – Defle DEFLECTION OF n method – Macaulay's method – Area mom- ns - Conjugate beam and strain energy – Max	ection of helic BEAMS ent Theorems well's recipro	al spring for con cal theo	s, carriage springer, carriage springer, carriage springer, carriage springer, carriage springer, carriage spri carriage springer, carriage	ection in ings 12
Torsion formulation shafts fixed at the UNIT 1V Double Integration deflections in bear UNIT V	on stresses and deformation in circular and ho both ends – Stresses in helical springs – Defle DEFLECTION OF n method – Macaulay's method – Area mom ns - Conjugate beam and strain energy – Max COLUMNS, THIN CYLINI	ection of helic BEAMS ent Theorems well's recipro DERS AND	al spring for con cal theo SPHER	nputation of slo ES	ection in ings 12 opes and 12
Torsion formulation shafts fixed at the UNIT 1V Double Integration deflections in bear UNIT V Columns – End co	on stresses and deformation in circular and ho both ends – Stresses in helical springs – Defle DEFLECTION OF n method – Macaulay's method – Area mom- ns - Conjugate beam and strain energy – Max COLUMNS, THIN CYLINI onditions – Equivalent length of a column – F	ection of helic BEAMS ent Theorems well's recipro DERS AND Euler equation	al spring for con cal theo SPHER - Slend	nputation of slo rems ES derness ratio –	ection in ings 12 opes and 12 Rankine
Torsion formulation shafts fixed at the UNIT 1V Double Integration deflections in bear UNIT V Columns – End conformula for column	on stresses and deformation in circular and ho both ends – Stresses in helical springs – Defle DEFLECTION OF n method – Macaulay's method – Area mom- ns - Conjugate beam and strain energy – Max COLUMNS, THIN CYLINI onditions – Equivalent length of a column – H ns. Stresses in thin cylindrical shell due to inter-	ection of helic BEAMS ent Theorems well's recipro DERS AND Euler equation rnal pressure of	al spring for con cal theo SPHER n – Slend circumfe	s, carriage springer, carriage springer, carriage springer, spring	ection in ings 12 opes and 12 Rankine gitudinal
Torsion formulation shafts fixed at the UNIT 1V Double Integration deflections in bear UNIT V Columns – End con formula for column stresses and deform	on stresses and deformation in circular and ho both ends – Stresses in helical springs – Defle DEFLECTION OF n method – Macaulay's method – Area mom- ns - Conjugate beam and strain energy – Max COLUMNS, THIN CYLINI onditions – Equivalent length of a column – E ns. Stresses in thin cylindrical shell due to inter- mation in thin cylinders – spherical shells sub-	ection of helic F BEAMS ent Theorems well's recipro DERS AND Euler equation rnal pressure of bjected to inter	al spring for con cal theo SPHER n – Slend circumfe	s, carriage springer, carriage springer, carriage springer, spring	ection in ings 12 opes and 12 Rankine gitudinal
Torsion formulation shafts fixed at the UNIT 1V Double Integration deflections in bear UNIT V Columns – End con formula for column stresses and deform	on stresses and deformation in circular and ho both ends – Stresses in helical springs – Defle DEFLECTION OF n method – Macaulay's method – Area mom- ns - Conjugate beam and strain energy – Max COLUMNS, THIN CYLINI onditions – Equivalent length of a column – H ns. Stresses in thin cylindrical shell due to inter-	ection of helic F BEAMS ent Theorems well's recipro DERS AND Euler equation rnal pressure of bjected to inter	al spring for con cal theo SPHER n – Slend circumfe ernal pre	s, carriage springer, carriage springer, carriage springer, spring	ection in ings 12 opes and 12 Rankine gitudinal
Torsion formulation shafts fixed at the UNIT 1V Double Integration deflections in bear UNIT V Columns – End con formula for column stresses and deform	on stresses and deformation in circular and ho both ends – Stresses in helical springs – Defle DEFLECTION OF n method – Macaulay's method – Area mom- ns - Conjugate beam and strain energy – Max COLUMNS, THIN CYLINI onditions – Equivalent length of a column – E ns. Stresses in thin cylindrical shell due to inter- mation in thin cylinders – spherical shells sub-	ection of helic F BEAMS ent Theorems well's recipro DERS AND Euler equation rnal pressure of bjected to inter	al spring for con cal theo SPHER n – Slend circumfe ernal pre	s, carriage springer, carriage springer, carriage springer, spring	ection in ings 12 opes and 12 Rankine gitudinal nation in
Torsion formulation shafts fixed at the UNIT 1V Double Integration deflections in bear UNIT V Columns – End conformula for column stresses and deform spherical shells – I Text Books	on stresses and deformation in circular and ho both ends – Stresses in helical springs – Defle DEFLECTION OF n method – Macaulay's method – Area mom- ns - Conjugate beam and strain energy – Max COLUMNS, THIN CYLINI onditions – Equivalent length of a column – E ns. Stresses in thin cylindrical shell due to inter- mation in thin cylinders – spherical shells sub-	ection of helic BEAMS ent Theorems well's recipro DERS AND Euler equation rnal pressure of bjected to inte lure	al spring for con cal theo SPHER n – Slend circumfe ernal pre	s, carriage springer, carriage springer, carriage springer, spring	ection in ings 12 opes and 12 Rankine gitudinal nation in
Torsion formulation shafts fixed at the UNIT 1V Double Integration deflections in bear UNIT V Columns – End con formula for column stresses and deform spherical shells – I Text Books 1. Ramamru	on stresses and deformation in circular and ho both ends – Stresses in helical springs – Defle DEFLECTION OF n method – Macaulay's method – Area mom- ns - Conjugate beam and strain energy – Max COLUMNS, THIN CYLINI onditions – Equivalent length of a column – H ns. Stresses in thin cylindrical shell due to inter- mation in thin cylinders – spherical shells sub Lame's theory – Application of theories of fai	ection of helic BEAMS ent Theorems well's recipro DERS AND Euler equation rnal pressure of bjected to inte lure ai Publishing	al spring for con cal theo SPHER n – Slend circumfe ernal pre To compan	s, carriage springer, carriage springer, carriage springer, spring	ection in ings 12 opes and 12 Rankine gitudinal nation in 60
Torsion formulation shafts fixed at the UNIT 1V Double Integration deflections in bear UNIT V Columns – End con formula for column stresses and deform spherical shells – I Text Books 1. Ramamru	on stresses and deformation in circular and ho both ends – Stresses in helical springs – Defle DEFLECTION OF n method – Macaulay's method – Area mom- ns - Conjugate beam and strain energy – Max COLUMNS, THIN CYLINI onditions – Equivalent length of a column – H ns. Stresses in thin cylindrical shell due to inter- mation in thin cylinders – spherical shells sub Lame's theory – Application of theories of fai	ection of helic BEAMS ent Theorems well's recipro DERS AND Euler equation rnal pressure of bjected to inte lure ai Publishing	al spring for con cal theo SPHER n – Slend circumfe ernal pre To compan	s, carriage springer, carriage springer, carriage springer, spring	ection in ings 12 opes and 12 Rankine gitudinal nation in 60
Torsion formulation shafts fixed at the UNIT 1V Double Integration deflections in bear UNIT V Columns – End con formula for column stresses and deform spherical shells – 1 Text Books 1. Ramamru 2. Bansal R. References	on stresses and deformation in circular and ho both ends – Stresses in helical springs – Defle DEFLECTION OF n method – Macaulay's method – Area mom- ns - Conjugate beam and strain energy – Max COLUMNS, THIN CYLINI onditions – Equivalent length of a column – H ns. Stresses in thin cylindrical shell due to inter- mation in thin cylinders – spherical shells sub Lame's theory – Application of theories of fai tham S., "Strength of Materials", Dhanpatra K., "A Text book of strength of material", T	ection of helic BEAMS ent Theorems well's recipro DERS AND Euler equation rnal pressure of bjected to inte lure ai Publishing Laxmi public	al spring for con cal theo SPHER a – Slend circumfe ernal pre To compan ation, N	s, carriage spring mputation of slover rems ES derness ratio – erential and long ssure – Deform otal Periods: y, (2012) ew Delhi, (201	ection in ings 12 opes and 12 Rankine gitudinal nation in 60 4)
Torsion formulation shafts fixed at the UNIT IV Double Integration deflections in bear UNIT V Columns – End con formula for column stresses and deform spherical shells – I Text Books 1. Ramamru 2. Bansal R. References 1. Popov E.F	on stresses and deformation in circular and ho both ends – Stresses in helical springs – Defle DEFLECTION OF a method – Macaulay's method – Area mom- ns - Conjugate beam and strain energy – Max COLUMNS, THIN CYLINI onditions – Equivalent length of a column – H ns. Stresses in thin cylindrical shell due to inter- mation in thin cylinders – spherical shells sub Lame's theory – Application of theories of fai tham S., "Strength of Materials", Dhanpatra K., "A Text book of strength of material", P., "Engineering Mechanics of Solids", Prer	ection of helic F BEAMS ent Theorems well's recipro DERS AND Euler equation rnal pressure of bjected to inter lure ai Publishing Laxmi public htice-Hall of I	al spring for com cal theo SPHER n – Slend circumfe rmal pre To compan ation, N ndia, Ne	s, carriage springer, carriage s	ection in ings 12 opes and 12 Rankine gitudinal nation in 60 4)
Torsion formulation shafts fixed at the UNIT IV Double Integration deflections in bear UNIT V Columns – End con formula for column stresses and defort spherical shells – I Text Books 1. Ramamru 2. Bansal R. References 1. Popov E.H 2. Beer F.P.	on stresses and deformation in circular and ho both ends – Stresses in helical springs – Defle DEFLECTION OF n method – Macaulay's method – Area mom- ns - Conjugate beam and strain energy – Max COLUMNS, THIN CYLINI onditions – Equivalent length of a column – H ns. Stresses in thin cylindrical shell due to inter- mation in thin cylinders – spherical shells sub Lame's theory – Application of theories of fai tham S., "Strength of Materials", Dhanpatra K., "A Text book of strength of material", P., "Engineering Mechanics of Solids", Prer- and Johnston R., "Mechanics of Materials"	ection of helic BEAMS ent Theorems well's recipro DERS AND Euler equation rnal pressure of bjected to intellure ai Publishing Laxmi public htice-Hall of I , McGraw-Hi	al spring for con cal theo SPHER a – Slend circumfe ernal pre To compan ation, N ndia, Ne	s, carriage spring mputation of slover rems ES derness ratio – prential and long ssure – Deform otal Periods: y, (2012) ew Delhi, (2010) cw Delhi, (2010) Co, (2012)	ection in ings 12 opes and 12 Rankine gitudinal nation in 60 4)
Torsion formulation shafts fixed at the UNIT IV Double Integration deflections in bear UNIT V Columns – End con formula for column stresses and deform spherical shells – I Text Books 1. Ramamru 2. Bansal R.: References 1. Popov E.H 2. Beer F.P. 3. Timoshen	on stresses and deformation in circular and ho both ends – Stresses in helical springs – Defle DEFLECTION OF a method – Macaulay's method – Area mom- ns - Conjugate beam and strain energy – Max COLUMNS, THIN CYLINI onditions – Equivalent length of a column – H ns. Stresses in thin cylindrical shell due to inter- mation in thin cylinders – spherical shells sub Lame's theory – Application of theories of fai tham S., "Strength of Materials", Dhanpatra K., "A Text book of strength of material",	ection of helic BEAMS ent Theorems well's recipro DERS AND Euler equation rnal pressure of bjected to intellure ai Publishing Laxmi public ntice-Hall of I , McGraw-Hi Nostrand con	al spring for com cal theo SPHER n – Slend circumfe mal pre To compan ation, N ndia, Ne Il Book npany , I	ss, carriage spring mputation of slover rems ES derness ratio – crential and long ssure – Deform otal Periods: y, (2012) ew Delhi, (2010) cw Delhi, (2010) Co, (2012) New York, (20	ection in ings 12 opes and 12 Rankine gitudinal nation in 60 4) 0)

Course Outcomes				Pro	ogram	Outc	omes	(POs)					ogram utcome		
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3	2	1	2								2	3	2		1
CO2	3	2	1	2								2	3	2		1
CO3	3	2	1	2			2					2	3	2		1
CO4	3	1	2	1								2	3	2		1
CO5	3	1	2	1								2	3	2		1
CO6	3	1	2	1			2					2	3	2		1

191ME43	MATERIAL	S ENGINEERI	NG			L-	T-P	С
						3-	0-0	3
Programme:	B.E. Mechanical Engineering		Sem:	IV	Categ	ory:	P	С
Prerequisites:	Engineering Physics							
Aim:	To impart the knowledge on prop	perties and the ap	plication	ns of n	naterials			
Course Outcomes	:							
The students will b	be able to							
CO1. Construct	a phase diagram and identify the n	naterial in variou	s phases					
	ne various types of heat treatment		•					
	a TTT diagram by changes that tal	•	the cooli	ng pro	ocesses			
	e plastic deformation and testing of	· ·		C I				
-	properties and applications various		-ferrous	metal	S			
	the properties and applications of							
Review (Not for H								2
	BCC, FCC and HCP structure – u	nit cell – crystall	ographic	plane	s a	nd	direc	tions,
•	s – crystal imperfections, point, li	•	01					· ·
size number					8			8
UNIT 1	CONSTITUTION OF ALL	OVS AND PHA	SE DIA	GRAI	MS			7
	oys – Solid solutions, substitution					Is	omorp	
	tic, peritectic, and peritectroid				0		-	,
	steel and cast Iron, microstruct					lonun	und.	14111
UNIT 1I	HEAT TRE		11					9
Definition – Full	annealing, stress relief, recrystall	ization and sphe	eroidizin	g – n	ormalizi	ng, ha	rdenin	g and
	- isothermal transformation diagra							
- Hardenability, J	ominy and quench test - Austen	nering martem	n amin a	20.52			ă i	
		npering, marieng	pering –	case	hardenn	ng – (Carbur	ızıng,
	ng, carbonitriding, flame and indu	iction hardening			hardenn	ng –	Carbur	ızıng,
Nitriding, cyanidi UNIT 111		iction hardening			hardenii	ng –	Carbur	9
UNIT 111	ng, carbonitriding, flame and indu	TING OF MAT	ERIALS					9
UNIT 111 Mechanism of plas	ng, carbonitriding, flame and indu MECHANICAL TES	Iction hardening FING OF MAT - Types of fractur	ERIALS re – Testi	ng of:	materials	s under	• tensio	9 on,
UNIT 111 Mechanism of plas compression and sl	ng, carbonitriding, flame and indu MECHANICAL TEST tic deformation, slip and twinning -	Iction hardening FING OF MAT - Types of fractur , Vickers and Roc	ERIALS re – Testi ckwell),	ng of : Impac	materials t test –]	s under	• tensio	9 m,
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Course Outcomes				Pro	gram	Outc	omes	(POs))				Pr Ot	ogram itcome	Specif s (PSO	ic s)
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3	2	1	2								2	3	2		1
CO2	3	2	1	2								2	3	2		1
CO3	3	2	1	2			2					2	3	2		1
CO4	3	1	2	1								2	3	2		1
CO5	3	1	2	1								2	3	2		1
CO6	3	1	2	1			2					2	3	2		1

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191ME44	KINEMATICS OF MA	CHINERY		L-T-P	С
				3-1-0	4
Programme:	B.E. Mechanical Engineering	Sem:	IV	Category:	PC
Prerequisites:	Engineering Mechanics			·	
Aim:	To impart knowledge of motion characte students to develop new mechanisms	istics of mechanis	ms and	machines and to	make the
Course Outcom	les:				
The students will	be able to				
CO1: Explain the	concepts of machines, mechanisms and rela	ed terminologies			
CO2: Analyze pla	nar mechanism for displacement, velocity an	d acceleration gra	phically	У	
CO3: Utilize anal	ytical method for analysis of given mechanis	m			
CO4: Perform the	kinematic analysis of a given cam mechanis	m			
CO5: Analyze van	ious motion transmission elements like gear	s, gear trains			
CO6: Recognize f	riction and its effects in mechanical compor	ents			

CO6: Recognize friction and its effects in mechanical components

UNIT 1

MECHANISMS AND MACHINES

Definitions - Link, Kinematic pair, Kinematic chain, Mechanism, and Machine - Degree of Freedom - Mobility -Kutzbach criterion - Grashoff's law - Kinematic Inversions of four bar chain and slider crank chain - Mechanical Advantage – Transmission angle – quick return mechanisms, Toggle mechanism, Ratchets and pawl mechanisms – Indexing Mechanisms

UNIT 11

KINEMATIC ANALYSIS

Analysis of simple mechanisms - Graphical Methods for displacement, velocity and acceleration - Coriolis acceleration – Analytical method of analysis of slider crank mechanism and four bar mechanism – Approximate analytical expression for displacement, Pantograph, Straight line mechanism, approximate straight line motion mechanism.

UNIT 1II

KINEMATICS OF CAMS

Classifications - Displacement diagrams - Parabolic, Simple harmonic and Cycloidal motions - Graphical construction of displacement diagrams and layout of plate cam profiles - circular arc and tangent cams - Pressure angle and undercutting

UNIT 1V

GEARS AND GEAR TRAINS

Classification of gears - Gear tooth terminology - Fundamental Law of toothed gearing and involute gearing -Length of path of contact and contact ratio - Interference and undercutting - Gear trains - Simple, compound and Epicyclic gear trains - Differentials 12

UNIT V

FRICTION IN MACHINE ELEMENTS

Surface contacts - Sliding and Rolling friction - Friction drives - Friction in screw threads - Friction clutches - Belt and rope drives - Friction in brakes- Band and Block brakes

> **Total Periods:** 60

Text Books

- 1. Rattan S.S., "Theory of Machines", Tata McGraw-Hill, (2014)
- 2. Khurmi R.S., Gupta J.K., "Theory of Machines", Eurasia Publishing House, (2014)

References

- 1. Norton R.L., "Kinematics and Dynamics of Machinery", Tata McGraw Hill, (2009)
- 2. Sadhu Singh, "Theory of Machines", Pearson Education, (2010)
- 3. Bansal R.K. Brar.J.S., "A Text Book of Theory of Machines", Lakshmi Publication, (2015)
- Uicker (Jr) J.J., Pennock G.R. and Shigley J.E., "Theory of Machines and Mechanisms" Oxford 4. International Student Edition, (2009)

Course Outcomes				Pr	ograr	n Out	come	s (PO	s)					ogram itcome		
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3	2	2	2	3		1					1	3	2		2
CO2	3	3	2	1	2							2	2	3		1
CO3	2	2	3	2	1		1					1	2	2		1
CO4	3	2	2	1	1	1						2	3	2		2
CO5	3	1	2	2	2						1	2	2	3	1	1
CO6	2	3	2	2	2		2					1	3	2	1	1

191ME45	MANUFACTURING TECH	NOLOGY			L-T-P	С
					3-0-2	4
Programme:	B.E. Mechanical Engineering	Sem:	IV	Cat	tegory:	PC
Prerequisites:	Manufacturing Processes		1		8 1	
Aim:	To understand the basic principles and wor	king of variou	ıs mac	hine to	ools	
Course Outcome		6				
The students will	be able to					
CO1. Know the pr	rinciple of metal cutting process					
-	asic operation of centre lathe					
CO3. Recognize t	he parts and working of special purpose lathe	e				
-	the working principle of reciprocating machi					
CO5. Explain the	hole making process					
CO6. Introduce th	e various methods of Grinding and Gear cutt	ing process				
THEORY						
UNIT 1	THEORY OF METAL C	UTTING				9
Introduction: mat	erial removal processes, types of machine to	ools- theory	of met	al cutti	ing: chip f	ormation.
	g, cutting tool materials, properties and applic	-				
- cutting fluids- fe			,			8
UNIT 1I	CENTRE LATHE AND SPECIAL I	PURPOSE L	ATHE	2S		9
Centre lathe cor	nstructional features, cutting tool geometry	various on	eration	ne tan	er turning	methods
	thods, special attachments, machining time	-		-	-	
-		-			-	
	s – single spindle, swiss type, automatic	screw type,	multi	spinal	e – Turrei	Indexing
mechanism, Bar f		FO				0
UNIT 111	SPECIAL MACHIN	ES				
						9
	chine tools: shaper, planer, slotter machine	• •		-	-	- Milling:
types, milling cut	ters, operations – Hole making: drilling – Q	• •		-	-	- Milling:
types, milling cut		• •		-	-	- Milling:
types, milling cut	ters, operations – Hole making: drilling – Q	uill mechanis	sm, Re	-	-	- Milling:
types, milling cut Broaching machin UNIT 1V	ters, operations – Hole making: drilling – Q les – Types- Operations ABRASIVE PROCESSES AND G	EAR CUTTI	sm, Re NG	aming	, Boring, T	- Milling: Capping – 9
types, milling cut Broaching machin UNIT 1V Introduction, Class	ters, operations – Hole making: drilling – Q les – Types- Operations	EAR CUTTI	sm, Re NG (Abras	aming ives &	, Boring, T Bond), Se	- Milling: Capping – 9 lection of
types, milling cut Broaching machin UNIT 1V Introduction, Clas Grinding wheel, I machines - honin	ters, operations – Hole making: drilling – Q les – Types- Operations ABRASIVE PROCESSES AND G sification, working of grinding machines, Gr	EAR CUTTI inding wheel	sm, Re NG (Abras ining	aming ives & time -	, Boring, 7 Bond), Se Types of	- Milling: Capping – 9 lection of grinding
types, milling cut Broaching machin UNIT 1V Introduction, Clas Grinding wheel, I machines - honin shaping, hobbing.	ters, operations – Hole making: drilling – Q les – Types- Operations ABRASIVE PROCESSES AND G sification, working of grinding machines, Gr Process parameters - cutting speed, feed, I g, lapping, super finishing, polishing and	EAR CUTTI inding wheel DOC & mach buffing, – G	sm, Re NG (Abras ining	aming ives & time -	, Boring, 7 Bond), Se Types of	- Milling: Tapping – 9 lection of Tgrinding eneration,
types, milling cut Broaching machin UNIT 1V Introduction, Clas Grinding wheel, I machines - honin	ters, operations – Hole making: drilling – Q les – Types- Operations ABRASIVE PROCESSES AND G sification, working of grinding machines, Gr. Process parameters - cutting speed, feed, I	EAR CUTTI inding wheel DOC & mach buffing, – G	sm, Re NG (Abras ining	aming ives & time -	, Boring, 7 Bond), Se Types of	- Milling: Capping – 9 lection of grinding
types, milling cut Broaching machin UNIT 1V Introduction, Clas Grinding wheel, I machines - honin shaping, hobbing. UNIT V Introduction - Mic – Micro drilling – Nano-Machining	ters, operations – Hole making: drilling – Q les – Types- Operations ABRASIVE PROCESSES AND G sification, working of grinding machines, Gr Process parameters - cutting speed, feed, I g, lapping, super finishing, polishing and	EAR CUTTI inding wheel DOC & mach buffing, – G CHINING icro-fabricatio	m, Re NG (Abras ining ear cur on Tec bricatio	aming ives & time - tting, f	Boring, 7	- Milling: Capping – 9 lection of grinding eneration, 9 ro turning lications -
types, milling cut Broaching machin UNIT 1V Introduction, Clas Grinding wheel, I machines - honin shaping, hobbing. UNIT V Introduction - Mic – Micro drilling – Nano-Machining	ters, operations – Hole making: drilling – Q ters, operations ABRASIVE PROCESSES AND G sification, working of grinding machines, Gri Process parameters - cutting speed, feed, I g, lapping, super finishing, polishing and MICRO AND NANO MAC cro-electromechanical Systems (MEMS) - Mi Micro Milling - Silicon Layer Processes - LI – Focused beam lithography – Nano imprin	EAR CUTTI inding wheel DOC & mach buffing, – G CHINING icro-fabricatio	m, Re NG (Abras ining ear cur on Tec bricatio	aming ives & time - tting, f	Boring, 7	- Milling: Capping – 9 lection of grinding eneration, 9 ro turning lications -
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PRACTICAL

LIST OF EXPERIMENTS

- 1. Exercise on centre lathe
 - Facing,
 - Plain turning,
 - Step turning,
 - Taper turning,
 - Knurling
 - Thread cutting
- 2. Exercises in Shaper
 - Round to square
 - Dovetail groove making
- 3. Exercise in Slotter Internal keyway cutting
- 4. Exercises in Drilling machine Drilling and Tapping
- 5. Exercise in Milling Machine External keyway milling
- 6. Exercises in Grinding / Abrasive machining Surface grinding
- 7. Exercise in Gear Hobbing

LIST OF EQUIPMENTS

	(For a batch of 30 students))	
1.	Centre Lathe	15 Nos.	
2.	Turret and Capstan Lathe	1 No.	
3.	Horizontal Milling Machine	1 No.	
4.	Vertical Milling Machine	1 No.	
5.	Surface Grinding Machine	1 No.	
6.	Cylindrical Grinding Machine	1 No.	
7.	Shaper	2 Nos.	
8.	Slotter	1 No.	
9.	Planner	1 No.	
10	Radial Drilling Machine	1 No.	
1		1 No.	
12	•	1 No.	

Course Outcomes				Pro	gram	Out	come	s (PO	s)						m Spe nes (PS	
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3		1			2	1		2			2				3
CO2	3		1			2	1		2			2				3
CO3	3		1			2	1		2			2				3
CO4	3		1			2	1		2			2				3
CO5	3		1			2	1		2			2				3
CO6	3		1			2	1		2			2				2

191ME47	FLUID MECHANICS LABORAT	ORY			L-T-P	C
					0-0-2	1
Programme:	B.E. Mechanical Engineering	Sem:	IV	Ca	tegory:	PC
Prerequisites:	Fluid Mechanics and Machinery				ľ	
Aim:	To impart knowledge of characteristics of fluids					
Course Outcom						
The students will	be able to					
CO1. To measu	re the coefficient of discharge orifice and venturimet	ter				
	es the characteristics of centrifugal pump					
•	e pressure loss due to friction and minor losses in pip	pe flow				
CO4. Perform t	he operations and plot the characteristics curves of v	arious j	oumps			
	nine the efficiency of the Pelton turbine					
	ments in various turbines					
LIST OF EXPER	IMENTS					
1. Determination	of the Coefficient of discharge of given Orifice meter	er.				
2. Determination	of the Coefficient of discharge of given Venturimeter	er.				
3. Calculation of	the rate of flow using Rota meter.					
4. Determination	of friction factor for a given set of pipes.					
5. Conducting ex	periments and drawing the characteristic curves of co	entrifug	gal pur	np / s	ubmergible	pump
6. Conducting ex	periments and drawing the characteristic curves of re-	eciproca	ating p	ump.		
7. Conducting ex	periments and drawing the characteristic curves of G	Bear pui	np.			
8. Conducting ex	periments and drawing the characteristic curves of P	elton w	heel.			
9. Conducting ex	periments and drawing the characteristics curves of I	Francis	turbin	e.		
10. Conducting e	xperiments and drawing the characteristic curves of	Kaplan	turbin	ne.		
LIST OF EQUIP	MENTS					
(For a batch of 30) students)					
1. Orifice meter s	setup					
2. Venturi meter	setup					
3 Rotameter set	up					
4. Pipe Flow anal	ysis setup					
e 1	mp/submergible pump setup					
6. Reciprocating	pump setup					
7. Gear pump set	-					
8. Pelton wheel s	etup					
9. Francis turbine	*					
10. Kaplan turbir	e setup					
I						
Course	Program Outcomes (POs)				Program S	specific

Course Outcomes				Pro	gram	Out	come	s (PO	s)				P C	rograi Jutcom	n Spec les (PS	ific Os)
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3	2		3						2	1	2	3	2		2
CO2	3	2		3						2	1	2	3	2		2
CO3	3	2		3						2		2	3	2		3
CO4	2		3						2	1	2	3	2		2	
CO5	2		3						2	1	2	3	2	2		1
CO6	2		3						2		2	3	2			2

191ME48	MATERIAL TESTING LABORA	TORY			L-T-P	С
	1				0-0-2	1
Programme:	B.E. Mechanical Engineering	Sem:	IV	C	ategory:	PC
Prerequisites:	Materials Engineering	•			i	
	To impart knowledge of motion characteristics of	fmechan	isms a	und m	achines and	to make
Aim:	the students to develop new mechanisms					
Course Outcome	S:					
The students will	be able to					
CO1. Justify the	behavior of structural elements, such as bars, l	beams a	nd co	lumns	s subjected	to tension
compression,	shear, bending, and torsion by means of experiment	ts.				
CO2. Represent	the concepts of hardening and determine the hardne	ess of the	e mate	rial		
CO3. Identify w	ith the tension and compression test on springs					
CO4. Predict the	e hardness of metals					
CO5. Perform th	ne compression test on spring					
CO6. Do micros	scopic examination of metal samples					
	LIST OF EXPERIMENT	ſS				
1. Tension t	est on a mild steel rod					
2. Double sl	near test on Mild steel					
3. Torsion t	est on mild steel rod					
4. Impact te	st on metal specimen					
5. Hardness	test on metals - Brinell and Rockwell Hardness Nu	mber				
6. Deflectio	n test on helical springs					
7. Compress	sion test on helical springs					
8. Deflectio	n test on beams					
9. Microsco	pic Examination of Hardened samples and Hardene	d and ter	npereo	d sam	ples.	
	LIST OF EQUIPMENTS					
	(For a batch of 30 student	,				
	ile Testing machine with double shear attachment -	40 Ton	Capac	ity		
	g Machine (60 N/M Capacity)					
	Machine (300 J Capacity)					
	ss Testing Machine					
	ness Testing Machine					
	Machine for tensile and compressive loads (2500 N	I)				
7. Metallurgical N						
8. Muffle Furnace	e (800°C)					

Course Outcomes				Pro	gram	Out	comes	s (PO	s)				P O	rograr outcom	n Spec es (PS	ific Os)
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3	2		3						2	1	2	3	2		2
CO2	3	2		3						2	1	2	3	2		2
CO3	3	2		3						2	1	2	3	2		2
CO4	3	3		2							1	2	2	2		1
CO5	3	3		2							1	2	2	2		1
CO6	3	3		2							1	2	2	2		1

Programme: B.E. Mechanical Engineering Sem: V Categor Prerequisites: Kinematics of Machinery To understand the method of static and dynamic force analysis of mechanisms and to st undesirable effects of unbalances in rotors, engines and the principles of governors and gyroscopes. Course Outcomes: The students will be able to COL Understand the method of static force analysis and dynamic force analysis of mechanisms COL Understand the method of static force analysis and dynamic force analysis of mechanisms COL Inderstand the method of static force analysis and their analysis COA Recognize the whiting and critical speed of shafts CO5 Examine the forced vibratory systems and their analysis CO6 Analyze the principles of governors, gyroscopes and vibration sensor UNIT 1 FORCE ANALVSIS AND FLYWHELS Static force analysis – D'Alembert's principle – Inertia force and Inertia torque – Dynamic force analysis – Dynamic Analysis in Reciprocating Engines – Crank shaft Torque – Engine shaking Forces – Turning moment diagrams – Flywhecls of engines. UNIT 11 Static and dynamic balancing – Balancing of rotating masses – Balancing a single cylinder Engine – Prima secondary unbalanced forces – Balancing Multi – cylinder Engines. UNIT 11 SINGLE DEGREE OF FREEDOM SYSTEMS – FREE VIBRATION <	191M	E51	DYNAMICS OF MACHINERY				L-T-P	С
Prerequisites: Kinematics of Machinery To understand the method of static and dynamic force analysis of mechanisms and to st undesirable effects of unbalances in rotors, engines and the principles of governors and gyroscopes. Course Outcomes: The students will be able to C01. Understand the method of static force analysis and dynamic force analysis of mechanisms C02. Interpret the concept and basics of free vibratory systems and their analysis C04. Recognize the whirling and critical speed of shafts C05. Analyze the principles of governors, gyroscopes and vibration sensor UNIT 1 FORCE ANALYSIS AND FLYWHEELS Static force analysis – D'Alembert's principle – Inertia force and Inertia torque – Dynamic force analysis – Dynamic Analysis in Reciprocating Engines – Crank shaft Torque – Engine shaking Forces – Turning momen diagrams – Flywheels of engines. UNIT 11 SINCLE DEGREE OF FREEDOM SYSTEMS – FREE VIBRATION Basic features of vibratory systems – Basic elements and lumping of parameters – Degrees of freedom – Sing degree of freedom – Free vibration – Formulation of equations of motion – natural frequency – Types of Dam Damped free vibration – Whirling of shafts and critical speed – Torsional systems – Natural frequency of two three rotor systems. Response to periodic forcing – Harmonic Forcing – Forced vibration , Vibration sensor UNIT V MECHANISMS FOR CONTROL Governors – Types – Centrifugal governors – Gravity controlled and spring controlled centrifugal governors – Characteristics – E							3-0-0	3
To understand the method of static and dynamic force analysis of mechanisms and to st undesirable effects of unbalances in rotors, engines and the principles of governors and gyroscopes. Course Outcomes: The students will be able to COI. Understand the method of static force analysis and dynamic force analysis of mechanisms CO2. Know the undesirable effects of unbalances in rotors and engines CO3. Interpret the concept and basics of free vibratory systems and their analysis CO4. Recognize the whirling and critical speed of shafts CO5. Examine the forced vibratory systems and their analysis CO4. Recognize the whirling and critical speed of shafts CO5. Examine the forced vibratory systems and their analysis CO4. Recognize the whirling and critical speed of shafts CO5. Examine the forced vibratory systems and their analysis CO4. Recognize the whirling and critical speed of shafts CO5. Examine the force on vibratory systems and their analysis CO4. Recognize the whirling and critical speed of shafts CO5. Examine the forced vibratory systems and their analysis CO5. Examine the forced vibratory systems and their analysis CO8. The principles of governors, gyroscopes and vibration sensor UNIT 11 BALANCING Static and dynamic balancing – Balancing of rotating masses – Balancing a single cylinder Engine – Prime	ogram	me:	B.E. Mechanical Engineering	Sem:	V	Ca	ategory:	PC
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 References 1. Shigley J.E., and Uicker J.J., "Theory of Machines and Mechanisms", McGraw-Hill, (2009) 2. Rao J.S. and Dukkipati R.V., "Mechanism and Machine Theory", Wiley-Eastern Limited, New De (2015) 			•	(2005)				
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	2. Ra	ao J.S. and	Dukkipati R.V., "Mechanism and Machine Theory", Wiley	-Eastern	n Limit	ted, N	New Delh	i,
3 Singh V.P. "Theory of Machines" DhannatRai Publishing Company (P) Limited (2010)	(2	2015)						
5. Singh v.r., Theory of Machines , Dhanpattar rubising Company (1) Elinited, (2010)	3. Si	ingh V.P.,	"Theory of Machines", DhanpatRai Publishing Company (P)) Limite	d, (201	10)		
4. Khurmi R.K., Gupta J.K., "Theory of Machines", Eurasia Publishing House, New Delhi, (2014)	4. K	hurmi R.K	., Gupta J.K., "Theory of Machines", Eurasia Publishing Hou	ise, New	v Delh	i, (20	14)	
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Course Outcomes				ŀ	Progr	am O	utcor	nes (I	POs)				Prog		pecific (PSOs)	e Outcomes)
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3	3		2							1	2	2	2		1
CO2	3	3		2							1	2	2	2		1
CO3	3	3		2							1	2	2	2		1
CO4	3	3		2							1	2	2	2		1
CO5	3	3		2							1	2	2	2		1
CO6	3	3		2							1	2	2	2		1

191ME52	THERMAL ENGINEE	RING			L	Τ	Р	C
					3	0	0	3
Programme:	B.E. Mechanical Engineering	Sem:	5	Cate	gory	: PC		
Prerequisites:								
Aim:	To acquire the basic knowledge, and th applications	ermodyna	umic c	concep	ot int	o var	ious	thermal
Course Outcome	s:							
CO2. Know the oCO3. Examine aCO4. Analyze thCO5. Calculate t	the classification of air standard efficiency concepts of PV diagram of four stroke and bout the performance calculation of petrol a e flow of steam through nozzles and to draw he isentropic efficiency of multistage comp te the principle and practice of thermal comp	and diesel w the velc pressor	engin ocity d	e iagrar		ants		
UNIT 1	GAS POWER CYCLES							9
Air standard cycl	es – Otto, Diesel, Dual and Brayton cycle d T-s diagrams – Actual cycles	s – air-sta	andarc	l effic	iency	r — m	ean e	
UNIT 1I	INTERNAL COMBUS	TION EN	GIN	ES				9
Carburetor system Lubrication system calculation UNIT 111 Flow of steam thr	nd port timing diagrams – Comparison of m, Diesel pump and injector system – O em and Cooling system – Battery and <u>STEAM NOZZLES AN</u> ough nozzles, shapes of nozzles, effect of f Reaction principles, compounding, velocity – Governors	Comparis Magneto ND TURE Friction, cr	on of Ignit SINES itical	petro ion S	l and yster	1 dies n –	sel en Perfo	ngine – ormance <u>9</u> aturated
UNIT 1V	AIR COM	PRESSO	R					9
without clearance, compressors, Mul principle of rotary	*	ork of mu	entrop ltistag	ic effi ge air c	cienc comp	y of 1	recipi	ocating perating
UNIT V	REFRIGERATION AND					1.4		<u>9</u>
principle of vapou	on refrigeration cycle – super heat, sub co ar absorption system – Comparison betweer g system: Types, Working Principles – Psyc	n vapour c	ompre	ession	and a	absorp	otion	systems
	Total Periods:4	5						
Text Books:								
	K., "Thermal Engineering", S.Chand Public P.L, "Thermal Engineering", Khanna Publ							
References:								
 Sarkar B.I Rudramoo 	9, "Refrigeration and Air Conditioning", Ta K., "Thermal Engineering", McGraw Hill F orthy R., "Thermal Engineering", Tata McC R.S. & Gupta J.K., "Refrigeration and Air C	Publication Graw-Hill	n, (200 , New)1) Delhi	, (20	09)		(2006)

Course		Program Outcomes (POs)												Program Specific Outcomes (PSOs)			
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	
CO1	2	2										3	2				
CO2		2	3	3								3		3			
CO3			3		2							1				2	
CO4		3		1	2							3		3			
CO5		3	2									1			2		
CO6				1	2							3				3	

191ME53	APPLIED HYDRAULICS AN	D PNEU	JMA	FICS	L-T-P	С
					3-1-0	4
Programme:	B.E. Mechanical Engineering	Sem:	V	Category:	PC	
Prerequisites:	Fluid Mechanics and Machinery					
A :	To know the advantages and applications	of fluid p	ower s	system in auto	mation of m	nachine
Aim:	tools and other equipments.			-		
Course Outcom	les:					
The students will	be able to					
CO1. Understand	the fundamentals of hydraulic and pneumati	c systems				
	proper hydraulic cylinders for specific applic					
	ious components of pneumatic system used i		applica	ations		
	e electronic circuits used in pneumatic system	ns				
	hydraulic circuits with various components					
	chematic diagrams to construct pneumatic ci					
UNIT 1	FLUID POWER SYSTEMS AN					9
	id power, Advantages and application – Type					
÷	lisposing of fluids – Fluid power Symbols -	- Basics o	f hydr	aulics – Appli	cations of p	bascal's
law.				NIEG		-
UNIT 1I	HYDRAULIC SYSTEMS				. 1 11	9
	tors: Linear hydraulic actuators – Types of h					
	rs special cylinders like tanden, rodless, teles e and piston motors-Hydraulic Powerpacks	-	l cushi	oning devices	, Rotary ac	tuators
– Fluid gear, van						
e :				ONENITO		0
UNIT 111	PNEUMATIC SYSTEM	S AND C			iak avhaust	9
UNIT 111 Properties of air –	PNEUMATIC SYSTEM Compressors – Filter, Regulator, Lubricator	S AND C Unit – A	ir cont	rol valves, Qu		valves
UNIT 111 Properties of air – pneumatic actuato	PNEUMATIC SYSTEM Compressors – Filter, Regulator, Lubricator rs – Fluid power circuit design, Speed control	$\frac{S \text{ AND } C}{\text{Unit} - A}$	ir cont ynchr	rol valves, Qu onizing circuit	, Penumo hy	valves draulio
UNIT III Properties of air – pneumatic actuato circuit, Sequential	PNEUMATIC SYSTEM Compressors – Filter, Regulator, Lubricator	$\frac{S \text{ AND } C}{\text{Unit} - A}$	ir cont ynchr	rol valves, Qu onizing circuit	, Penumo hy	valves draulio
UNIT III Properties of air – pneumatic actuato circuit, Sequential Powerpacks.	PNEUMATIC SYSTEM Compressors – Filter, Regulator, Lubricator rs – Fluid power circuit design, Speed control l circuit design for simple applications usi	S AND C Unit – A circuits, s ng cascad	ir cont ynchro e met	rol valves, Qu onizing circuit, hod- Robotic	, Penumo hy	valves draulic eumatic
UNIT 111 Properties of air – pneumatic actuato circuit, Sequential Powerpacks. UNIT 1V	PNEUMATIC SYSTEM Compressors – Filter, Regulator, Lubricator rs – Fluid power circuit design, Speed control l circuit design for simple applications usi DESIGN OF HYDRA	S AND C Unit – A circuits, s ng cascad ULIC CI	ir cont synchro e met RCUI	rol valves, Qu onizing circuit, hod- Robotic TS	, Penumo hy circuits-Pne	valves draulic eumatic 9
UNIT III Properties of air – pneumatic actuato circuit, Sequential Powerpacks. UNIT 1V Directional contro	PNEUMATIC SYSTEM Compressors – Filter, Regulator, Lubricator rs – Fluid power circuit design, Speed control l circuit design for simple applications usi DESIGN OF HYDRA l valve – 3/2 way valve – 4/2 way valve – Sh	S AND C Unit – A circuits, s ng cascad ULIC CI uttle valve	ir cont synchro e met RCUI e – che	rol valves, Qu onizing circuit, hod- Robotic TS eck valve – pre	, Penumo hy circuits-Pne	valves draulic eumatic <u>9</u> ol valve
UNIT III Properties of air – pneumatic actuato circuit, Sequential Powerpacks. UNIT 1V Directional contro – pressure reducin	PNEUMATIC SYSTEM Compressors – Filter, Regulator, Lubricator rs – Fluid power circuit design, Speed control l circuit design for simple applications usi DESIGN OF HYDRA l valve – 3/2 way valve – 4/2 way valve – Sh g valve, sequence valve, Flow control valve	S AND C Unit – A circuits, s ng cascad ULIC CI uttle valve – Fixed at	ir cont synchre e met RCUI e – che nd adju	rol valves, Qu onizing circuit, hod- Robotic TS eck valve – pre istable, electric	, Penumo hy circuits-Pne ssure contro cal control so	valves vdraulic eumatic 9 ol valve olenoic
UNIT 111 Properties of air – pneumatic actuato circuit, Sequential Powerpacks. UNIT 1V Directional contro – pressure reducin valves, relays, 1	PNEUMATIC SYSTEM Compressors – Filter, Regulator, Lubricator rs – Fluid power circuit design, Speed control l circuit design for simple applications usi DESIGN OF HYDRA l valve – 3/2 way valve – 4/2 way valve – Sh g valve, sequence valve, Flow control valve adder diagram – Types of accumulators –	S AND C Unit – A circuits, s ng cascad ULIC CI uttle valve – Fixed an - Accumu	ir cont synchro e met RCUI e – cho nd adju lators	rol valves, Qu onizing circuit, hod- Robotic TS eck valve – pre istable, electric circuits, sizin	, Penumo hy circuits-Pne ssure contro cal control so g of accumo	valves draulic eumatic 9 ol valve olenoic ulators
UNIT 111 Properties of air – pneumatic actuato circuit, Sequential Powerpacks. UNIT 1V Directional contro – pressure reducin valves, relays, 1 intensifier – Appli	PNEUMATIC SYSTEM Compressors – Filter, Regulator, Lubricator rs – Fluid power circuit design, Speed control l circuit design for simple applications usi DESIGN OF HYDRA l valve – 3/2 way valve – 4/2 way valve – Sh g valve, sequence valve, Flow control valve adder diagram – Types of accumulators – ications of intensifier – Intensifier circuit – s	S AND C Unit – A circuits, s ng cascad ULIC CI uttle valve – Fixed an - Accumu simple pro-	ir cont synchro e met RCUI e – che nd adju lators blems	rol valves, Qu onizing circuit, hod- Robotic TS eck valve – pre istable, electric circuits, sizin	, Penumo hy circuits-Pne ssure contro cal control so g of accumo	valves draulic eumatic 9 ol valve olenoic ulators
UNIT III Properties of air – pneumatic actuato circuit, Sequential Powerpacks. UNIT 1V Directional contro – pressure reducin valves, relays, 1 intensifier – Appli Drilling, Planning	PNEUMATIC SYSTEM Compressors – Filter, Regulator, Lubricator rs – Fluid power circuit design, Speed control l circuit design for simple applications usi DESIGN OF HYDRA l valve – 3/2 way valve – 4/2 way valve – Sh g valve, sequence valve, Flow control valve adder diagram – Types of accumulators –	S AND C Unit – A circuits, s ng cascad ULIC CI uttle valve – Fixed ar - Accumu simple pro ft applicat	ir cont synchro e met RCUI e – cho nd adju lators blems cions.	rol valves, Qu onizing circuit, hod- Robotic TS eck valve – pre ustable, electric circuits, sizin, - Design of hy	, Penumo hy circuits-Pne ssure contro cal control so g of accumo	valves draulic eumatic 9 ol valve olenoic ulators
UNIT III Properties of air – pneumatic actuato circuit, Sequential Powerpacks. UNIT IV Directional contro – pressure reducin valves, relays, 1 intensifier – Appli Drilling, Planning UNIT V Servo systems – H fluidic devices, sim power circuits – troubleshooting- E	PNEUMATIC SYSTEM Compressors – Filter, Regulator, Lubricator rs – Fluid power circuit design, Speed control l circuit design for simple applications usi DESIGN OF HYDRA l valve – 3/2 way valve – 4/2 way valve – Sh g valve, sequence valve, Flow control valve adder diagram – Types of accumulators – ications of intensifier – Intensifier circuit – s , Shaping, Surface grinding, Press and Forkli	S AND C Unit – A circuits, s ng cascad ULIC CI uttle valve – Fixed an - Accumu simple pro ft applicat ATIC CI ystems ar ic pneuma ic and p	RCUI e met e che d adju lators blems ions. RCUI d proj tic log neuma	rol valves, Qu onizing circuit, hod- Robotic TS eck valve – pre istable, electric circuits, sizin - Design of hy TS portional valve ic circuits, lado tic power pa	, Penumo hy circuits-Pne ssure contro cal control se g of accum rdraulic circ es – Introdue ler diagrams cks – failu	valves draulic eumatic 9 ol valve olenoid ulators uits for 9 ction te 5- Fluid ure and
UNIT III Properties of air – pneumatic actuato circuit, Sequential Powerpacks. UNIT 1V Directional contro – pressure reducin valves, relays, 1 intensifier – Appli Drilling, Planning UNIT V Servo systems – H fluidic devices, sim power circuits –	PNEUMATIC SYSTEM Compressors – Filter, Regulator, Lubricator rs – Fluid power circuit design, Speed control l circuit design for simple applications usi DESIGN OF HYDRA l valve – 3/2 way valve – 4/2 way valve – Sh g valve, sequence valve, Flow control valve adder diagram – Types of accumulators – ications of intensifier – Intensifier circuit – s , Shaping, Surface grinding, Press and Forkli DESIGN OF PNEUM Hydro Mechanical, Electro hydraulic servo s nple circuits – Introduction to electro hydrauli Installation and maintenance of hydraul	S AND C Unit – A circuits, s ng cascad ULIC CI uttle valve – Fixed an - Accumu simple pro ft applicat ATIC CI ystems ar ic pneuma ic and p	RCUI e met e che d adju lators blems ions. RCUI d proj tic log neuma	rol valves, Qu onizing circuit, hod- Robotic TS eck valve – pre ustable, electric circuits, sizin, - Design of hy TS portional valve ic circuits, lade tic power pa nd tool handlir	, Penumo hy circuits-Pne ssure control cal control se g of accum draulic circ es – Introduc ler diagrams cks – failu ag in CNC M	valves draulic eumatic 9 ol valve olenoic ulators uits for 9 ction to Fluid tre and fachind
UNIT III Properties of air – pneumatic actuato circuit, Sequential Powerpacks. UNIT 1V Directional contro – pressure reducin valves, relays, 1 intensifier – Appli Drilling, Planning UNIT V Servo systems – H fluidic devices, sim power circuits – troubleshooting- D tools.	PNEUMATIC SYSTEM Compressors – Filter, Regulator, Lubricator rs – Fluid power circuit design, Speed control l circuit design for simple applications usi DESIGN OF HYDRA l valve – 3/2 way valve – 4/2 way valve – Sh g valve, sequence valve, Flow control valve adder diagram – Types of accumulators – ications of intensifier – Intensifier circuit – s , Shaping, Surface grinding, Press and Forkli DESIGN OF PNEUM Hydro Mechanical, Electro hydraulic servo s nple circuits – Introduction to electro hydrauli Installation and maintenance of hydraul	S AND C Unit – A circuits, s ng cascad ULIC CI uttle valve – Fixed an - Accumu simple pro ft applicat ATIC CI ystems ar ic pneuma ic and p	RCUI e met e che d adju lators blems ions. RCUI d proj tic log neuma	rol valves, Qu onizing circuit, hod- Robotic TS eck valve – pre ustable, electric circuits, sizin, - Design of hy TS portional valve ic circuits, lade tic power pa nd tool handlir	, Penumo hy circuits-Pne ssure contro cal control se g of accum rdraulic circ es – Introdue ler diagrams cks – failu	valves draulic eumatic 9 ol valve olenoid ulators uits for 9 ction te 5- Fluid ure and
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Course Outcomes		Program Outcomes (POs)												Program Specific Outcomes (PSOs)			
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	
CO1	2	2	3	2								2	2				
CO2	2		3									2		3			
CO3		2	3	3	2							1		3			
CO4	2	1		2								1			2		
CO5	2	1	1	1								2			2		
CO6		2	2	1	2							1				3	

191ME54	ELECTRONICS INSTRUMENTATIO	ON AND CO	NTRO)L	L-T-P	С
1,11,11,11,11,1				-	3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:	V	C	ategory:	PC
Prerequisites:	Nil				8 1	
Aim:	To understand the principles, methods and a	applications of	of meas	urem	ents	
Course Outcomes:	1 1 /	11				
The students will be	able to					
CO1. Understand the	e basic concepts of measurements					
CO2. Familiarize the	e displacement measurement instrumentation					
CO3. Explain the ap	plications of transducers in measurements					
CO4. Describe the e	lements of control system					
CO5. Analyze the tin	me response					
CO6. Practice the sta						
UNIT 1	BASIC MEASUREMEN					9
-	asurements systems - units and standards					-
	g coil, moving iron meters – multimeters Er	rors in meas	uremer	nt -Ty	pes of errors	s, Effect of
component errors.						
UNIT 1I	SENSORS AND TH					9
	arement –LVDT, Digital Transducers (optica					
Strain gauge based	load cells and torque sensors Pressure M	Measurement	- Elas	stic p	ressure trans	ducers viz.
Bourdon tubes, diapl	rragm, bellows and piezoelectric pressure sense	sors, Amplifi	cation -	– Filte	ering – Sampl	e and Hold
circuits						
UNIT 1II	SYSTEMS AND REPR	ESENTATIO	DN			9
Basic elements in co	ntrol systems: - Open and closed loop syster	ns – Mathem	atical r	nodel	ling of contr	ol systems,
concept of transfer f	unction - AC and DC servomotors – Block di	iagram reduct	ion tec	hniqu	les.	
UNIT 1V	TIME RESPONS	F				9
	ime domain specifications – Types of test		1 II or	der sv	ustem respor	1
•	s of P, PI, PID modes of feedback control – Ti	•		-	ystem respon	
coefficients - Effects		line response	anarysi	15.		
UNIT V	STABILITY ANALYS	SIS				9
	epts of stability - The Routh criteria for stal		imenta	l dete	ermination of	² frequency
	analysis using Bode plot - Process control s	•				
applications		· j - · · - · · j - · · ·				
11				Tota	I Periods:	45
Text Books						
	. and Gopal, M., "Control Systems Engineeri	ng". New Ag	e Interi	nation	al Publishers	. 2017
-	A.K "A Course in Electrical & Electronic Mea					
Co, New De					, <u>,,,,,</u> ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	
References	, - ••					
	ll, "Electronic Instrumentation and Measurem	nents". Oxfor	d Univ	ersitv	Press. 2013	
	D.and W.D.Cooper, "Modern Electronic Instr			•		
	1 India Private Ltd., 2010.	unionation a		.54101		[
	A. "Control system Engineering" 3 rd Edition	RBA Public	ation ?	011		
4.	11. Contor system Engineering 5 Edition		au 011 Z	VII.		
т,						

Course Outcomes				Pro	ogram	Outo	omes	(POs)				I (Program Dutcom	m Spec les (PS	ific Os)
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3	2	1	2								2	3	2		1
CO2	3	2	1	2								2	3	2		1
CO3	3	2	1	2			2					2	3	2		1
CO4	3	1	2	1								2	3	2		1
CO5	3	1	2	1								2	3	2		1
CO6	3	1	2	1			2					2	3	2		1

191ME55	MACHINE DESIGN AND DRA	WING			L-'	T-P	С
171111100	(PSG Design Data Book is permitt					0-2	4
Programme:	B.E. Mechanical Engineering	Sem:	V	Categ		<u>P</u>	
Prerequisites:		~~~~~	•	enreg	0131	-	-
Aim:	To study the design principles and procedures o	f Machin	o Flo	ments			
	To study the design principles and procedures of			ments			
Course Outcomes:	11 /						
The students will be							
	e materials and evaluate the failure of machine ele	ments					
	e strength of shafts & coupling jack with suitable thread						
	mporary and permanent joints depends on application	ion					
	le spring for automobile applications	.1011					
	e bearing design in their project work						
UNIT 1	STEADY AND VARIABLE STRESSES I	N MACI	HINF	PART	8		12
	gn process – Selection of materials – Fits and toler					l torsi	
	Application of Principal stresses in designing ma						
	- Stress concentration due to holes and notche						
relations			, ei, c	, coulina		50401	
	: Tolerance zone, Types of fits & Stress concentrat	ion - Indı	ıstrial	drawin	g and	bluep	rint.
Geometrical dimens	• • •				0	1	,
UNIT 1I	SHAFTS AND COUPLINGS	}					12
	fts based on strength, rigidity and critical speed -		of ke	ys – De	sign o	of rigi	
flexible couplings -		C		•	C	e	
**Manual Drawing	g: Flange Coupling & Bushed pin type coupling						
UNIT 1II	POWER SCREWS AND LEVE	RS					12
	w threads in power screws - Types of threads -						
	k – Introduction of levers – Design of a lever – I	Iand leve	ers, fo	oot leve	rs, sa	fety v	alve
levers & rocker arm							
	Screw Jack & Rocker arm for exhaust valve						
UNIT 1V	TEMPORARY AND PERMANENT						12
Design of Knuckle	TEMPORARY AND PERMANENT joint – Design of socket and spigot joint, sleeve	and cot	ter jo				be –
Design of Knuckle Applications – Desi	TEMPORARY AND PERMANENT joint – Design of socket and spigot joint, sleeve gn of welded joints, Welding symbols – Applicati	and cot	ter jo				be –
Design of Knuckle Applications – Design of rivet heads – App	TEMPORARY AND PERMANENT joint – Design of socket and spigot joint, sleeve gn of welded joints, Welding symbols – Applicati plications	and cot	ter jo				be –
Design of Knuckle Applications – Desi of rivet heads – App	TEMPORARY AND PERMANENT joint – Design of socket and spigot joint, sleeve gn of welded joints, Welding symbols – Applicati	and cot	ter jo				be –
Design of Knuckle Applications – Desig of rivet heads – App **Manual Drawing UNIT V	TEMPORARY AND PERMANENT joint – Design of socket and spigot joint, sleeve gn of welded joints, Welding symbols – Applicati blications g: Knuckle joint & Pipe joints SPRINGS AND BEARING	and cott ons – De	ter jo sign	of rivete	ed join	nts, T	pe – /pes 12
Design of Knuckle Applications – Desi of rivet heads – App **Manual Drawing UNIT V Design of helical spi	TEMPORARY AND PERMANENT joint – Design of socket and spigot joint, sleeve gn of welded joints, Welding symbols – Applications g: Knuckle joint & Pipe joints SPRINGS AND BEARING rings – compression & tension springs – Leaf spring	and cott ons – De S g – Belle	ter jo sign o	of rivete	- App	nts, Ty	be – /pes 12 ns –
Design of Knuckle Applications – Desig of rivet heads – App **Manual Drawing UNIT V Design of helical spi Sliding contact bear	TEMPORARY AND PERMANENT joint – Design of socket and spigot joint, sleeve gn of welded joints, Welding symbols – Applications g: Knuckle joint & Pipe joints SPRINGS AND BEARING rings – compression & tension springs – Leaf sprintings – Design of hydrodynamic bearings – McKe	and cott ons – De S g – Belle e's Equat	ter jo esign eville ion, S	of rivete spring – Sommer	- App field	nts, Ty	<u>pe</u> – /pes <u>12</u> ns – per –
Design of Knuckle Applications – Desig of rivet heads – App **Manual Drawing UNIT V Design of helical spi Sliding contact bear Selection of lubricat	TEMPORARY AND PERMANENT joint – Design of socket and spigot joint, sleeve gn of welded joints, Welding symbols – Applications g: Knuckle joint & Pipe joints SPRINGS AND BEARING rings – compression & tension springs – Leaf spring	and cott ons – De S g – Belle e's Equat	ter jo esign eville ion, S	of rivete spring – Sommer	- App field	nts, Ty	<u>pe</u> – /pes <u>12</u> ns – per –
Design of Knuckle Applications – Desig of rivet heads – App **Manual Drawing UNIT V Design of helical spr Sliding contact bear Selection of lubricat – Applications	TEMPORARY AND PERMANENT joint – Design of socket and spigot joint, sleeve gn of welded joints, Welding symbols – Applications g: Knuckle joint & Pipe joints SPRINGS AND BEARING rings – compression & tension springs – Leaf sprint ings – Design of hydrodynamic bearings – McKe ion – Rolling contact bearings – Life of bearings –	and cott ons – De S g – Belle e's Equat	ter jo esign eville ion, S	of rivete spring – Sommer	- App field	nts, Ty	<u>pe</u> – /pes <u>12</u> ns – per –
Design of Knuckle Applications – Desig of rivet heads – App **Manual Drawing UNIT V Design of helical spr Sliding contact bear Selection of lubricat – Applications	TEMPORARY AND PERMANENT joint – Design of socket and spigot joint, sleeve gn of welded joints, Welding symbols – Applications g: Knuckle joint & Pipe joints SPRINGS AND BEARING rings – compression & tension springs – Leaf sprintings – Design of hydrodynamic bearings – McKe	and cott ons – De S g – Belle e's Equat	ter jo esign eville ion, S	of rivete spring – Sommer	- App field	nts, Ty	<u>pe</u> – /pes <u>12</u> ns – per –
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Design of Knuckle Applications – Desig of rivet heads – App **Manual Drawing UNIT V Design of helical spr Sliding contact bear Selection of lubricat – Applications **Manual Drawing Text Books: 1. Gupta J.K., 2. Narayanan H References: New R	TEMPORARY AND PERMANENT joint – Design of socket and spigot joint, sleeve gn of welded joints, Welding symbols – Applications gr: Knuckle joint & Pipe joints SPRINGS AND BEARING rings – compression & tension springs – Leaf spring ings – compression & tension springs – Leaf spring ings – Design of hydrodynamic bearings – McKe ion – Rolling contact bearings – Life of bearings – g: Leaf spring & Bearings Lecture: 45 "A Textbook of Machine Design", Eurasia Publisk K.L., "Machine Design", Khanna Publishers, (201 teferences are added	and cott ons – De g – Belle e's Equat Selection Practice: ning Hou 4)	eville ion, S of R 15 use, (2	of rivete spring – Sommer olling C Tota 2014)	- App field Contac	licatic Numb	ns – ings
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Design of Knuckle Applications – Desig of rivet heads – App **Manual Drawing UNIT V Design of helical spr Sliding contact bear Selection of lubricat: – Applications **Manual Drawing Text Books: 1. Gupta J.K., 2. Narayanan H References: New R 1. Bhandari V. 2. Shigley, J.J. McGraw-Hi 3. Juvinal, R.C	TEMPORARY AND PERMANENT joint – Design of socket and spigot joint, sleeve gn of welded joints, Welding symbols – Applications g: Knuckle joint & Pipe joints SPRINGS AND BEARING rings – compression & tension springs – Leaf sprin ings – compression & tension springs – Leaf spring ings – Design of hydrodynamic bearings – McKe ion – Rolling contact bearings – Life of bearings – g: Leaf spring & Bearings Lecture: 45 "#A Textbook of Machine Design", Eurasia Publisk K.L., "Machine Design", Khanna Publishers, (201 deferences are added B., "Design of Machine Elements", Tata McGraw E. and Mischke, C.R., Mechanical Engineer	and cott ons – De g – Belle e's Equat Selection Practice: hing Hou 4) -Hill Bo ing Des	eville sign eville ion, S of R se, (2 ok Co sign, iley,	of rivete spring – Sommer olling C Tota 2014) 5, (2016 Fifth 1 1994.	- App field Contac	icatic Numb t bear	ns – ings

Course Outcomes]	Progr	am O	outcor	nes (I	POs)				Pr Ot	ogram utcome	Specifies (PSC	fic Ds)
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3	2	3	2						2		2	2	3		2
CO2	3	3	3	2						2		2	2	3		3
CO3	3	3	3	2						2		2	3	3		3
CO4	3	3	3	2						2		2	3	1		3
CO5	3	3	3	2						2		2	3	3		3
CO6	3	2	3	2						2		2	3	3		3

191ME57	DYNAMICS LABORA	ATORY			L-T-P	С	
					0-0-2		1
Programme:	B.E. Mechanical Engineering	Sem:	V	Ca	tegory:	PC	
Prerequisites:							
Aim:	To educate the students to apply the ki	netic solutions	to va	iriou	s experim	ents	
Course Outcom	es:						
The students will	be able to						
CO1. Know the	functions of kinematic links and its me	chanisms					
CO2. Interpret	the fundamentals of the natural frequence	y of free vibra	tion o	of fiz	ked beam		
CO3. Find the g	gyroscopic effect						
CO4. Determin	e the basic concepts of governor apparat	tus					
CO5. Identify t	he different cam profile mechanisms						

LIST OF EXPERIMENTS

- 1. Study of velocity ratios of simple, compound, Epicyclic and differential gear trains.
- 2. Study of kinematics of Four Bar, Slider Crank, Crank Rocker, Double crank, Double rocker, Oscillating cylinder Mechanisms.
- 3. Determination of Mass moment of inertia of Fly wheel and Axle system.
- 4. Determination of Mass Moment of Inertia of axis symmetric bodies using Turn Table apparatus.
- 5. Determination of Mass Moment of Inertia using bifilar suspension and compound pendulum.
- 6. Determination of gyroscopic effect and couple.
- 7. Determination of range sensitivity, effort etc., for Watts, Porter and Proell Governors.
- 8. Cam profile and Motion curve drawings
- 9. Determination of natural Frequency and verification of Laws of springs in Single degree of
- 10. freedom Spring Mass System.
- 11. Determination of torsional natural frequency of single and Double Rotor systems.
- 12. Vibration of Equivalent Spring mass system.
- 13. Determination of critical speeds of shafts.
- 14. Balancing of rotating masses
- 15. Transverse vibration of fixed beam with and without concentrated masses.

Total Periods: 45

LIST OF EQUIPMENTS

(For a batch of 30 students)

1. Cam analyzer	1 No.
2. Motorized gyroscope	1 No.
3. Governor apparatus - Watt, Porter, Proell and Hartnell governors	1 No.
4. Whirling of shaft apparatus	1 No.
5. Static and dynamic balancing machine	1 No.
6. Vibrating table	1 No.
7. Vibration test facilities apparatus	1 No.
8. Gear Model	1 No.
9. Kinematic Models to study various mechanisms	1 No

Course Outcomes				ł	Progr	am O	utcor	nes (l	POs)						Specif s (PSC	
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3	2		2					3			2		3	1	3
CO2	3	2		3					3			2		3	2	3
CO3	2	3		2					3			2		2		3
CO4	3	3		2					3			2		2		2
CO5	3	3		2					3			2		3		3
CO6	3	2		3					3			2		2		3

Programme: B.E. Mechanical Engineering Sem: 5 Category Prerequisites: Image: Course Outcomes: Ima	P (L-T-P	RY	RATOR	INEERING LABO	THERMAL ENGINEER	191ME58
Prerequisites:	2	0-0-2					
Aim: To obtain the basic knowledge about internal combustion engine and its pe Course Outcomes: The students will be able to CO1. Draw the valve timing and port timing diagram for petrol & diesel engine CO2. Find the flash point / fire point and viscosity for the given sample	PC	Category:	5	Sem:	ing	B.E. Mechanical Engineering	Programme:
Course Outcomes: The students will be able to CO1. Draw the valve timing and port timing diagram for petrol & diesel engine CO2. Find the flash point / fire point and viscosity for the given sample							Prerequisites:
The students will be able to CO1. Draw the valve timing and port timing diagram for petrol & diesel engine CO2. Find the flash point / fire point and viscosity for the given sample	formance	nd its perfor	engin	mbustion	edge about internal co	To obtain the basic knowledge abo	Aim:
CO1. Draw the valve timing and port timing diagram for petrol & diesel engine CO2. Find the flash point / fire point and viscosity for the given sample						5:	Course Outcome
CO2. Find the flash point / fire point and viscosity for the given sample						be able to	The students will I
			ne	iesel engi	liagram for petrol & d	lve timing and port timing diagram	CO1. Draw the va
				nple	osity for the given san	h point / fire point and viscosity for	CO2. Find the flas
CO3. Determine the performance and efficiency of petrol / diesel engine				igine	cy of petrol / diesel er	ne performance and efficiency of pe	CO3. Determine the
CO4. Identify the performance difference of various engines				C			
CO5. Draw the heat balance sheet for SI/CI engine							

LIST OF EXPERIMENTS

- 1. Valve Timing and Port Timing Diagrams
- 2. Performance Test on 4-stroke Diesel Engine
- 3. Heat Balance Test on 4-stroke Diesel Engine
- 4. Morse Test on Multi cylinder Petrol Engine
- 5. Retardation Test to find Frictional Power of a Diesel Engine
- 6. Determination of Viscosity Red Wood Viscometer
- 7. Determination of Flash Point and Fire Point
- 8. Study of Steam Generators and Turbines

Total Periods: 45

LIST OF EQUIPMENTS (For a batch of 30 students)

1.	I.C Engine – 2 Stroke and 4 Stroke model	1 set
2.	Red Wood Viscometer	1 No.
3.	Apparatus for Flash and Fire Point	1 No.
4.	4-Stroke Diesel Engine with mechanical loading	1 No.
5.	4-Stroke Diesel Engine with hydraulic loading.	1 No.
6.	4-Stroke Diesel Engine with electrical loading	1 No.
7.	Multi-cylinder Petrol Engine	1 No.

Course Outcomes				I	Progr	am O	utcor	nes (I	POs)				Pr Ou	ogram itcome	Specit s (PSC	fic Ds)
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	2	1	1	2		2	1			1		1	2	3		1
CO2	2	2	2	2		2	2			1		2	2	3		1
CO3	2	3	2	2		2	2			1		2	2	3		1
CO4	2	3	2	2		2	2			1		2	2	3		1
CO5	2	3	2	2		2	2			1		2	2	3		1
CO6	2	2	2	1		2	2			1		2	2	3		1

191ME61	AUTOMATION IN MANUI	FACTURING	L-T-P	С
	•		3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem: V	Category:	РС
Prerequisites:				
1	To gain the knowledge about the Advanced	d and computerized N	/anufacturing Te	chniques
Aim:	followed in the Shop floor of the Industrie		8	1
Course Outcome	· · · · · · · · · · · · · · · · · · ·			
The students will b				
	iderstand the concept of CIM			
	plain the components of CIM			
	cognize the Group Technology and CAPP			
CO4. Lis	st out the various techniques in shop floor co	ontrol		
	now the concept of FMS			
	miliarize the computer aided planning and c			
UNIT 1	BASICS OF CIN	1		9
Brief introductio	n to CAD and CAM - Manufactur	ing Planning, Ma	nufacturing co	ntrol –
Introduction to C.	AD/CAM – Concurrent Engineering – C	CIM concepts – Con	mputerized elen	nents of
	pes of production – Typical CAD comma			
modeling and sol	id modeling (concepts only) in relation t	o popular CAD pac	ckages	
UNIT 11	COMPONENTS OF CI	M I I I I I I I I I I I I I I I I I I I	C	9
	and a technology, CASA/SME model of Cl	M, CIM II, benefits	of CIM, commu	nication
	ndamentals of computer communication i			
	ynchronous, synchronous, modulation, der			
serial, parallel, asy		nouuluiton, simpler	and duplex -1	ypes of
	CIM – point to point (PTP), star and multi	· •	•	• •
communication in	· · · ·	plexing. Computer 1	networking in CI	M - the
communication in seven layer OSI mo	CIM – point to point (PTP), star and multipodel, LAN model, MAP model, network	plexing. Computer 1	networking in CI	M - the
communication in seven layer OSI mo of networks in CIN UNIT 111 GR	CIM – point to point (PTP), star and multiodel, LAN model, MAP model, network	plexing. Computer 1 topologies – star, ri CR AIDED PROCE	networking in CI ing and bus, adv SS PLANNING	M - the vantages
communication in seven layer OSI mo of networks in CIN UNIT 111 GR History Of Group	CIM – point to point (PTP), star and multi odel, LAN model, MAP model, network A COUP TECHNOLOGY AND COMPUTE Technology – role of G.T. in CAD/CAM I	plexing. Computer n topologies – star, ri CR AIDED PROCE ntegration – part fan	networking in CI ing and bus, adv SS PLANNING nilies – classifica	M – the vantages 9 tion and
communication in seven layer OSI mo of networks in CIN UNIT 111 GR History Of Group coding – DCLASS	CIM – point to point (PTP), star and multi odel, LAN model, MAP model, network A COUP TECHNOLOGY AND COMPUTE Technology – role of G.T. in CAD/CAM I and MICLASS and OPTIZ coding systems	plexing. Computer i topologies – star, ri CR AIDED PROCE ntegration – part fan – facility design usir	networking in CI ing and bus, adv SS PLANNING nilies – classifica ng G.T. – benefits	M – the vantages 9 tion and s of G.T.
communication in seven layer OSI mo of networks in CIM UNIT 111 GR History Of Group coding – DCLASS – cellular manufact	CIM – point to point (PTP), star and multi odel, LAN model, MAP model, network A COUP TECHNOLOGY AND COMPUTE Technology – role of G.T. in CAD/CAM I and MICLASS and OPTIZ coding systems uring – Process planning – role of process pl	plexing. Computer i topologies – star, ri CR AIDED PROCE ntegration – part fan – facility design usir anning in CAD/CAM	networking in CI ing and bus, adv SS PLANNING nilies – classifica ng G.T. – benefits	M – the vantages 9 tion and of G.T.
communication in seven layer OSI mo of networks in CIN UNIT 111 GR History Of Group coding – DCLASS – cellular manufact to computer aided p	CIM – point to point (PTP), star and multi odel, LAN model, MAP model, network A COUP TECHNOLOGY AND COMPUTE Technology – role of G.T. in CAD/CAM I and MICLASS and OPTIZ coding systems uring – Process planning – role of process planning – process planning – variant approach and gen	plexing. Computer in topologies – star, ri CR AIDED PROCE ntegration – part fan – facility design usir anning in CAD/CAM erative approaches	networking in CI ing and bus, adv SS PLANNING nilies – classifica ng G.T. – benefits	M – the vantages 9 tion and s of G.T.
communication in seven layer OSI mo of networks in CIN UNIT 111 GR History Of Group coding – DCLASS – cellular manufact to computer aided p UNIT 1V	CIM – point to point (PTP), star and multi odel, LAN model, MAP model, network A COUP TECHNOLOGY AND COMPUTE Technology – role of G.T. in CAD/CAM I and MICLASS and OPTIZ coding systems uring – Process planning – role of process plan process planning – variant approach and gen SHOP FLOOR CONTRO	plexing. Computer in topologies – star, ri CR AIDED PROCE ntegration – part fan – facility design usir anning in CAD/CAM erative approaches DL AND FMS	networking in CI ing and bus, adv SS PLANNING nilies – classifica ng G.T. – benefits I Integration – app	M – the vantages <u>9</u> tion and s of G.T. proaches <u>9</u>
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Course Outcomes				ł	Progr	am O	utcor	nes (l	POs)				Pr Ou	ogram itcome	Specif s (PSC	fic Ds)
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	1				2	1	2			2	2	3		3	3	3
CO2	1				3	2	2			2		3		3	2	3
CO3					3	2	2			2		3		3	2	3
CO4					3	2	2			3		3		3	2	3
CO5	2			1	3	2	3			3		3		3	2	3
CO6		3	3	2	2	2	2			2		3		3	1	3

191ME62	DESIGN OF TRANSMISSION S	SYSTEM	5	L-T-P	С
				3-1-0	4
Programme:	B.E. Mechanical Engineering	Sem:	VI	Category:	PC
Prerequisites:					
Aim:	To study the design principles and procedures	of Transm	ission	systems	
Course Outcome				<i>.</i>	
The students will					
	concepts of various power transmission systems				
	esign flat, V belt drives and chain drives				
	mission between parallel shafts and design spur	& helical	gears		
CO4. Visualize tra	ansmission between intersecting shafts and desig	gn the beve	el & w	orm gears	
CO5. Prepare kind	ematic layout and structural arrangement of the	gear boxes		-	
CO6. Design cluto	ches and brakes for the automobile components.	-			
UNIT 1	DESIGN FOR FLEXIBLE EL	LEMENTS			9
Selection of V be	lts and pulleys - selection of flat belts and pull	eys - wire	ropes	and pulleys - s	selection of
transmission chair	s and sprockets – Design of pulleys and sprocke	ets			
UNIT 1I	SPUR & HELICAL GEARS				9
	y – spur gears – speed ratio and number of teet		nalvs	s – factor of sa	fety – gear
	rating calculations based on strength and wea				
	al and transverse plane – equivalent number of				1
UNIT 1II	BEVEL & WORM GEARS			•	9
	r – tooth terminology, tooth forces and stresses,		numb	er of teeth – est	-
	of straight bevel gears – worm gear – merits an				
UNIT 1V	DESIGN OF GEAR BOXES				9
Geometric progre	ssion – standard step ratio – ray diagram, kiner	matics layo	ut – d	esign of sliding	mesh gear
	esh gear box – design of multi speed gear box	5		8	U
UNIT V	DESIGN OF CAM CLUTCHES AN	D BRAKI	ES		9
Cam Design – typ	es – pressure angle and under cutting base circle	e determina	tion –	forces and surfa	ace stresses
	clutches – axial clutches – cone clutches – inte				
external shoe brak			U		
	es				
				Total Perio	ls: 45
Text Books:				Total Perio	ls: 45
Text Books:	S., Gupta J.K., "A Textbook of Machine Desi	gn", Euras	ia Put		I
Text Books: 1. Khurmi R				lications, (2014	4)
Text Books: 1. Khurmi R	S., Gupta J.K., "A Textbook of Machine Desi			lications, (2014	4)
Text Books: 1. Khurmi R 2. Sundarara References:	S., Gupta J.K., "A Textbook of Machine Desi	e Design",	Anura	lications, (2014 Idha Publication	4) ns, (2013)
Text Books:1.Khurmi R2.SundararaReferences:1.Shigley,	S., Gupta J.K., "A Textbook of Machine Desi ijamoorthy T.V. and Shanmugam N., "Machine	e Design",	Anura	lications, (2014 Idha Publication	4) ns, (2013)
Text Books: 1. Khurmi R 2. Sundarara References: I. 1. Shigley, McGraw-	S., Gupta J.K., "A Textbook of Machine Desi jamoorthy T.V. and Shanmugam N., "Machine J.E. and Mischke, C.R., Mechanical Engi	e Design", neering D	Anura esign,	lications, (2014 Idha Publication Fifth Edition	4) ns, (2013)
Text Books:1.Khurmi R2.SundararaReferences:1.Shigley, McGraw-2.Juvinal, R	S., Gupta J.K., "A Textbook of Machine Desi jamoorthy T.V. and Shanmugam N., "Machine J.E. and Mischke, C.R., Mechanical Engi Hill International; 1989.	e Design", neering D sign, John	<u>Anura</u> esign, Wiley	lications, (2014 Idha Publication Fifth Edition , 1994.	4) ns, (2013)
Text Books:1.Khurmi R2.SundararaReferences:1.Shigley, McGraw-2.Juvinal, R3.R. L. Nor	S., Gupta J.K., "A Textbook of Machine Desi jamoorthy T.V. and Shanmugam N., "Machine J.E. and Mischke, C.R., Mechanical Engi Hill International; 1989. C., Fundamentals of Machine Component Des	e Design", neering D sign, John bach, Prenti	Anura Pesign, Wiley	lications, (2014 Idha Publication Fifth Edition , 1994. Il, 1998	4) ns, (2013)

Course Outcomes					Prog	am O	utcor	nes (P	Os)					ogram utcome	-	
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3	2	3	2						2		2	2	3		2
CO2	3	3	3	2						2		2	2	3		3
CO3	3	3	3	2						2		2	3	3		3
CO4	3	3	3	2						2		2	3	1		3
CO5	3	3	3	2						2		2	3	3		3
CO6	3	2	3	2						2		2	3	3		3

191ME63	AUTOMOBILE ENGINEE	RING			L-T-P	С
					3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:	VI		Category:	PC
Prerequisites:						
1 A :	To understand the construction and working	principle o	f vario	ous	parts of an a	utomobil
Aim:	and practice assembling and dismantling of e	ngine parts	and tra	ansı	nission syste	m
Course Outcome	s:					
The students will	be able to					
	hicle construction, chassis, frame, body and en	gine compo	nents			
	various types of fuels used in automobiles	0 1				
•	method of controlling pollution					
-	e transmission systems, wheels and tyre					
	e the concepts of steering, braking and suspens	ion systems				
	ctronically controlled gasoline, diesel injection			r el	ectrical circu	its used i
automobiles		2				
UNIT 1	VEHICLE STRUCTURE AND	ENGINE C	OMP	ON	IENTS	9
Types of automob	piles, Vehicle construction and different layout					stances t
V 1	omponents of Engine – their forms, functions a	· · · ·			•	
	&Solex carburetor, Super chargers & Turbo ch		, ,		,	
UNIT 1I	ENERGY SOURC	<u> </u>				9
	s of fuel, Rating of fuels, Properties – conven		Alter	nati	full C	ompresse
in portante quantita					ve meis – Ca	
Natural Gas. Liqu	efied Petroleum Gas, Alcohols, Bio-diesel and I	Hydrogen, F				·
· .	efied Petroleum Gas, Alcohols, Bio-diesel and I verter system Electric and Hybrid Vehicles Fi	• •				
way catalytic con	verter system, Electric and Hybrid Vehicles, Fu	uel Cell	Engine	em		ol by thre
way catalytic con UNIT 111	verter system, Electric and Hybrid Vehicles, Fu TRANSMISSION SYSTEM, WHEE	uel Cell	Ingine	em	ission contro	ol by three 9
way catalytic con UNIT 111 Clutch – types and	verter system, Electric and Hybrid Vehicles, Fu TRANSMISSION SYSTEM, WHEE d construction, Need for a gearbox, Types of ge	uel Cell ILS AND T ear boxes –	Engine YRES manua	em b al a	nd automatic	bl by thre
way catalytic con UNIT 111 Clutch – types and gear box), Over dr	verter system, Electric and Hybrid Vehicles, Fu TRANSMISSION SYSTEM, WHEE d construction, Need for a gearbox, Types of ge- rive, Transfer box, Fluid flywheel – Torque com-	uel Cell LS AND T ear boxes – verter, Propo	Engine YRES manua eller sł	em S al a naft	nd automatic	ol by thre 9 (epicycli pints, Fina
way catalytic con UNIT 1II Clutch – types and gear box), Over dr drive and Differen	verter system, Electric and Hybrid Vehicles, Fu TRANSMISSION SYSTEM, WHEE d construction, Need for a gearbox, Types of ge- rive, Transfer box, Fluid flywheel – Torque com- tial, Rear axle drive – Hotchkiss Drive and Toro	uel Cell LS AND T ear boxes – verter, Propo que Tube Dr	Engine YRES manua eller sl ive – '	em S al a naft	nd automatic	ol by thre 9 (epicycli pints, Fina
way catalytic con UNIT 111 Clutch – types and gear box), Over dr drive and Differen wheel & Cast whe	verter system, Electric and Hybrid Vehicles, Fu TRANSMISSION SYSTEM, WHEE d construction, Need for a gearbox, Types of ge- rive, Transfer box, Fluid flywheel – Torque com- tial, Rear axle drive – Hotchkiss Drive and Toro- tial, Tyres – Designations – Types – Tubed tyres	uel Cell LS AND T ear boxes – verter, Prop que Tube Dr & Tubeless	Engine YRES manua eller sl rive – V tyres	em al an naft Whe	nd automatic , Universal jo eels – Disc w	ol by thre 9 (epicycli vints, Fina heel, Wir
way catalytic con UNIT 111 Clutch – types and gear box), Over dr drive and Differen wheel & Cast whe UNIT 1V	verter system, Electric and Hybrid Vehicles, Fu TRANSMISSION SYSTEM, WHEE d construction, Need for a gearbox, Types of ge rive, Transfer box, Fluid flywheel – Torque com- tial, Rear axle drive – Hotchkiss Drive and Tord reel, Tyres – Designations – Types – Tubed tyres FRONT AXLE, STEERING, BRAKES	uel Cell LS AND T ear boxes – verter, Prop que Tube Dr & Tubeless AND SUSI	Engine YRES manua eller sl 'ive – ' tyres PENS	em al a: naft Wh	iission contro nd automatic , Universal jo eels – Disc w	ol by thre 9 (epicycli pints, Fina heel, Wir 9
way catalytic con UNIT 111 Clutch – types and gear box), Over dr drive and Differen wheel & Cast whe UNIT 1V Front Axle – Type	verter system, Electric and Hybrid Vehicles, Fu TRANSMISSION SYSTEM, WHEE d construction, Need for a gearbox, Types of ge- rive, Transfer box, Fluid flywheel – Torque com- tial, Rear axle drive – Hotchkiss Drive and Toro- tel, Tyres – Designations – Types – Tubed tyres FRONT AXLE, STEERING, BRAKES es of Front Axle, Steering geometry, Steering	uel Cell LS AND T ear boxes – verter, Propo que Tube Dr & Tubeless AND SUSI mechanism	Imagine YRES manual eller sh rive – V tyres PENSI – Ack	em al a naft Wh ION	iission contro nd automatic , Universal jo eels – Disc wi N SYSTEMS nann, Types o	ol by thre 9 (epicycli bints, Fina heel, Wir 9 0 9
way catalytic con UNIT 111 Clutch – types and gear box), Over dr drive and Differen wheel & Cast whe UNIT 1V Front Axle – Type	verter system, Electric and Hybrid Vehicles, Fu TRANSMISSION SYSTEM, WHEE d construction, Need for a gearbox, Types of ge rive, Transfer box, Fluid flywheel – Torque com- tial, Rear axle drive – Hotchkiss Drive and Tord reel, Tyres – Designations – Types – Tubed tyres FRONT AXLE, STEERING, BRAKES	uel Cell LS AND T ear boxes – verter, Propo que Tube Dr & Tubeless AND SUSI mechanism	Imagine YRES manual eller sh rive – V tyres PENSI – Ack	em al a naft Wh ION	iission contro nd automatic , Universal jo eels – Disc wi N SYSTEMS nann, Types o	ol by thre 9 (epicycli bints, Fina heel, Wir 9 0 9
way catalytic con UNIT 111 Clutch – types and gear box), Over dr drive and Differen wheel & Cast whe UNIT 1V Front Axle – Typ- gear box & Steerin System, Regenera	verter system, Electric and Hybrid Vehicles, Fu TRANSMISSION SYSTEM, WHEE d construction, Need for a gearbox, Types of generic, Transfer box, Fluid flywheel – Torque con- tial, Rear axle drive – Hotchkiss Drive and Torder tel, Tyres – Designations – Types – Tubed tyres FRONT AXLE, STEERING, BRAKES es of Front Axle, Steering geometry, Steering in ng ratio, Power Steering, Braking Systems – Di- tive brake system, Suspension Systems – Type	uel Cell LS AND T ear boxes – verter, Prope que Tube Dr & Tubeless AND SUSI mechanism rum brakes	Engine YRES manua eller sh ive – ' tyres PENSI – Ack & Dise	em al a naft Who ION ern c br	nd automatic , Universal jo eels – Disc w N SYSTEMS nann, Types o akes, Antiloc	ol by thre 9 (epicycli bints, Fina heel, Wir 9 of steerin k Brakin
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Course Outcomes				I	Progr	am O	utcor	nes (I	POs)				Pr Ou	ogram itcome	Specif s (PSC	fic (s)
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
C01	2		2	2		3							3			
CO2			3			2										2
CO3						2							2			
CO4									2		1					1
CO5	2		3										3			
CO6			2						2			2	3			

191ME64	HEAT AND MASS TRANSF	ER			L-T-l)	С
					3-0-2		4
Programme:	B.E. Mechanical Engineering	Sem:	VI	C	ategory:	PC	-
Prerequisites:			. –	-	8,-		
	To understand the basic concepts of Heat and Ma	ag Tron	afor a	nd i	ta applicatio		
Aim:		ass fram	ster a	na i	is application	011	
Course Outcome							
The students will				0			
	modes of heat transfer and solve the conduction ar						
	the basic concept of convection, flow over plate,	cylinder	s and	sphe	eres		
	the concept of pool boiling		1				
	types of heat exchanger and solve the heat exchan	ger prob	lems				
	about radiation and solve the radiation problems		c				
	ass transfer problem and know about the diffusion	mass tra	nster				10
UNIT 1	CONDUCTION		1.D	1.		т	12
	Mechanism of Heat Transfer – Conduction, Con-						
	eral Differential equation of Heat Conduction – Car		•				
	ly State Heat Conduction – Conduction through Plan						
	ems – Conduction with Internal Heat Generation	-Exter	nded S	Surfa	ices – Unst	eady I	leat
	nped Analysis – Use of Heislers Chart	.1 1	T 1			C	
	mal conductivity measurement by guarded plate	method	, Thei	mal	conductivi	ty of]	oipe
	gged pipe apparatus						1.
UNIT 1I	CONVECTION		T		<u> </u>		12
	Heat Transfer Coefficients – Boundary Layer Co	-	• •				
	nensional Analysis – External Flow – Flow over I						
	nd Turbulent Flow – Combined Laminar and Turb						
	nensional Analysis – Flow over vertical Plate, Hor	rizontal	Plate,	Inc	lined Plate,	Cyline	lers
and Spheres		_					
	al convection heat transfer from a vertical cylinder					be	
UNIT 1II	PHASE CHANGE HEAT TRANSFER A						12
	condensation - pool boiling, flow boiling, correlat						
	rs – Heat Exchanger Analysis – LMTD Method a	nd NTU	– Efi	fecti	veness – Ov	verall I	Heat
	nt – Fouling Factors						
	tiveness of Parallel/counter flow heat exchanger	, Heat t	ransfe	r fro	om pin-fin	natura	ıl &
forced convection	modes						
UNIT 1V	RADIATION						12
	aws of Radiation - Stefan Boltzman Law, Kircho						
	Shape Factor Algebra – Electrical Analogy – R	adiation	Shiel	ds –	- Introducti	on to	Gas
Radiation							
	mination of emissivity of a grey surface						
UNIT V	MASS TRANSFER						12
Basic Concepts -	Diffusion Mass Transfer - Fick's Law of Diffusion	on – Ste	ady st	ate 1	Molecular I	Diffusio	on –
Convective Mass	Transfer - Momentum, Heat and Mass Transfer	: Analog	gy – (Conv	rective Mas	s Tran	sfer
Correlations							
**Practical: Deter	mination of Stefan-Boltzmann constant						
	Lecture: 45	Pract	tice: 1	5	Total Per	iods:	60
Text Books:							
	R.C., "Fundamentals of Engineering Heat and M	Mass Tr	ansfer	". N	ew Age Int	ernatio	onal
publicatio	÷ ÷			,			
	raman C.P., "Fundamentals of Heat and Mass T	'ransfer'	. New		e Internatio	onal. N	Jew
Delhi, (20			, 1.00	2		, 1	
References:	,						
	"Heat and Mass Transfer", Central Publishing Ho	use (20	04)				
-	N., "Heat Transfer", McGraw-Hill Book Co., (200		(דט				
	"Heat Transfer", Tata McGraw-Hill, New Delhi, (· ·					
-	.P., "Heat and Mass Transfer", Tata McGraw-Hill,						
T. IIUIIIIail J.	л., таа ани мазя таняны, така месотаж-ПШ,	(2013)					

	LIST OF EQUIPMENTS	
1.	Guarded plate apparatus	1 No.
2.	Lagged pipe apparatus	1 No.
3.	Natural convection-vertical cylinder apparatus	1 No.
4.	Forced convection inside tube apparatus	1 No.
5.	Pin fin apparatus	1 No.
6.	Stefan-Boltzmann apparatus	1 No.
7.	Emissivity measurement apparatus	1 No.
8.	Parallel/counter flow heat exchanger apparatus	1 No.

Course Outcomes				ł	Progr	am O	utcor	nes (l	POs)				Prog	ram Sj (Outcomes	
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3	2	1	3		2	2					1	2	2		2
CO2	3	2	3	3		2	2					1	2	2		1
CO3	3	2	2	2		1	2					1	2	1		2
CO4	3	3	2	2		2	2					1	2	2		2
CO5	3	2	1	3		1	2					1	2	2		2
CO6	3	2	1	3		1	1					1	2	1		1

191ME67	CAD/CAM LABORATORY	ľ		L-T-P	С
				0-0-3	2
Programme:	B.E. Mechanical Engineering	Sem:	VI	Category:	PC
Prerequisites:	Computer Aided Drafting Laboratory			·	
Aim:	To communicate knowledge in Solid Modeling software	& CNC	C by u	sing relevant C.	AD/CAN
Course Outcon	ies:				
The students will	be able to				
CO1. Interpret th studies	e fundamentals of the Computer Aided Design w	which wi	ll equi	ip them to purs	ue highe
CO2. Identify the structural p	different modeling, transformation and assemblin oblems	ng tools	in con	nputer aided mo	odeling o
	y solid part modeling and assembling the parts by	using me	odeling	g software packa	ige
	he need of G & M codes in CNC part programming	U			C
U	programme for Milling and Lathe	-			
CO5. Write part p	and Dame				

Computer Aided Design (CAD)
3D PART MODELING – Protrusion, revolve protrusion, swept protrusion, lofted protrusion, helical protrusion, rib, dimensioning, Move, Pattern, Mirror, Round, Chamfer, Hole, Thread etc.
ASSEMBLY – 3D Modeling of • Knuckle joint • Universal coupling • Plummer Block • Screw Jack • Stuffing Box • Tail Stock
 Bushed Pin Type Flange coupling Crane Hook C-Clamp
Computer Aided Manufacturing (CAM)

a) MANUAL PART PROGRAMMING (Using G and M Codes) in CNC lathe

Part programming for

1. Turning,

- 2. Facing,
- 3. Drilling
- 4. Internal Thread cutting
- 5. External Thread cutting

b) MANUAL PART PROGRAMMING (using G and M codes) in CNC milling

Part programming for

- 1. Linear & Circular interpolation
- 2. Rectangular and circular
- 3. Canned cycles

NOTE: Practical examination duration is Three hours. Students will carry out one exercise in modeling and one exercise in CNC part programming & simulation.

SYSTEM REQUIREMENTS (For a batch of 30 Students)

Hardware:

- 1. Intel i3 core due processor with 4GB ram with 500GB hard disk -30 Nos.
- 2. Laser Printer 1 No.
- 3. Trainer CNC Lathe 1 No.
- 4. Trainer CNC Milling 1 No.

Software:

- 1. CAD/CAM software Solid Edge V20/CREO V2.0 50 licenses
- 2. CAM Software CNC Programming & Simulation software 30 licenses

Total Periods: 45

Course Outcomes				I	Progr	am O	utcor	nes (l	POs)				P O	rograi outcom	n Spec es (PS	ific Os)
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	2	2	2	3	3		2			3	2	2	2	3	3	2
CO2	2	2	2	3	3		2			3	2	2	2	3	3	2
CO3	2	2	2	3	3		2			3	2	2	2	3	3	2
CO4	2	2	2	3	3		2			3	2	2	2	3	3	2
CO5	2	2	2	3	3		2			3	2	2	2	3	3	2
CO6	2	2	2	3	3		2			3	2	2	2	3	3	2

191ME71	TOTAL QUALITY MANAGEMENT	L-T-P	С
		3-0-0	3
Programme:	B.E. Mechanical Engineering Sem: VII Cat	tegory:	РС
Prerequisites:	Nil		
Aim:	To understand the various principles, practices of TQM to achieve qua various statistical approaches for Quality control	ality and to	learn the
Course Outcomes	• • • • • • • • • • • • • • • • • • •		
The students will be	able to		
CO1. Know the basic			
CO2. Understand the			
	workplace with the help of 5S		
	igma and bench marking techniques		
CO5. Familiarize Qu CO6. Study the varie	ality circles and QFD		
UNIT 1	EVALUATION OF TQM		9
	for quality – Evolution of quality – Definition of quality – Dimensions of	f manufact	
	sic concepts of TQM – Definition of TQM – TQM Framework – Contri		•
1 2		ioutions of	Denning,
Juran and Crosby – E			0
UNIT 1I	TQM PRINCIPLES		9
	egic quality planning, Quality statements - Customer focus - Cus		
	on, Customer complaints, Customer retention - Employee involven		
-	n and Teamwork, Recognition and Reward, Performance appraisal – G		-
*	SA cycle, 5S, Kaizen – Supplier partnership – Partnering, Supplier	selection,	Supplier
Rating			
UNIT 1II	TQM TOOLS & TECHNIQUES I		9
	tools of quality - New management tools - Six-sigma: Concepts, method		
to manufacturing, ser	vice sector including IT – Bench marking– Reason to bench mark, Bencl	h marking	process –
FMEA – Stages, Typ	es		
	TOM TOOLS & TECHNIQUES II		
UNIT 1V	IQM IOOLS & IECHNIQUES II		9
Quality circles – Q	Quality Function Deployment – Taguchi quality loss function – – Cost of Quality – Performance measures	TPM – C	
Quality circles – Quality circ	Quality Function Deployment – Taguchi quality loss function – – Cost of Quality – Performance measures	TPM – C	
Quality circles – Q improvement needs UNIT V	Quality Function Deployment – Taguchi quality loss function – – Cost of Quality – Performance measures QUALITY SYSTEMS		Concepts,
Quality circles – Quality Circ	Quality Function Deployment – Taguchi quality loss function – – Cost of Quality – Performance measures QUALITY SYSTEMS - ISO 9000:2000 Quality System – Elements, Documentation, Quality a	uditing –	Concepts, 9 QS
Quality circles – Q improvement needs UNIT V Need for ISO 9000 – 9000 – ISO 14000 –	Quality Function Deployment – Taguchi quality loss function – – Cost of Quality – Performance measures QUALITY SYSTEMS - ISO 9000:2000 Quality System – Elements, Documentation, Quality a TS1600 – Concepts, Requirements and Benefits – Case studies of TQN	uditing –	Concepts, 9 QS
Quality circles – Quality Circ	Quality Function Deployment – Taguchi quality loss function – – Cost of Quality – Performance measures QUALITY SYSTEMS - ISO 9000:2000 Quality System – Elements, Documentation, Quality a TS1600 – Concepts, Requirements and Benefits – Case studies of TQN ervice sectors including IT	uditing – 1 implemen	9 QS ntation in
Quality circles – Q improvement needs UNIT V Need for ISO 9000 – 9000 – ISO 14000 – manufacturing and se	Quality Function Deployment – Taguchi quality loss function – – Cost of Quality – Performance measures QUALITY SYSTEMS - ISO 9000:2000 Quality System – Elements, Documentation, Quality a TS1600 – Concepts, Requirements and Benefits – Case studies of TQN ervice sectors including IT	uditing –	Concepts, 9 QS
Quality circles – Quality Constrained and Second Action of the second	Quality Function Deployment – Taguchi quality loss function – – Cost of Quality – Performance measures QUALITY SYSTEMS – ISO 9000:2000 Quality System – Elements, Documentation, Quality a TS1600 – Concepts, Requirements and Benefits – Case studies of TQM ervice sectors including IT Total I	uditing – 1 implemen Periods:	9 QS ntation in
Quality circles – Quality circles – Quality circles – Quimprovement needs – UNIT V Need for ISO 9000 – 9000 – ISO 14000 – manufacturing and set Text Books 1. Dale H. Best	Quality Function Deployment – Taguchi quality loss function – – Cost of Quality – Performance measures QUALITY SYSTEMS – ISO 9000:2000 Quality System – Elements, Documentation, Quality a TS1600 – Concepts, Requirements and Benefits – Case studies of TQN ervice sectors including IT Total I terfiled et al., "Total Quality Management", Pearson Education Asia	uditing – 1 implemen Periods:	9 QS ntation in
Quality circles – Q improvement needs – UNIT V Need for ISO 9000 – 9000 – ISO 14000 – manufacturing and se Text Books 1. Dale H. Best 2. Shridhara Bl	Quality Function Deployment – Taguchi quality loss function – – Cost of Quality – Performance measures QUALITY SYSTEMS – ISO 9000:2000 Quality System – Elements, Documentation, Quality a TS1600 – Concepts, Requirements and Benefits – Case studies of TQM ervice sectors including IT Total I	uditing – 1 implemen Periods:	9 QS ntation in
Quality circles – Q improvement needs – UNIT V Need for ISO 9000 – 9000 – ISO 14000 – manufacturing and se Text Books 1. Dale H. Best 2. Shridhara Bl References	Quality Function Deployment – Taguchi quality loss function – – Cost of Quality – Performance measures QUALITY SYSTEMS - ISO 9000:2000 Quality System – Elements, Documentation, Quality a TS1600 – Concepts, Requirements and Benefits – Case studies of TQM ervice sectors including IT Total I terfiled et al., "Total Quality Management" , Pearson Education Asia hat K., "Total Quality Management" , Himalaya Publishing House, (2)	uditing – 1 implemen Periods: 1, (2014) 2013)	9 QS ntation in 45
Quality circles – Q improvement needs – UNIT V Need for ISO 9000 – 9000 – ISO 14000 – manufacturing and se Text Books 1. Dale H. Best 2. Shridhara Bl References 1. James R. Ev	Quality Function Deployment – Taguchi quality loss function – – Cost of Quality – Performance measures QUALITY SYSTEMS – ISO 9000:2000 Quality System – Elements, Documentation, Quality a TS1600 – Concepts, Requirements and Benefits – Case studies of TQN ervice sectors including IT Total I terfiled et al., "Total Quality Management", Pearson Education Asia hat K., "Total Quality Management", Himalaya Publishing House, (2 //ans and William M. Lindsay, "The Management and Control of Q	uditing – 1 implemen Periods: 1, (2014) 2013)	9 QS ntation in 45
Quality circles – Q improvement needs – UNIT V Need for ISO 9000 – 9000 – ISO 14000 – manufacturing and se Text Books 1. Dale H. Best 2. Shridhara Bl References 1. James R. Ev South-Wester	Quality Function Deployment – Taguchi quality loss function – – Cost of Quality – Performance measures QUALITY SYSTEMS – ISO 9000:2000 Quality System – Elements, Documentation, Quality a TS1600 – Concepts, Requirements and Benefits – Case studies of TQM ervice sectors including IT Total I terfiled et al., "Total Quality Management", Pearson Education Asia hat K., "Total Quality Management", Himalaya Publishing House, (2 yans and William M. Lindsay, "The Management and Control of Q ern, (2010)	uditing – 1 implemen Periods: a, (2014) 2013) Quality", 7	9 QS ntation in 45
Quality circles – Q improvement needs – UNIT V Need for ISO 9000 – 9000 – ISO 14000 – manufacturing and se Text Books 1. Dale H. Best 2. Shridhara Bl References 1. James R. Ev South-Weste 2. Oakland J.S.	Quality Function Deployment – Taguchi quality loss function – – Cost of Quality – Performance measures QUALITY SYSTEMS – ISO 9000:2000 Quality System – Elements, Documentation, Quality a TS1600 – Concepts, Requirements and Benefits – Case studies of TQN ervice sectors including IT Total I terfiled et al., "Total Quality Management", Pearson Education Asia hat K., "Total Quality Management", Himalaya Publishing House, (2 //ans and William M. Lindsay, "The Management and Control of Q	uditing – 1 implement Periods: 1, (2014) 2013) Quality", 7 , (2003)	9 QS ntation in 45

Course Outcomes				ł	Progr	am O	utcor	nes (l	POs)				Prog		pecific PSOs)	Outcomes
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1		2							3	2	3	1		2		3
CO2								2	3			2				2
CO3								2	3			2		2		3
CO4	2			3					2		2	2		2	2	3
CO5	1			3						2	2	1		1		2
CO6								1		2	3	1				3

191ME72	GAS DYNAM	ICS AND JET PROP	PULSI	DN		L-T-P	С
						3-0-0	3
Programme:	B.E. Mechanical Engine	ering	Sem:	VII	Cate	egory:	PC
Prerequisites:						0.	
Aim:	To understand the comp	ressible flow, shock wa	ves, jet j	propuls	ion and	d Rocket	Propulsion
Course Outcome	s:			•			
The students will	be able to						
CO1. Explain the	classification of compress	sible fluid flow					
	e isentropic flow through						
2	e flow through heat transfe						
CO4. Describe th applications	e governing equation usin	g normal and oblique sh	locks to	analyze	e the M	layer rela	tion and it
* *	engines and to determine t	the propulsive efficiency	v				
	ne performance of turbo je			nes			
UNIT 1		CEPTS AND ISENTR			5		9
Energy and mome	entum equations of compre	ssible fluid flows – Stag	nation s	tates, M	lach w	aves and	Mach con
	number on compressibility						
Use of Gas tables		•	•				
UNIT 1I	FLOW	THROUGH DUCTS					9
Flows through co	nstant area ducts with hea	at transfer (Rayleigh flo	w) and	Friction	n (Fan	no flow)	– variatio
of flow properties	s – Use of tables and char	ts – Generalised gas dy	namics			,	
UNIT 1II	NORMAI	L AND OBLIQUE SH	OCK				9
	ons – Variation of flow pa		mal and	oblique	e shock	s – Pranc	itl – Meye
	table and charts – Applica						
UNIT 1V		JET PROPULSION					9
	pulsion – Thrust equation						
cycle analysis and	l use of stagnation state p	erformance of ram jet,	turbojet	, turbof	an and	l turbo pr	op engine
UNIT V		SPACE PROPULSIO	N				9
Types of rocket	engines – Propellants – f	feeding systems – Ignit	tion and	comb	ustion	- Theory	y of rocke
propulsion - Perfe	ormance study - Staging -	Terminal and characteri	istic velo	ocity – A	Applica	ations – s	pace flight
					Tote	al Period	s: 45
Text Books:					1.011		
	J.D., "Modern Compressit	ole Flow", McGraw Hill	1, (2011)				
	I., "Fundamentals of Com				al (P) I	Limited, 1	New Delhi
(2010)	•	• ′	~			,	
References:							
1. Hill P., Per company,	terson C., "Mechanics and (2012)	1 Thermodynamics of P	ropulsio	n", Ad	dison -	- Wesley	Publishin
1 2	J., "Principles of Jet Prop	ulsion and Gas Turbines	s". John	Wilev	New Y	York (20	10)
	., "Rocket Propulsion Ele			·· 110y,		, Jin, (20	
	"Cog Turkingg" Toto M			D 11	· (201	1)	

4. Ganesan V., "Gas Turbines", Tata McGraw Hill Publishing Co., New Delhi, (2011)

Course					Pro	gram O	outcome	s (POs)					Program Specific Outcome (PSOs)							
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PS O4				
C01	1	3	1			2	2					3		2						
CO2	2	2	1	3	2		1					3	1							
CO3	1	3	3	3										2						
CO4	3		1	2								3		2						
CO5	3	2	1	3	1							3			3					
CO6	1	2	2	3	1							3		2						

191ME73	FINITE ELEMENT AN	NALYSIS		L-T-P	С
				3-1-0	4
Programme:	B.E. Mechanical Engineering	Sem:	VII	Category:	РС
Prerequisites:	Fluid Mechanics and Machinery & Heat a	and Mass Trans	fer		
•	To introduce the concepts of Mathemati	cal Modeling o	f Engin	eering Problem	ns and to
Aim:	appreciate the use of FEM to a range of E	0	0	e	
Course Outcom	es:				
The students will l	be able to				
	the various approximation and elimination			ution	
	rious numerical engineering problems in 11		lement		
	the elements in CST & axisymmetric elem				
	the difference between iso, super and sub pa				
	e the numerical engineering problems in dy		& fluid	mechanics prol	olems
	the various applications involved in 1D, 2D				
UNIT 1	INTEGRAL FORMULATION & V				12
	eering analysis -weighted residual method				
	weighted residual statement- principle of s				
	e continuous trial functions- simultaneous li	inear algebraic e	quation	s– Numerical in	tegration
– Gaussian quadra					10
UNIT 1I	1D BAR & TRUSS ELE		1 1	. 1	12
	atrix algebra – general steps in FEA – co-or				
	application to bar element – quadratic ba				lement –
Ŷ	ement equations- assembly- element conr	• •	-	ons	
UNIT 1II	PLANE STRESS & PLANE ST				12
	stant strain triangular element (CST)- strain				
	gular element – iso-parametric elements– ja	acobian matrix	–natural	co-ordinate sy	stem and
	ormation – axisymmetric element				
UNIT 1V	DYNAMIC & FLUID FLC				12
	vibration - equations of motion based on				
	n of beams - consistent & lumped mass n				rs –Fluid
mechanics in 2-D-	- shape function, stiffness matrix, load vector	or, assembly – A	pplicati	on	
UNIT V	HEAT TRANSFER AN				12
Temperature distri	ibution using weighted residual approach	- application to	o one-di	mensional hear	t transfer
problems in bar e	lement – heat transfer analysis in CST element	ment – axisymi	netric e	lement – scalar	· variable
problems in 2-D					-
				Total Periods:	60
Text Books					
1. Seshu P.,	"Text Book of Finite Element Analysis"	", Prentice-Hall	of Indi	a Pvt. Ltd. Ne	w Delhi,
(2013)			-		-
2. Chennake	sava R. Alavala, "Finite Elements M		Concept	ts and Appli	cations",
2. Chennake Prentice- H	sava R. Alavala, "Finite Elements M all of India, Eastern Economy Editions, (20		Concept	ts and Applie	cations",
2. Chennake Prentice- H	all of India, Eastern Economy Editions, (20	009)			cations",
2. Chennake Prentice- H References 1. Bhavikatti	all of India, Eastern Economy Editions, (20 S.S., "Finite Element Analysis", New Ag	009) ge International	Publish	ers, (2015)	
2. Chennake Prentice- H References 1. Bhavikatti 2. Reddy J.N	all of India, Eastern Economy Editions, (20 S.S., "Finite Element Analysis", New Ag I., "An Introduction to the Finite Elemen	009) ge International t Method", Mc	Publish Graw-H	ers, (2015) (ill Edition, (20	10)
 Chennake Prentice- H References Bhavikatti Reddy J.N David V. I 	all of India, Eastern Economy Editions, (20 S.S., "Finite Element Analysis", New Ag	009) ge International It Method", Mc t Analysis", Tat	Publish Graw-H a McGr	ers, (2015) Iill Edition, (20 aw-Hill Edition	10) n, (2005)

Course Outcomes				1	Progr	am O	utcor	nes (I	POs)				Program Specific Outcomes (PSOs)					
Outcomes	PO1	PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12										PSO1	PSO2	PSO3	PSO4			
CO1	3	3	3	2	1						1	2	3	2				
CO2	3	3	3	3	3						2	2	3	2	1			
CO3	3	2	3	2	3						2	2	3	2	1			
CO4	3	2	1	1	2						1	2	3	3	1			
CO5	3	3	3	3	3						1	2	3	3	1			
CO6	3	3	3	3	3						1	2	3	3	1			

191ME74	MECHATRONICS			L-T-	P	C
				3-0-	2	4
Programme:	B.E. Mechanical Engineering	Sem:	VII	Category	:	PC
Prerequisites:						
Aim:	To understand multidisciplinary applications o	f Electro	nics in	Mechanica	sys	tems
Course Outcomes:						
The students will be	able to					
CO1. Explain the b	asics of Mechatronics systems					
CO2. Classify vario	us sensors and transducers with their properties					
•	aulic, Pneumatic, Electrical and Mechanical Syst	tems				
	ion for various types of system models and contr					
•	pasic concept and structure of PLC					
	as Mechatronics Systems design					
UNIT 1	MECHATRONICS, SENSORS AND TI	DANGD	UCED	c .	T	9
	hatronics Systems – Systems – Measurement Systems				long	-
	ion, Proximity, Velocity, Motion, Force, Fluid					
UNIT 1I	ACTUATION SYSTEMS					9
	ducers - Performance Terminology - Electric	al Actu	ation S	vstems – N	lech	
	ate Switches – Solenoids – Construction and wor					
	AC and DC drives, Stepper Motors – AC & DC	• •	-			
UNIT 111	SYSTEM MODELS AND CONTROL					9
Building blocks of N	Aechanical, Electrical, Fluid and Thermal Systems	s, Rotatio	onal – T	Transnationa	l Sy	stem
	Systems - Hydraulic - Mechanical Systems -					
Proportional Mode	Derivative Made Internal Made DID Contra	. 11	Digital	Controllers	$-V\epsilon$	1 .
	- Derivative Mode - Integral Mode - PID Control			controllers		elocit
Control – Adaptive	Control – Digital Logic Control – Micro Process	ors Cont	rol.	controllers		
Control – Adaptive UNIT 1V	Control – Digital Logic Control – Micro Process PROGRAMMING LOGIC CONTR	ors Cont OLLEF	rol. RS			9
Control – Adaptive UNIT 1V Programmable Log	Control – Digital Logic Control – Micro Process PROGRAMMING LOGIC CONTR gic Controllers – Basic PLC Structure – Ing	ors Cont OLLEF put / O	rol. RS utput	Processing	 - L	9 .adde
Control – Adaptive UNIT 1V Programmable Log Programming – Mr	Control – Digital Logic Control – Micro Process PROGRAMMING LOGIC CONTR gic Controllers – Basic PLC Structure – Ing emonics – Timers, Latching, Internal relays and	ors Cont OLLEF put / O l counte	rol. Sutput rs – Sh	Processing ift Register	 - L	9 .adde
Control – Adaptive UNIT 1V Programmable Log Programming – Mr and Jump Controls	Control – Digital Logic Control – Micro Process PROGRAMMING LOGIC CONTR gic Controllers – Basic PLC Structure – Ing emonics – Timers, Latching, Internal relays and – Data Handling – Analogs Input / Output – Sel	ors Cont OLLEF put / O d counter lection o	rol. LS utput rs – Sh f a PLO	Processing ift Register	 - L	9 Ladde Aaste
Control – Adaptive UNIT 1V Programmable Log Programming – Mr and Jump Controls UNIT V	Control – Digital Logic Control – Micro Process PROGRAMMING LOGIC CONTR gic Controllers – Basic PLC Structure – Ing emonics – Timers, Latching, Internal relays and – Data Handling – Analogs Input / Output – Sel DESIGN OF MECHATRONICS SYS	ors Cont OLLEF put / O d counter lection o TEM	rol. RS utput rs – Sh f a PL0	Processing ift Register	– L s – N	9 Ladde Aaste 9
Control – Adaptive UNIT 1V Programmable Log Programming – Mr and Jump Controls UNIT V Stages in designing	Control – Digital Logic Control – Micro Process PROGRAMMING LOGIC CONTR gic Controllers – Basic PLC Structure – Ing emonics – Timers, Latching, Internal relays and – Data Handling – Analogs Input / Output – Sel DESIGN OF MECHATRONICS SYS Mechatronics Systems – Possible Design Solution	ors Cont OLLEF put / O d counte lection o TEM s – desig	rol. tS utput rs – Sh f a PLO gning of	Processing ift Register C	- L s - N	9 Ladde Maste 9 ronic
Control – Adaptive UNIT 1V Programmable Log Programming – Mr and Jump Controls UNIT V Stages in designing systems compare	Control – Digital Logic Control – Micro Process PROGRAMMING LOGIC CONTR gic Controllers – Basic PLC Structure – Ing emonics – Timers, Latching, Internal relays and – Data Handling – Analogs Input / Output – Sel DESIGN OF MECHATRONICS SYS Mechatronics Systems – Possible Design Solution Traditional and Mechatronics – Selection of S	ors Cont OLLEF put / O l counte lection o TEM is – desig Sensors -	rol. utput rs – Sh f a PLO ning of - auton	Processing ift Register C Various Me natic washin	_ L s – N chat g ma	9 Ladde Maste 9 ronic
Control – Adaptive UNIT 1V Programmable Log Programming – Mr and Jump Controls UNIT V Stages in designing systems compare – digital camera –	Control – Digital Logic Control – Micro Process PROGRAMMING LOGIC CONTR gic Controllers – Basic PLC Structure – Ing emonics – Timers, Latching, Internal relays and – Data Handling – Analogs Input / Output – Sel DESIGN OF MECHATRONICS SYS Mechatronics Systems – Possible Design Solution Traditional and Mechatronics – Selection of S Pick and place Robot – Autonomous mobile ro	ors Cont OLLEF put / O l counte lection o TEM is – desig Sensors -	rol. utput rs – Sh f a PLO ning of - auton	Processing ift Register C Various Me natic washin	_ L s – N chat g ma	9 Ladde Maste 9 ronic
Control – Adaptive UNIT 1V Programmable Log Programming – Mr and Jump Controls UNIT V Stages in designing systems compare – digital camera –	Control – Digital Logic Control – Micro Process PROGRAMMING LOGIC CONTR gic Controllers – Basic PLC Structure – Ing emonics – Timers, Latching, Internal relays and – Data Handling – Analogs Input / Output – Sel DESIGN OF MECHATRONICS SYS Mechatronics Systems – Possible Design Solution Traditional and Mechatronics – Selection of S	ors Cont OLLEF put / O l counte lection o TEM is – desig Sensors -	rol. S utput rs – Sh f a PLC ming of – auton ireless	Processing ift Register C various Me natic washin surveillanc	_ L s – N chat g ma	9 Ladde Maste 9 ronic achin lloon
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Control – Adaptive UNIT 1V Programmable Log Programming – Mr and Jump Controls UNIT V Stages in designing systems compare – digital camera – Engine Managemen Text Books: 1. William Bo	Control – Digital Logic Control – Micro Process PROGRAMMING LOGIC CONTR gic Controllers – Basic PLC Structure – Ing emonics – Timers, Latching, Internal relays and – Data Handling – Analogs Input / Output – Sel DESIGN OF MECHATRONICS SYS Mechatronics Systems – Possible Design Solution Traditional and Mechatronics – Selection of S Pick and place Robot – Autonomous mobile ro t system – Automatic car park barrier Iton., "Mechatronics – A multidisciplinary appr	ors Cont OLLEF put / O l counte lection o TEM s – desig Sensors - bot – W	rol. S utput rs – Sh f a PLO ning of - auton Tot Pearson	Processing ift Register C Evarious Me atic washin surveillanc al Periods:	- L s - N chat g ma e bal	9 Aaste 9 ronic achin Iloon 45
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Control – Adaptive UNIT 1V Programmable Log Programming – Mr and Jump Controls UNIT V Stages in designing systems compare – digital camera – Engine Managemen Text Books: 1. William Bo 2. Rajput R.K References: 1. Smaili, A. Oxford uni	Control – Digital Logic Control – Micro Process PROGRAMMING LOGIC CONTR ric Controllers – Basic PLC Structure – Ing emonics – Timers, Latching, Internal relays and – Data Handling – Analogs Input / Output – Sel DESIGN OF MECHATRONICS SYS Mechatronics Systems – Possible Design Solution Traditional and Mechatronics – Selection of S Pick and place Robot – Autonomous mobile ro t system – Automatic car park barrier Iton., "Mechatronics – A multidisciplinary appr ., "A textbook of Mechatronics", S. Chand & Cu and Mrad, F., "Mechatronics integrated tech versity press, (2014).	ors Cont OLLEF put / O l counte lection o TEM is – desig Sensors – bot – W	rol. S utput rs – Sh f a PLO ning of – auton rireless Tot Pearson 2) s for in	Processing ift Register C Various Me natic washin surveillanc al Periods: education, ntelligent n	- L s - M chat g ma g ma g ma (201	9 adde Maste 9 ronic achin Iloon 45
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- 3. Dan Necsulesu, "Mechatronics", Pearson Education Asia, (2002).
- 4. Nitaigour Premchand Mahadik, "Mechatronics", Tata McGraw-Hill publishing Company Ltd, (2010)

LIST OF EXPERIMENTS

- 1. Design and testing of fluid power circuits to control
 - (i) velocity (ii) direction and (iii) force of single and double acting actuators
- 2. Design of circuits with logic sequence using Electro pneumatic trainer kits
- 3. Simulation of basic Hydraulic, Pneumatic and Electric circuits using software
- 4. Circuits with multiple cylinder sequences in Electro pneumatic using PLC
- 5. Speed Control of DC drives
- 6. Servo controller interfacing for DC motor
- 7. PID controller interfacing
- 8. Stepper motor interfacing with 8051 Micro controller

(i) full step resolution (ii) half step resolution

9. Modeling and analysis of basic electrical, hydraulic and pneumatic systems using LABVIEW

Total Periods: 45

LIST OF EQUIPMENTS (For a batch of 30 students)

1.	Basic Pneumatic Trainer Kit	2 Nos.
2.	Electrical controls/PLC control kit	1 No.
3.	Hydraulics and Pneumatics Systems Simulation Software – Fluidsim	10 Nos.
4.	8051 - Microcontroller kit with stepper motor and drive circuit sets	2 Nos.
5.	LAB VIEW software with Sensors to measure Pressure, Flow rate, direction, speed, velocity and force	2 Nos.

Course Outcomes]	Progr	am O	utcor	nes (F	Program Outcomes (POs)													
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4						
CO1	3		1								1	2	1									
CO2	3		1		1						2	2	1	2		1						
CO3	2		1		1						2	2	1	2		2						
CO4	2	2	1	2	1						2	2	1	2		1						
CO5	2		1		1						2	2	1	2		2						
CO6	2	2	1		2						2	2	1	3		3						

191ME79	PROJECT – I		L-T-P			
	•				0-0-4	
Programme:	B.E. Mechanical Engineering	Sem:	VII	Cat	tegory:	PRO
Prerequisites:	Knowledge gained in all semesters					
Aim:	To understand the real time applications in engin	neering f	fields thr	ough p	project we	ork
Course Outcom	es:					
The students will	be able to					
CO1. Apply the ba	asic principles of mechanical engineering courses					
CO2. Ensure the w	vorking principle of mechanisms involved in the f	àbricatio	n			
CO3. Analyze the	real time problems					
CO4. Realize the	industrial project work concepts					
~~~ ~						

CO5. Simulate and design the mechanical systems

CO6. Use the software's in mechanical applications

Course Outcomes				I		Program Specific Outcomes (PSOs)										
Outcomes	PO1	PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO										PO12	PSO1	PSO2	PSO3	PSO4
C01	3	3	3	2	2	1		2	2	1	1	3	3	2		
CO2	3	3	3	3	2		2	2	2	1	2	3	3		3	
CO3	3	3	3	3	2				2	1	2	3	2	3		
CO4	3	3	3	3		3	2		2	1	2	3	2		2	
CO5	3	3	3						2	2	2	3	2	3		2
CO6	3	3	3		3				2	2	2	3	3	2		2

191ME77	SIMULATION AND ANALYS		L-T-P	С		
					0-0-2	1
Programme:	B.E. Mechanical Engineering	Sem:	VII	Cat	egory:	PC
Prerequisites:						
Aim:	To gain knowledge in analyzing various s	tructures by usi	ing rele	vant so	oftware	
<b>Course Outcome</b>	s:					
The students will	be able to					
CO1. Demonstrat	e the features of ANSYS software					
CO2. Validate the	stress analysis in beam problems with emp	virical formulas				
CO3. Explicit the	stress analysis of a plate with a circular hol	e and axi-symn	netric co	ompor	lent	
CO4. Identify the	need of mode frequency analysis in 2D cor	nponent		•		
	Thermal analysis of a 2D component	•				
CO6. Import any	solid model to ANSYS for contact analysis					

#### List of Exercises

- 1. Static Analysis of 2-D beam problems
- 2. Static Analysis of Plane stress problems
- 3. Static Analysis of Axisymmetric problems
- 4. Structural Analysis of Trusses
- 5. Stress analysis of rectangular L bracket
- 6. Stress analysis of a plate with a circular hole
- 7. Stress analysis of a bicycle frame
- 8. Mode frequency analysis of a 2D plate
- 9. Mode frequency analysis of beams
- 10. Harmonic analysis of a 2D component
- 11. Transient Heat Transfer Analysis of 2D problems
- 12. Heat Transfer Analysis of Axisymmetric Problems
- 13. Contact Analysis of a simple solid model
- 14. Buckling Analysis of a column

**NOTE:** Practical examination duration is Three hours. Students will carry out two exercises by using ANSYS software.

SYSTEM REQUIREMENTS	
(For a batch of 30 Students)	

#### <u>Hardware:</u>

1. Intel i3 core due processor with 4GB ram with 500GB hard disk - 30 Nos.

2. Laser Printer – 1 No.

#### Software:

1. ANSYS V14.5/equivalent - 50 licenses

#### **Total Periods: 45**

Course Outcomes				1	Progr	am O	utcor	nes (l	POs)				Program Specific Outcomes (PSOs)					
Outcomes	PO1										PO12	PSO1	PSO2	PSO3	PSO4			
CO1	2	3	3						2	3		2	2			2		
CO2	2	1	1		2				2	2		3	3	3	1	2		
CO3	2	3	3		2					2		2	3	3	2	2		
CO4	2	3	3		2					2		2	3	3	2	2		
CO5	2	3	3		2				2	2		2	3	3	2	2		
CO6	2	3	3		2				2	1		3	2	3	3	3		

1: Slight (Low) 2: Moderate (Medium) 3: Substantial (High)

191ME89	PROJECT – II		L-T-P		С		
					0-0-12	2	6
<b>Programme:</b>	B.E. Mechanical Engineering	Sem:	VIII	Cat	egory:	PI	ROJ
<b>Prerequisites:</b>	Knowledge gained in all semesters						
Aim:	To understand the real time applications in engin	neering f	fields thr	ough p	roject wo	ork	
<b>Course Outcom</b>	es:						
The students will b	be able to						
CO1.	Apply the basic principles of mechanical er	ngineerir	ig course	s			
CO2.	Ensure the working principle of mechanism	ns involv	ed in the	fabric	ation		
CO3.	Analyze the real time problems						
CO4.	Realize the industrial project work concepts	5					
CO5.	Simulate and design the mechanical system	S					
CO6.	Use the software's in mechanical application	ons					

Course Outcomes	Program Outcomes (POs)												P O	Program Specific Outcomes (PSOs)				
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4		
C01	3	3	3	2	2	1		2	2	1	1	3	3	2				
CO2	3	3	3	3	2		2	2	2	1	2	3	3		3			
CO3	3	3	3	3	2				2	1	2	3	2	3				
CO4	3	3	3	3		3	2		2	1	2	3	2		2			
CO5	3	3	3						2	2	2	3	2	3		2		
CO6	3	3	3		3				2	2	2	3	3	2		2		

# **PROGRAMME ELECTIVES**

191HSEA	PROFESSIONAL ETHICS IN	ENGINEERI	NG	L-T-P	C
				3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem	: -	Category:	HSMO
Prerequisites:					
Aim:	To create an awareness on Engineering social values and loyalty and to apprecia				moral a
<b>Course Outcome</b>	s:	_			
CO2. Illustrate the CO3. Estimate ris CO4. Outline the CO5. Know how	the various concepts and theories of Ethics e role of Engineers in experimentation k factors and analyze the various ways of r rights and responsibility of engineers in ba to get patent rights ethical issues in global level	educing the ri		Management	
UNIT I	ENGINEERING ETHI	CS			9
Senses of Engine Autonomy – Kol	ering Ethics – Variety of moral issues – nlberg's theory – Gilligan's theory – C Professional Ideals and Virtues – Uses of	Types of inconsensus and	Contro		as – Mo
UNIT II	ENGINEERING AS SOCIAL EXPERI	MENTATIO	N		9
	xperimentation – Engineers as responsible l Standards – A Balanced Outlook on Law				Codes of
UNIT III	ENGINEER'S RESPONSIBILITY	FOR SAFET	Y		9
Safety and Risk –	Assessment of Safety and Risk – Risk Bene bach to Risk – Chernobyl Case Studies and	fit Analysis –		ng Risk – The C	Bovernme
UNIT IV	RESPONSIBILITIES AN	DRIGHTS			9
Collegiality and I	Loyalty – Respect for Authority – Collect ional Crime – Professional Rights – Emplo	ive Bargainin			Conflicts
UNIT V	GLOBAL ISSUES				9
Technological De	rporations – Business Ethics – Environ velopment – Weapons Development – En ert Witnesses and Advisors – Honesty – Mo	gineers as Ma	anagers	– Consulting E	Engineers
				Total Periods	s: 45
Text Books:					
2. Charles E	tin and Roland Schinzinger, "Ethics in Er . Harris, Michael S. Pritchard and Michae hompson Learning, (2016)				
References:					
2. John R. B	. Fleddermann, "Engineering Ethics", Pren oatright, "Ethics and the Conduct of Busing G. Seebauer and Robert L. Barry, "Fundar	ess", Pearson I	Educatio	on, (2017)	Engineer

- 3. Edmund G. Seebauer and Robert L. Barry, "Fundamentals of Ethics for Scientists and Engineers", Oxford University Press, (2015)
- 4. David Ermann and Michele S. Shauf, "Computers, Ethics and Society", Oxford University Press, (2016)

Course Outcomes	Program Outcomes (POs)											Program Specific Outcomes (PSOs)				
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1						1		3	1		1	2				2
CO2						2		3	2		2	2				2
CO3						2		3			2	2				2
CO4						1		3	2		2	1				2
CO5						1		3			1	2				2
CO6						1		3			2	2				2

					ation 201
191MEEA	ADDITIVE MANUFACTURI	NG		L-T-P	С
				3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:		Category:	PE
Aim:	To know the principle, methods, possibilities a	nd limita	ations a	as well as envir	onmental
	effects of Additive Manufacturing technologies.				
UNIT I	INTRODUCTION				9
	ed - Development of Additive Manufacturing				
	ation –Rapid Prototyping- Rapid Tooling – F	Rapid M	lanufa	cturing – Appl	ications-
Benefits –Case	studies.				
UNIT II	DESIGN FOR ADDITIVE MANUFAC				9
	ata processing - CAD model preparation - P				
	del slicing – Tool path generation- Design for A				
	unique capabilities - DFAM for part quality i	mprove	ment-	Customised de	sign and
	nedical applications.				
UNIT III PHO	<b>TOPOLYMERIZATION AND POWDER E</b>	BED FU	SION	PROCESSES	5 9
Photo polymeriz	ation: SLA-Photo curable materials – Process	- Advar	ntages	and Applicatio	ns.
Powder Bed Fus	sion: SLS-Process description – powder fusion	mechar	nism –	Process Param	eters
- Typical Mater	ials and Application. Electron Beam Melting.				
UNIT IV	<b>EXTRUSION BASED AND SHEET LAM</b>	IINATI	ON P	ROCESSES	9
Extrusion Base	d System: FDM-Introduction - Basic Princi	ple – N	/lateria	als – Applicat	ions and
	oextrusion. Sheet Lamination Process:LOM-G	-			
bonding.		e		U	
UNIT V PR	INTING PROCESSES AND BEAM DEPOS	SITION	PRO	CESSES	9
Droplet formation	on technologies – Continuous mode – Drop on	Deman	d mod	le – Three Dim	ensional
	ntages – Bioplotter - Beam Deposition Process:				
	ss parameters – Materials – Benefits – Applica			1	
-	^ ^ *			<b>Total Periods</b>	: 45
<b>Text Books:</b>					
1. Chua C.	K., Leong K.F., and Lim C.S., "Rapid proto	typing:	Princi	ples and appli	cations".
	ition, World Scientific Publishers, 2010.	JI C		1 11	,
	oson, David W.Rosen, Brent Stucker "Additive	e Manuf	àcturii	ng Technologie	s: Rapid
	ing to Direct Digital Manufacturing" Springer			8 8	1
		,			
References:					
	Gebhardt "Understanding Additive Manufactu	uring: R	apid P	rototyping, Ra	oid
	turing" Hanser Gardner Publication 2011.	8	1	JI 6,]	
	A.K. and Nasr E.A., "Rapid Prototyping: The	orv and	practi	ce". Springer	2006.
	V. and Liou F.W., "Rapid Prototyping and Eng				
2. LIUU L. V	- local manual () CDC Decar 2007		o "rpn		

- prototype development", CRC Press, 2007.
  4. Tom Page "Design for Additive Manufacturing" LAP Lambert Academic Publishing, 2012.

Course Outcomes		Program Outcomes (POs)											Program Specific Outcomes (PSOs)				
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	
CO1	1	3	1	2	3	2	1					1	1	2	2	3	
CO2	2	2	1	3	3	2	2					3	1	3	2	3	
CO3	2	2	1	3	3	2	1					3		2	2	2	
CO4	2	2	1	3	3	2	1					1		2	2	2	
CO5	1	2	1	3	3	2	1					1		2	2	2	
CO6	1	2	1	3	3	2	1					1		2	2	2	

<b>191MEEB</b>	COMPOSITE MATERIALS AND ENG	GINEE	RING	T	L-T-P	С
					3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:		C	ategory:	PE
Prerequisites:						
Aim:	To understand the fundamentals of composite matching	aterial ar	nd its 1	mech	nanical beha	vior
<b>Course Outcome</b>	S:					
The students will	be able to					
CO1. Understand	the concept of fiber preparation and its applicatior	is				
	different composite manufacturing methods					
	at plate laminate constitute equations					
	the lamina strength analysis					
	nisotropic analysis of composites					
	thermal properties of composites				~ ~	
UNIT I	BASICS TO FIBERS AND REINFORCEM ix materials – Polymers – Metals – Ceramics –					9
Inorganic Fibers, Advantages and D – Particulate – Re	Metal Filaments – Ceramic Fibers – Fiber Fabrica rawbacks of Composites Materials – Mechanical P inforced Composite Materials – Dispersion Stren of Mixtures – Characteristics of Fiber Reinforced C	ation – N roperties gthened	Natura s and A Comp	l Co Appl posit	mposite Wo ications of C e – Fiber –F	od, Jute – omposites
UNIT II	MANUFACTURING OF COMPO	SITES				9
Pultrusion, Resin Composites (SMC State Processing, I Process – Infiltrati	Polymer Matrix Composites (PMCs) – Handlay- Transfer Moulding (RTM) – Bag Moulding, ) – Manufacturing of Metal Matrix Composites (M Manufacturing of Ceramic Matrix Composites (CM on Technique, Direct Oxidation – Interfaces	Injectio IMCs) – MCs) – H	n Mo Solid	uldi state	ng, Sandwie , Liquid Stat	ch Mould te, Vapour n Bonding
UNIT III	LAMINA CONSTITUTIVE EQUATIO	NS				9
Laminated anisotr Symmetric Lamin	ive Equations: Lamina Assumptions – Macrosco opic plates – Laminate Constitutive Equations – Co ates, Angle Ply Laminates, Cross Ply Laminates – ties from Laminate Tests – Quasi-Isotropic Lamin STRENGTH ANALYSIS OF COMPO	bupling In Laminat ates – D	nteraci e Stru	tions ctura	s, Balanced I 11 Moduli – I	Laminates, Evaluation
	aximum Stress and Strain Criteria – Von-Misses		anitani	on f	on Instrumia	-
<ul> <li>Generalized Hill</li> <li>Prediction of lam</li> <li>Analysis – Buckli</li> </ul>	l's Criterion for Anisotropic materials – Tsai-H inate Failure Equilibrium Equations of Motion – ng Analysis – Free Vibrations – Natural Frequen	ill's Fail Energy	lure C	riter	ion for Ĉon	nposites – c Bending
UNIT V	THERMAL ANALYSIS	M 1.6				9
Equations – Ortho	onstant C.T.E's – Modification of Hooke's Law - otropic Lamina C.T.E's – C.T.E's for special La ric Balanced Laminates, Zero C.T.E laminates, T	minate (	Config	urat si-Iso	ions – Unid	irectional, inates
Text Books:						I
1. Gibson, R (1994)	.F., "Principles of Composite Material Mechanics K., "Fiber Reinforced Composites: Materials, Mat				-	
Inc, (1993	)				U /	
Inc, (1993 References:	)					
References:1.Issac M. I Press Edit2.Robert M.	Daniel and Ori Ishai, "Engineering Mechanics of G ion (2007) Jones, "Mechanics of Composite Materials", McC., "Primer on Composite Materials, Analysis", Tec	- Graw Hi	11, (19	98)	ls", Oxford	

Course Outcomes				ł	Progr	am O	utcor	nes (l	POs)				Pr Ou	ogram itcome	Specif s (PSC	fic Ds)
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
C01	2						1				1	2	1		3	
CO2	2		1				1				1	2	1			1
CO3	2	1		2			1					1	1	1		2
CO4	2	1	1	2			1					1	1	1		2
CO5	2	1	1	2								1	1	1		2
CO6	2	1	1	2								1	1	1		2

<b>191MEEC</b>	COMPUTATIONAL FLUID DYN	AMICS	5	L-T-P	С
				3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:		Category:	PE
Prerequisites:	Fluid Mechanics and Machinery			· · · · · ·	
Aim:	To impart the knowledge of numerical technique heat transfer problems	es to the	solutic	on of fluid dyna	mics and
<b>Course Outcomes:</b>					
The students will be a	able to				
CO1. Understand th	e governing equations of fluid flow				
CO2. Apply explicit	, implicit and semi-implicit methods of finite different	encing			
CO3. Possess the kn	owledge of CFD techniques	-			
CO4. Know the basi	c aspects of grid generation				
	ow problems and heat transfer				

CO6. Solve fluid flow field using some popular CFD techniques

UNIT IINTRODUCTION AND GOVERNING EQUATIONS9Introduction – Impact and applications of CFD in diverse fields – Governing equations of fluid dynamics – Continuity<br/>– Momentum and energy – Generic integral form for governing equations – Initial and Boundary conditions –<br/>Governing equations for boundary layers – Classification of partial differential equations – Hyperbolic – Parabolic –<br/>Elliptic and Mixed types – Applications and relevance9UNIT IIFINITE DIFFERENCE METHOD9

Introduction to Finite differences – Derivation of finite difference equations – Simple Methods – General Methods for first and second order accuracy – solution methods for finite difference equations – Elliptic equations – Iterative solution Methods – Parabolic equations – Explicit and Implicit – Crank-Nicolson – ADI scheme – Stability criterion – Example problems on elliptic and parabolic equations – Grid independence test – Optimum step size

UNIT III

#### **GRID GENERATION**

Grid generation – General transformation of the equations – Form of the governing equations suitable for CFD – Boundary fitted Co-ordinate systems – Elliptic grid generation – Adaptive grids – Modern developments in grid generation

#### UNIT IV FINITE VOLUME METHOD FOR CONVECTION DIFFUSION

Steady one-dimensional convection and diffusion – Central, upwind differencing schemes – properties of discretization schemes – Conservativeness, Boundedness, Trasnportiveness, Hybrid, Power-law, quick Schemes

UNIT V

#### CALCULATION OF FLOW FIELD

Representation of the pressure gradient term and continuity equation – Staggered grid – Momentum equations – Pressure and Velocity corrections – Pressure Correction equation, simple algorithm and its variants – Turbulence models, mixing length model, Two equation (k- $\varepsilon$ ) models – High and low Reynolds number models

Total Periods: 45

9

**Text Books** 

- 1. Versteeg H.K. and Malalasekera W., "An Introduction to Computational Fluid Dynamics: The finite volume Method", Pearson Publication, (2008)
- 2. Hoffman K.A., "Computational Fluid Dynamics for Engineering", Engineering Education System, Austin, Texas, (2000)

#### References

- 1. Muralidhar K., and Sundarajan T., "Computational Fluid Flow and Heat Transfer", Narosa Publishing House, New Delhi, (2011)
- 2. Anderson J.D., "Computational Fluid Dynamics The basics with applications", McGraw-Hill, (2000)
- 3. Patankar S.V., "Numerical Heat Transfer and Fluid Flow", Hemisphere Publishing Corporation, (2004)
- 4. Prodip Niyogi, Chakrabarty S.K., Laha M.K., "Introduction to Computational Fluid Dynamics", Pearson Education, (2005)

Course Outcomes	Program Outcomes (POs)											Progr	Program Specific Outcomes (PSOs)				
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	
CO1	2		3	2								2	2	3			
CO2	2	2		2	3							2	3				
CO3	3		2	2								1	2		3		
CO4	2	3		3	2							2	2		3		
CO5	2		3		3							2	2	3			
CO6	2	2	3		3							2	2		3		

Programme:         B.E. Mechanical Engineering         Sem:         -         Category:         PE           Aim:         To gain the knowledge about the Advanced and computerized Manufacturing Techniques followed in the Shop floor of the Industries         -         Category:         PE           Aim:         To gain the knowledge about the Advanced and computerized Manufacturing Techniques followed in the Shop floor of the Industries         -         Category:         PE           Course Outcomes:         The students will be able to         -         COI.         Understand the concept of CIM           CO2.         Explain the components of CIM         -         CO4.         List out the various techniques in shop floor control           CO6.         Familiarize the computer aided planning and control         -         9           Brief introduction to CAD and CAM – Manufacturing Planning, Manufacturing control – Introduction to CAD/CAM – Concurrent Engineering – CIM concepts – Computerized elements of CIM system – Types of production – Typical CAD command structure, wire frame modeling, surface modeling and solid modeling (concepts only) in relation to popular CAD packages         9           CIM as a concept and a technology, CASA/SME model of CIM, CIM II, benefits of CIM, communication matrix in CIM, fundamentals of computer communication in CIM – point to point (PTP), star and multiplexing. Computer networking in CIM – te seven layer OSI model, LAN model, MAP model, network topologies – star, ring and bus, advantages of networks in CIM         9		COMPUTER INTEGRATED MA	NUFACTUR	ING	L-T-P	С
Prerequisites:         To gain the knowledge about the Advanced and computerized Manufacturing Techniques followed in the Shop floor of the Industries           Course Outcomes:         The students will be able to           COL.         Understand the concept of CIM           CO2.         Explain the concept of CIM           CO3.         Recognize the Group Technology and CAPP           CO4.         List out the various techniques in shop floor control           CO5.         Know the concept of FMS           CO6.         Familiarize the computer aided planning and control           BASICS OF CIM         9           Brief introduction to CAD and CAM – Manufacturing Planning, Manufacturing control – Introduction to CAD/CAM – Concurrent Engineering – CIM concepts – Computerized elements of CIM, system – Types of production – Typical CAD command structure, wire frame modeling, surface modeling and solid modeling (concepts only) in relation to popular CAD packages           COMPONENTS OF CIM         9           CIM as a concept and a technology, CASA/SME model of CIM, CIM II, benefits of CIM, communication matrix in CIM, fundamentals of computer communication in CIM – CIM data transmission methods – serial, parallel, asynchronous, synchronous, modulation, demodulation, simplex and duplex – Types of networks in CIM         9           ROUP TECHNOLOGY AND COMPUTER AIDED PROCESS PLANNING         9           History Of Group Technology – role of G.T. in CAD/CAM Integration – part families – classification and oeding – DCLASS and MICLASS and OPTI2 coding syste					3-0-0	3
Aim:         To gain the knowledge about the Advanced and computerized Manufacturing Techniques followed in the Shop floor of the Industries           Course Outcomes:         The students will be able to           CO1.         Understand the concept of CIM           CO2.         Explain the components of CIM           CO3.         Recognize the Group Technology and CAPP           CO4.         List out the various techniques in shop floor control           CO5.         Know the concept of FMS           CO6.         Familiarize the computer aided planning and control           BASICS OF CIM         9           Brief introduction to CAD and CAM – Manufacturing Planning, Manufacturing control – Introduction to CAD/CAM – Concurrent Engineering – CIM concepts – Computerized elements of CIM system – Types of production – Typical CAD command structure, wire frame modeling, surface modeling and solid modeling (concepts only) in relation to popular CAD packages           COMPONENTS OF CIM         9           CIM as a concept and a technology, CASA/SME model of CIM, CIM II, benefits of CIM, communication matrix in CIM, fundamentals of computer communication in CIM – CIM data transmission methods – serial, parallel, asynchronous, synchronous, synchronous, synchronous, sinplex and duplex – Types of communication in CIM – point to point (PTP), star and multiplexing. Computer networking in CIM – the seven layer OSI model, LAN model, MAP model, network topologies – star, ring and bus, advantages of networks in CIM         9           Briotry Of Group Technology – role of G.T. in CAD/CAM Integration –	Programme:	B.E. Mechanical Engineering	Sem:		Category:	PE
Alm:       [followed in the Shop floor of the Industries         Course Outcomes:         The students will be able to         CO1.       Understand the concept of CIM         CO2.       Explain the components of CIM         CO3.       Recognize the Group Technology and CAPP         CO4.       List out the various techniques in shop floor control         CO5.       Know the concept of FMS         CO6.       Familiarize the computer aided planning and control         BASICS OF CIM       9         Brief introduction to CAD and CAM – Manufacturing Planning, Manufacturing control – Introduction to CAD/CAM – Concurrent Engineering – CIM concepts – Computerized elements of CIM system – Types of production – Typical CAD command structure, wire frame modeling, surface modeling and solid modeling (concepts only) in relation to popular CAD packages         COMPONENTS OF CIM       9         CIM as a concept and a technology, CASA/SME model of CIM, CIM II, benefits of CIM, communication matrix in CIM , fundamentals of computer communication in CIM – CIM data transmission methods – serial, parallel, asynchronous, synchronous, modulation, demodulation, simplex and dubz – Types of communication in CIM – point to point (PTP), star and multiplexing. Computer networking in CIM – the seven layer OSI model, LAN model, MAP model, network topologies – star, ring and bus, advantages of networks in CIM       9         GROUP TECHNOLOGY AND COMPUTER AIDED PROCESS PLANING       9         History Of Group Technology – role of G.T. in CAD/CAM Integration	Prerequisites:					
Converse         Display           Course Outcomes:         Course Outcomests of CIM           CO2. Explain the components of CIM         CO3. Explain the components of CIM           CO3. Exolognize the Group Technology and CAPP         CO4. List out the various techniques in shop floor control           CO5. Know the concept of FMS         9           Barief introduction to CAD and CAM – Manufacturing Planning, Manufacturing control – Introduction to CAD/CAM – Concurrent Engineering – CIM concepts – Computerized elements of CIM system – Types of production – Typical CAD command structure, wire frame modeling, surface modeling adsolid modeling (concepts only) in relation to popular CAD packages         9           COMPONENTS OF CIM         9           CIM as a concept and a technology, CASA/SME model of CIM, CIM II, benefits of CIM, communication matrix in CIM, fundamentals of computer communication in CIM – point to point (PTP), star and multiplexing. Computer networking in CIM – the seven layer OSI model, LAN model, MAP model, network topologies – star, ring and bus, advantages of networks in CIM         9           History Of Group Technology – role of G.T. in CAD/CAM Integration – part families – classification and coding – DCLASS and OPTLZ coding systems – facility design using G.T benefits of G.T approaches to computer aided process planning – variant approach and generative approaches         9           Shop floor control – phases – factory data collection system – automatic identification methods – Bar code technology – automated data collection system – automatic identification methods – Bar code technology – automated data collection system – automatic identifica	•	To gain the knowledge about the Advanced	d and computer	ized Ma	nufacturing Te	echniques
The students will be able to         CO1.       Understand the concept of CIM         CO2.       Explain the components of CIM         CO3.       Recognize the Group Technology and CAPP         CO4.       List out the various techniques in shop floor control         CO5.       Know the concept of FMS         CO6.       Familiarize the computer aided planning and control         BASICS OF CIM       9         Brief introduction to CAD and CAM – Manufacturing Planning, Manufacturing control – Introduction to CAD/CAM – Concurrent Engineering – CIM concepts – Computerized elements of CIM system – Types of production – Typical CAD command structure, wire frame modeling, surface modeling and solid modeling (concepts only in relation to popular CAD packages         COMPONENTS OF CIM       9         CIM as a concept and a technology, CASA/SME model of CIM, CIM II, benefits of CIM, communication matrix in CIM, fundamentals of computer communication in CIM – CIM data transmission methods – serial, parallel, asynchronous, synchronous, modulation, demodulation, simplex and duplex – Types of communication in CIM – point to point (PTP), star and multiplexing. Computer networking in CIM – the seven layer OSI model, LAN model, MAP model, network topologies – star, ring and bus, advantages of networks in CIM         GROUP TECHNOLOGY AND COMPUTER AIDED PROCESS PLANNING       9         History Of Group Technology – role of G.T. in CAD/CAM Integration – part families – classification and coding – DCLASS and OPTLASS and OPTLASS and OPTLASS       9         Shop floor control – phases	AIIII;	followed in the Shop floor of the Industries	S			
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(concepts only) in relation to popular CAD packages       9         COMPONENTS OF CIM       9         CIM as a concept and a technology, CASA/SME model of CIM, CIM II, benefits of CIM, communication matrix in CIM, fundamentals of computer communication in CIM – CIM data transmission methods – serial, parallel, asynchronous, synchronous, modulation, demodulation, simplex and duplex – Types of communication in CIM – point to point (PTP), star and multiplexing. Computer networking in CIM – the seven layer OSI model, LAN model, MAP model, network topologies – star, ring and bus, advantages of networks in CIM       9         GROUP TECHNOLOGY AND COMPUTER AIDED PROCESS PLANNING       9         History Of Group Technology – role of G.T. in CAD/CAM Integration – part families – classification and coding – DCLASS and MICLASS and OPTIZ coding systems – facility design using G.T. – benefits of G.T. – cellular manufacturing – Process planning – role of process planning in CAD/CAM Integration – approaches to computer aided process planning – role of process planning in CAD/CAM Integration – approaches       9         Shop FloOR CONTROL AND FMS       9         Shop floor control – phases – factory data collection system – automatic identification methods – Bar code technology – automated data collection system – FMS – components of FMS – types – FMS workstation – material handling and storage system – FMS layout – computer control systems – applications and benefits         COMPUTER AIDED PLANNING, CONTROL AND MONITORING       9         Production planning and control – cost planning and control – inventory management – material requirements planning (MRP) – Lean and Agile Manufacturing – Types of production monitoring systems –						
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Text Books:         1. Mikell P. Groover, "Automation, Production Systems and Computer Integrated Manufacturing", Pearson Education (2013)         2. Mikell P. Groover, Emory Zimmers Jr., "CAD/CAM", Prentice Hall of India Pvt. Ltd., (2006)         References:         1. James A. Regh and Henry W.Kreabber, "Computer Integrated Manufacturing", Pearson Education, (2005)         2. Chris McMahon and Jimmie Browne, "CAD CAM Principles, Practice and Manufacturing Management", Pearson Education, (2005)         3. Ranky Paul G., "Computer Integrated Manufacturing", Prentice Hall of India Pvt. Ltd., (2005)	Shop floor contro technology – auto material handling <b>COMPUTER AI</b> Production planni planning (MRP) –	mated data collection system – FMS – comp and storage system – FMS layout – comput DED PLANNING, CONTROL AND MO ng and control – cost planning and control – Lean and Agile Manufacturing – Types of p	ponents of FMS er control system <b>NITORING</b> inventory mana roduction monit	S – type ms – ap	es – FMS worl plications and – material req	Bar code kstation – benefits 9 uirements
<ol> <li>Mikell P. Groover, "Automation, Production Systems and Computer Integrated Manufacturing", Pearson Education (2013)</li> <li>Mikell P. Groover, Emory Zimmers Jr., "CAD/CAM", Prentice Hall of India Pvt. Ltd., (2006)</li> <li>References:         <ol> <li>James A. Regh and Henry W.Kreabber, "Computer Integrated Manufacturing", Pearson Education, (2005)</li> <li>Chris McMahon and Jimmie Browne, "CAD CAM Principles, Practice and Manufacturing Management", Pearson Education, (2005)</li> <li>Ranky Paul G., "Computer Integrated Manufacturing", Prentice Hall of India Pvt. Ltd., (2005)</li> </ol> </li> </ol>	Shop floor contro technology – auto material handling <b>COMPUTER AI</b> Production planni planning (MRP) –	mated data collection system – FMS – comp and storage system – FMS layout – comput DED PLANNING, CONTROL AND MO ng and control – cost planning and control – Lean and Agile Manufacturing – Types of p	ponents of FMS er control system <b>NITORING</b> inventory mana roduction monit	S – type ms – ap	es – FMS worl plications and – material req ystems – struct	Bar code kstation – benefits 9 uirements ure model
<ul> <li>Pearson Education (2013)</li> <li>2. Mikell P. Groover, Emory Zimmers Jr., "CAD/CAM", Prentice Hall of India Pvt. Ltd., (2006)</li> <li>References: <ol> <li>James A. Regh and Henry W.Kreabber, "Computer Integrated Manufacturing", Pearson Education, (2005)</li> <li>Chris McMahon and Jimmie Browne, "CAD CAM Principles, Practice and Manufacturing Management", Pearson Education, (2005)</li> <li>Ranky Paul G., "Computer Integrated Manufacturing", Prentice Hall of India Pvt. Ltd., (2005)</li> </ol> </li> </ul>	Shop floor contro technology – auto material handling <b>COMPUTER AI</b> Production plannin planning (MRP) – of manufacturing	mated data collection system – FMS – comp and storage system – FMS layout – comput DED PLANNING, CONTROL AND MO ng and control – cost planning and control – Lean and Agile Manufacturing – Types of p	ponents of FMS er control system <b>NITORING</b> inventory mana roduction monit	S – type ms – ap	es – FMS worl plications and – material req ystems – struct	Bar code kstation – benefits 9 uirements ure model
<ol> <li>Mikell P. Groover, Emory Zimmers Jr., "CAD/CAM", Prentice Hall of India Pvt. Ltd., (2006)</li> <li>References:         <ol> <li>James A. Regh and Henry W.Kreabber, "Computer Integrated Manufacturing", Pearson Education, (2005)</li> <li>Chris McMahon and Jimmie Browne, "CAD CAM Principles, Practice and Manufacturing Management", Pearson Education, (2005)</li> <li>Ranky Paul G., "Computer Integrated Manufacturing", Prentice Hall of India Pvt. Ltd., (2005)</li> </ol> </li> </ol>	Shop floor contro technology – auto material handling <b>COMPUTER AI</b> Production planni planning (MRP) – of manufacturing <b>Text Books:</b>	mated data collection system – FMS – comp and storage system – FMS layout – compute <b>DED PLANNING, CONTROL AND MO</b> ng and control – cost planning and control – Lean and Agile Manufacturing – Types of p – process control and strategies – Direct Digit	ponents of FMS er control syste <b>NITORING</b> inventory mana roduction monit ital Control	S – type ms – ap gement coring sy	es – FMS worl plications and – material req ystems – struct <b>Total Period</b> s	Bar code kstation – benefits 9 uirements ure model s: 45
<ol> <li>James A. Regh and Henry W.Kreabber, "Computer Integrated Manufacturing", Pearson Education, (2005)</li> <li>Chris McMahon and Jimmie Browne, "CAD CAM Principles, Practice and Manufacturing Management", Pearson Education, (2005)</li> <li>Ranky Paul G., "Computer Integrated Manufacturing", Prentice Hall of India Pvt. Ltd., (2005)</li> </ol>	Shop floor contro technology – auto material handling <b>COMPUTER AI</b> Production plannin planning (MRP) – of manufacturing <b>Text Books:</b> 1. Mikell P.	mated data collection system – FMS – comp and storage system – FMS layout – compute <b>DED PLANNING, CONTROL AND MO</b> ng and control – cost planning and control – Lean and Agile Manufacturing – Types of pr – process control and strategies – Direct Digite Groover, "Automation, Production System	ponents of FMS er control syste <b>NITORING</b> inventory mana roduction monit ital Control	S – type ms – ap gement coring sy	es – FMS worl plications and – material req ystems – struct <b>Total Period</b> s	Bar code kstation – benefits 9 uirements ure model s: 45
<ol> <li>James A. Regh and Henry W.Kreabber, "Computer Integrated Manufacturing", Pearson Education, (2005)</li> <li>Chris McMahon and Jimmie Browne, "CAD CAM Principles, Practice and Manufacturing Management", Pearson Education, (2005)</li> <li>Ranky Paul G., "Computer Integrated Manufacturing", Prentice Hall of India Pvt. Ltd., (2005)</li> </ol>	Shop floor contro technology – auto material handling COMPUTER AI Production plannin planning (MRP) – of manufacturing Text Books: 1. Mikell P. Pearson E	mated data collection system – FMS – comp and storage system – FMS layout – comput DED PLANNING, CONTROL AND MOI ng and control – cost planning and control – Lean and Agile Manufacturing – Types of pr – process control and strategies – Direct Digi Groover, "Automation, Production System Education (2013)	ponents of FMS er control system <b>NITORING</b> inventory mana roduction monit ital Control	S – type ms – ap gement foring system	es – FMS worl plications and – material req /stems – struct Total Periods grated Manufa	Bar code kstation – benefits 9 uirements ure model s: 45 acturing",
<ol> <li>Chris McMahon and Jimmie Browne, "CAD CAM Principles, Practice and Manufacturing Management", Pearson Education, (2005)</li> <li>Ranky Paul G., "Computer Integrated Manufacturing", Prentice Hall of India Pvt. Ltd., (2005)</li> </ol>	Shop floor contro technology – auto material handling <b>COMPUTER AI</b> Production plannin planning (MRP) – of manufacturing <b>Text Books:</b> 1. Mikell P. Pearson E 2. Mikell P.	mated data collection system – FMS – comp and storage system – FMS layout – comput DED PLANNING, CONTROL AND MOI ng and control – cost planning and control – Lean and Agile Manufacturing – Types of pr – process control and strategies – Direct Digi Groover, "Automation, Production System Education (2013)	ponents of FMS er control system <b>NITORING</b> inventory mana roduction monit ital Control	S – type ms – ap gement foring system	es – FMS worl plications and – material req /stems – struct Total Periods grated Manufa	Bar code kstation – benefits 9 uirements ure model s: 45 acturing",
<ul><li>Pearson Education, (2005)</li><li>Ranky Paul G., "Computer Integrated Manufacturing", Prentice Hall of India Pvt. Ltd., (2005)</li></ul>	Shop floor contro technology – auto material handling COMPUTER AI Production plannin planning (MRP) – of manufacturing – Text Books: 1. Mikell P. Pearson E 2. Mikell P. References:	mated data collection system – FMS – comp and storage system – FMS layout – comput DED PLANNING, CONTROL AND MO ng and control – cost planning and control – Lean and Agile Manufacturing – Types of pr – process control and strategies – Direct Digi Groover, "Automation, Production System Education (2013) Groover, Emory Zimmers Jr., "CAD/CAM	ponents of FMS er control syste <b>NITORING</b> inventory mana roduction monit ital Control ns and Comput	S – type ms – ap gement coring sy ter Inte l of Ind	es – FMS worl plications and – material req ystems – struct Total Periods grated Manufa ia Pvt. Ltd., (2	Bar code kstation – benefits 9 uirements ure model s: 45 acturing", 2006)
	Shop floor contro technology – auto material handling COMPUTER AI Production planning planning (MRP) – of manufacturing – of manufacturing – 1. Mikell P. Pearson E 2. Mikell P. References: 1. James A.	mated data collection system – FMS – comp and storage system – FMS layout – comput DED PLANNING, CONTROL AND MOI ng and control – cost planning and control – Lean and Agile Manufacturing – Types of pr – process control and strategies – Direct Digi Groover, "Automation, Production System Education (2013) Groover, Emory Zimmers Jr., "CAD/CAM Regh and Henry W.Kreabber, "Computer Integ	ponents of FMS er control syste <u>NITORING</u> inventory mana roduction monit ital Control ns and Comput ", Prentice Hal rated Manufactu	S – type ms – ap gement coring sy ter Inte l of Ind	es – FMS worl plications and – material req vstems – struct Total Periods grated Manufa ia Pvt. Ltd., (2 earson Educatio	Bar code kstation – benefits 9 uirements ure model s: 45 acturing", 006) m, (2005)
4 Vorem Koren "Computer Integrated Manufacturing" McGrow Hill (2005)	Shop floor contro technology – auto material handling COMPUTER AI Production plannin planning (MRP) – of manufacturing – of manufacturing – dimension floor Text Books: 1. Mikell P. Pearson F 2. Mikell P. Beferences: 1. James A. I 2. Chris McM	mated data collection system – FMS – comp and storage system – FMS layout – comput DED PLANNING, CONTROL AND MOI ng and control – cost planning and control – Lean and Agile Manufacturing – Types of pr – process control and strategies – Direct Digi Groover, "Automation, Production System Education (2013) Groover, Emory Zimmers Jr., "CAD/CAM Regh and Henry W.Kreabber, "Computer Integ Mahon and Jimmie Browne, "CAD CAM Prince	ponents of FMS er control syste <u>NITORING</u> inventory mana roduction monit ital Control ns and Comput ", Prentice Hal rated Manufactu	S – type ms – ap gement coring sy ter Inte l of Ind	es – FMS worl plications and – material req vstems – struct Total Periods grated Manufa ia Pvt. Ltd., (2 earson Educatio	Bar code kstation – benefits 9 uirements ure model s: 45 acturing", 006) m, (2005)
T. I Orom Koren, Computer megrated Manufacturing , McOraw min, (2003)	Shop floor contro technology – auto material handling COMPUTER AI Production plannin planning (MRP) – of manufacturing – of manufacturing – of manufacturing – text Books: 1. Mikell P. Pearson E 2. Mikell P. References: 1. James A. I 2. Chris McM Pearson E	mated data collection system – FMS – comp and storage system – FMS layout – comput DED PLANNING, CONTROL AND MOI ng and control – cost planning and control – Lean and Agile Manufacturing – Types of pi – process control and strategies – Direct Digi Groover, "Automation, Production System Education (2013) Groover, Emory Zimmers Jr., "CAD/CAM Regh and Henry W.Kreabber, "Computer Integr Mahon and Jimmie Browne, "CAD CAM Princ ducation, (2005)	ponents of FMS er control syste <b>NITORING</b> inventory mana roduction monit ital Control as and Comput ", Prentice Hal rated Manufactu ciples, Practice a	S – type ms – ap gement coring sy ter Inte l of Ind ring", Pe nd Man	es – FMS worl plications and – material req /stems – struct Total Periods grated Manufa ia Pvt. Ltd., (2 earson Educatio ufacturing Man	Bar code kstation – benefits 9 uirements ure model s: 45 acturing", 006) m, (2005)

Course Outcomes				ł	Progr	am O	utcor	nes (l	POs)				Program Specific Outcomes (PSOs)				
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	
C01	2	1		1	2							1	1	1		2	
CO2	2			2	2							2	1			2	
CO3	1		2	1	1					1		1	1		1	1	
CO4	2		1	1						1		1	1		1	1	
C05																	
CO6	2			1	1					1		1	1			1	

191MEEE Programme:		FIREWORKS SAFETY										
Programme:	•				L-T-P 3-0-0	C 3						
	B.E. Mechanical Engineering	Sem:		Ca	tegory:	PE						
Prerequisites:	Nil	Seini			esorj.	12						
Aim:	To learn the properties, preparation of fire	works shamin	ola on	d safaty in	firoworka i	ductry						
				id safety III	meworks n	laustry						
Course Outcom												
The students will		1 • 1 /										
	e properties of various chemicals used in fire	eworks indust	ry									
	sitivity of fireworks chemicals											
	oncepts of earthing and legal requirements e process safety in fireworks industry											
	per material handling techniques / equipmen	<b>. t</b>										
	wastes and ensure the human safety in firew											
UNIT I	PROPERTIES OF FIREWORKS		c			9						
	ingredients of fireworks chemicals – Fuel – 0			a Agant I	Pinder pro							
	n fireworks: Aluminum powder, Ammonia					<b>.</b>						
	Boric Acid, Calcium sulfate, Carbon, Charco											
	rate, Potassium Nitrate, Potassium per chlo											
	t and friction sensitivity	inde, Soundin	1 viti ai	ie, strontiu		Julphul						
UNIT II	STATIC CHARGE AND DUST	EXPLOSION	J			9						
	charge – reasons – prevention – earthing –			lightning -	- causes and	-						
1	on and maintenance of lightning arrestor – $I$	<b>V</b> 1	<u> </u>	0 0								
	biological barriers – personal protective equi											
UNIT III	PROCESS SAFETY	1 1		1		9						
	y, mixing – filling – fuse cutting – fuse fixi	ng finishing	r dry	ving at vari	ous stages	-						
	ools – materials, layout: building – distan											
•	pries act – explosive act and rules	ees - person	ai più	lective eq	upments –	ponution						
*	*	7				0						
UNIT IV	MATERIAL HANDLING		•.		11	9						
	g – factors – types – fuse handling – paper											
	ndling the mix inside factory –material move		pit –	transport re	estrictions –	overnead						
-	extinguishers – loose chemicals handling ar	<u>^</u>										
UNIT V	WASTE CONTROL AND USE		<u> </u>	• 1	· · · 1·	9						
	es – wastes in fireworks – disposal – spillag											
•	ards in display –electronic ignition – restric – burns and scalds – role of fire service - fac											
The extinguishers	- buills and scalds - fole of the service - fac	ciones aci - c	lasses		otal Periods							
Text Books				10	Jtal I el lous	<b>4</b> 3						
	D. Mariahanar D. and Laharan Dair C. (	<b>T</b> '	D. 1.		Q . f. t?? 1	T 1'4'						
	P., Marichamy P. and Johnson Raja S., ' Publications, Madurai, (2019)	Fireworks –	Produ	iction and	Salety, Is	l Edition,						
	ancaster, Roy E.A. Butler, J. Mark Lancaste	er and Takeo	Shimi	711 "Firow	orks Princ	inles and						
	, Chemical Publishing Company, New Yorl		SIIIII	zu, rnew		ipies and						
Tractice	, chemical rubinning company, ivew rom	x, (2000)										
References												
	ton, "Dust Explosion Prevention and Pre-	otection", Ins	stitutic	on of Chen	nical Engin	eers, UK,						
	S. Russell, <b>"The Chemistry of Fireworks"</b> ,	Royal Societ	vofC	hemistry 1	JK (2000)							
	ngs of National conference on "Pyro Te	•	•	•		es Safety						
$\gamma$ $r_{10}$ $r_{20}$	tion (PESO), Ministry of Explosives, Govern					5 Survey						
Organizat	. "Fireworks Safety Manual: A Collection	of Essavs".	Hvde I	Park. New	York. (1990	))						
Organizat	, "Fireworks Safety Manual: A Collection	of Essays", ]	Hyde ]	Park, New	York, (1990	))						
Organizat	, "Fireworks Safety Manual: A Collection	of Essays", ]	Hyde ]	Park, New	York, (1990	))						

Course Outcomes					Progr	am O	utcon	nes (P	POs)					Program Specific Outcomes (PSOs)						
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4				
CO1	2	1	1	1		1					1	2	2							
CO2	2	2	1	1		1	2	1	1		1	1	1	2		2				
CO3	2	1	3	1		3	2			2			2							
CO4	2	1	3	2		3	2		1		2	1	2			2				
CO5	2	1	1	2		1	1				2		2	2		2				
CO6	2	2	3	2		3	3	2	1	1	2	1	2			1				

<b>191MEEF</b>	FUNDAMENTALS OF NANO TECHN		L-T-P	С		
					3-0-0	3
<b>Programme:</b>	B.E. Mechanical Engineering	Sem:		Ca	tegory:	PE
Prerequisites:	Physics of Materials					
Aim:	To learn about basis of nanomaterial science, prepar	ation me	ethod,	type	s and applic	ation
<b>Course Outcom</b>	ies:					
The students will	be able to					
CO1. Familiarize	about the science of nano materials					
CO2. Prepare nan	o materials using various methods					
CO3. Know the va	arious nano materials and oxides					
CO4. Identify the	various characterization technique					
CO5. Understand	the applications of MEMS					
CO6. Realize the	nano information storage system					

UNIT I BASICS OF NANOSCIENCE	9
Nano scale Science and Technology - Implications for Physics, Chemistry, Biology and Engi	neering –
Classifications of nano structured materials - nano particles - quantum dots, nanowires - ultra	
multilayered materials - Length Scales involved and effect on properties: Mechanical, Electronic	c, Optical,
Magnetic and Thermal properties	
UNIT II GENERAL METHODS OF PREPARATION	9
Bottom-up Synthesis – Top-down Approach: Co-Precipitation, Ultrasonication, Mechanical Milling, routes, Self-assembly, Vapour phase deposition, MOCVD, Sputtering, Evaporation, Molecular Bear Atomic Layer Epitaxy, MOMBE.	
UNIT III NANOMATERIALS	9
Nanoforms of Carbon – Buckminster fullerene – graphene and carbon nanotube, Single wall carbon I (SWCNT) and Multi wall carbon nanotubes (MWCNT) – methods of synthesis (arc-growth, laser abla routes, Plasma CVD), structure – property relationships applications – Nanometal oxides – ZnO, Ti ZrO ₂ , NiO, nanoalumina, CaO, AgTiO ₂ , Ferrites, Nano clays functionalization and applications	tion, CVD iO ₂ , MgO,
UNIT IV CHARACTERIZATION TECHNIQUES	9
Electron Microscopy including high resolution imaging, Surface Analysis techniques – AFM, SF SNOM, ESCA, SIMS – Nano indentation UNIT V APPLICATIONS	9
Nano InfoTech: Information storage – nanocomputer, molecular switch, super chip, nano crys	-
biotechlogy: nanoprobes in medical diagnostics and biotechnology, Nano medicines, Targetted drug Bioimaging – Micro Electro Mechanical Systems (MEMS), Nano Electro Mechanical Systems (NEM sensors, nano crystalline silver for bacterial inhibition, Nano particles for sun barrier products - In printing, solar cell, battery	g delivery, S) – Nano
Total Periods:	45
Text Books	
<ol> <li>Guozhong Cao, Ying Wang, "Nanostructures and Nanomaterials: Synthesis, Proper Applications", World Scientific Publications, Singapore, (2011)</li> <li>Charles P. Poole and Frank J. Ownes, "Introduction to Nanotechnology", Wiley India, N (2006)</li> </ol>	
References	
<ol> <li>Vollath D., "Nanomaterials: An Introduction to Synthesis, Properties and Application India, New Delhi, (2013)</li> <li>Jeremy Ramsden, "Nanotechnology: An Introduction", Elsevier, UK, (2008)</li> </ol>	ıs", Wiley

3. Edelstein A.S., Cammearata R.C., "Nanomaterials: Synthesis, Properties and Applications", Institute of Physics Publishing, Bristol and Philadelphia, (1996)

4. Manasi Karkere, **"Nanotechnology: Fundamentals and Applications"**, I.K. International, New Delhi, (2009)

Course Outcomes				ł	Progr	am O	utcor	nes (I	POs)				Program Specific Outcomes (PSOs)				
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	
C01	3	3										3	3				
CO2	3	3		3	3							3				2	
CO3		3		2								3		3			
CO4			2		3			1	2			3			3		
CO5	3			3	3	2	2					3		3			
CO6			3	2	3							3				2	

191MEEG	HYBRID AND E-VEHICLES	5		L-T-P	С
				3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:		Category:	PE
Prerequisites:	Thermal Engineering			· · · ·	
Aim:	To understand the basic concepts of Hybrid Elect	ric Vehi	cles an	d its application	
<b>Course Outcome</b>	S:				
CO2. Develop Co	be able to Hybrid Electric Drive-trains and Electric Drive-train nfiguration and control of DC Motor drives Energy Storage Requirements in Hybrid and Electr		les		

CO4. Matching the electric machine and the internal combustion engine

CO5. Identify the selecting the energy storage technology

CO6. Recognize the energy management strategies used in hybrid and electric vehicles

UNIT I INTRODUCTION TO HYBRID ELECTRIC VEHICLES	9
Introduction to Hybrid Electric Vehicles, Conventional Vehicles. Hybrid Electric Drive-trains and Electric	etric
Drive-trains: Basic concept of electric traction, introduction to various electric drive-train topologies, p	ower
flow control in electric drive-train topologies, fuel efficiency analysis.	
UNIT II ELECTRIC PROPULSION	9
Introduction to electric components used in hybrid and electric vehicles, Configuration and control of	
Motor drives, Configuration and control of Induction Motor drives, configuration and control of Perma	
Magnet Motor drives, Configuration and control of Switch Reluctance Motor drives, drive system effic	ciency.
UNIT III ENERGY STORAGE	9
Introduction to Energy Storage Requirements in Hybrid and Electric Vehicles. Battery, Fuel Cell, Supe	er
Capacitor and Flywheel based energy storage and its analysis, Hybridization of different energy storag	e
devices.	
UNIT IV SIZING THE DRIVE SYSTEM	9
Matching the electric machine and the internal combustion engine (ICE), Sizing the propulsion motor,	sizing
the power electronics, selecting the energy storage technology, Communications, supporting subsystem	ns.
UNIT V ENERGY MANAGEMENT STRATEGIES	9
Introduction to energy management strategies used in hybrid and electric vehicles, classification of dif	ferent
energy management strategies, comparison of different energy management strategies, implementation	i issues
of energy management strategies. Case Studies: Design of a Hybrid Electric Vehicle (HEV), Design of	a
Battery Electric Vehicle (BEV).	
Total Periods:	45
Text Books	
1. Kirpal Singh, "Automobile Engineering Vol.2", Standard Publishers, New Delhi, (2014)	
2. Ganesan V., "Internal Combustion Engines", Tata McGraw Hill, (2012)	
References	
1. Heinz Heisler, "Advanced Engine Technology", SAE International Publications, USA, (20	
2. John B. Heywood, "Internal Combustion Engine Fundamentals", Tata McGraw-Hill, (1988	)
3. Gupta H.N., "Fundamentals of Internal Combustion Engines", Prentice Hall of India, (2006	
4. Ultrich Adler, "Automotive Electric/Electronic Systems", Published by Robert Bosh GmbH,	(1995)

Course Outcomes				Prog	gram	Outc	omes	(POs	)				Program Specific Outcomes (PSOs)					
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4		
CO1	2	1		1	2							1	1	1		2		
CO2	2			2	2							2	1			2		
CO3	1		2	1	1					1		1	1		1	1		
CO4	2		1	1						1		1	1		1	1		
CO5																		
CO6	2			1	1					1		1	1			1		

<b>191MEEH</b>	INDUSTRIAL ENGINEERING & MAN	AGEN	1EN	Γ	L-T-P	С
					3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:	1	Ca	ategory:	PE
Prerequisites:	Engineering Economics and Management					
Aim:	To provide students an insight into the concepts of	findustr	ial eng	gine	ering and or	ganization
<b>Course Outcom</b>	les:					
The students will	be able to					
CO1. Forecast the	demand using various forecasting techniques					
CO2. Know the co	osting methods					
CO3. Understand	the concepts of industrial organization.					
CO4. Familiarize	with principles of work-study and ergonomics					
CO5. Study the va	arious aspects of plant design					
CO( II 1 1 1	41					

CO6. Understand the various manufacturing systems

		0
UNIT I		9
	and micro economics - Demand and supply - Factors influencing demand - Elasticity of dem	
	d forecasting - Time series - Exponential smoothing casual forecast - Delphi method - Corr	
-	gression – Elements of cost – Determination of Material cost – Labour cost – Expenses – Types	of cost
	of production – Overhead expenses	
UNIT I		9
	ction to Industrial Engineering - Concepts - History and Development of Industrial engine	
	of Industrial Engineer - Applications - Productivity - Factors affecting productivity - Inc	reasing
product	ivity of resources – Kinds of productivity measures	
UNIT I	II WORK DESIGN	9
	ction to work study – Method study – Time study – stopwatch time study – Standard data – I Ieasurement (M-T-M) – Work sampling – Ergonomics	Method
UNIT I	V PLANT LAYOUT	9
	cation – Factors – Plant layout – Types – Layout design process – Computerized Layout Plan action and Improvement algorithms – ALDEP – CORELAP and CRAFT – Scheduling	nning –
UNIT V	V GROUP TECHNOLOGY	9
machin	technology – Problem definition – Production flow analysis – Heuristic methods of group e matrices – Flexible Manufacturing System – FMS work stations – Material handling and S – Cellular Manufacturing System	Storage
	Total Periods:	45
Text B	ooks	
1.	Khanna O.P., <b>"Industrial Engineering and Management"</b> , Dhanpat Rai Publications, New (2006)	^y Delhi,
2.	Panneerselvam. R. "Production/Operations Management", Prentice Hall of India, New (2012)	Delhi
Referen	nces	
1.	Patil S.B., Karad A.A. and Kushare P.B., "Industrial Engineering and Management", Te Publications, Pune, (2009)	chnical
2.	Buffa E.S. and Sarin R.K., "Modern Production/Operational Management", Wiley India Delhi, (2009)	a, New
3.	Dan Reid R., Nada R. Sanders, "Operations Management: An Integrated Approach", Wile New Delhi, (2016)	y India
4.	Nigel Slack, Stuart Chambers, Robert Johnston., "Operation Management", Pearson Edu New Delhi, (2010)	ication

Course Outcomes				I	Progr	am O	utcor	nes (l	POs)				Program Specific Outcomes (PSOs)					
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4		
CO1	3	3	2	2						2		2	3			2		
CO2		2		3	1		1	3				3	2			2		
CO3	1			3	1			2	2	2		3		3		3		
CO4	2	1			2			3		1		3	1	2		2		
CO5	3	2	1	2	3		1	1				3		1		3		
CO6	3	2		1	1			2				3			2	2		

<b>191MEEI</b>	PRODUCT DESIGN AND DE	L-T-P	С		
				3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:		Category:	OE
Prerequisites:	Nil				
Aim:	Understand the application of product des	ign methods to	develo	op a product	
<b>Course Outcom</b>	les:				
The students will	be able to				
CO1: Know the c	ustomer needs for the product development				
CO2: Design the	product architecture				
CO3: Determine t	he cost reduction for the design				
CO4: Know the p	rocedure for prototyping				
CO5: Analyze the	project development t				
CO6: Develop the					
1	*				

UNIT I PRODUCT DEVELOPMENT AND CONCEPT SELECTION	9
Product development process Product development organizations- Identifying the customer needs Est the product specifications concept generation Concept selection.	ablishing
UNIT II PRODUCT ARCHITECTURE	9
Product architecture Implication of the architecture Establishing the architecture Related syste design issues.	em level
UNIT III INDUSTRIAL AND MANUFACTURING DESIGN	9
Need for industrial design Impact of industrial design Industrial design process. Assessing the operation industrial design-Human Engineering consideration - Estimate the manufacturing cost Reduce the cost Reduce the assembly cost Reduce the support cost Impact of DFM	
decisions on other factors	
UNIT IV PROTOTYPING AND ECONOMIC ANALYSIS	9
Principles of prototyping Planning for prototypes - Elements of economic analysis Base case model Sensitivity analysis Influence of the quantitative factors	financial
UNIT V MANAGING PRODUCT DEVELOPMENT PROJECTS	9
Sequential, parallel and coupled tasks - Baseline project planning Project Budget Project execution evaluation- patents- patent search-patent laws International code for patents.	1 Project
Total Periods:	45
References	
<ol> <li>Charles Gevirtz, Developing New products with TQM, McGraw Hill International editions, 19</li> <li>Karal .T. Ulrich, Steven D.Eppinger, Product Design and Development, McGRAW- HILL International Editions 2002</li> </ol>	94

International Editions.2003. 3. S.Rosenthal, Effective product design and development, Irwin 1992.

Course Outcomes		Program Outcomes (POs)											Program Specific Outcomes (PSOs)					
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4		
CO1		3	2	2						2		2	3	1		1		
CO2		2		3	1		1	3				3	2			2		
CO3				3	1			2	2	2		3		3	2			
CO4		1			2			3		1		3	1	2				
CO5		2	1	2	3		1	1				3		1		2		
CO6		2		1	1			2				3			2			

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45

**Total Periods:** 

191MEEJ	INTERNET OF THINGS FOR MANUF	RING	L-T-P	С	
	•			3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:		Category:	PC
Prerequisites:	Manufacturing Technology				
Aim:	To discover key IoT concepts including identi protocols To explore IoT technologies, architectures, stand created by collecting, communicating, coordinati To examine developments that will likely shape	lards, an ing, and	d regula leveragi	tion to realize ng data	the value
<b>Course Outcom</b>	ies:				
The students will	be able to				
CO1: Know the se	ecurity issues in the IoT				
CO2: Design proc	edure the implementing the IoT				
CO3: Determine t	he requirement for the IoT in manufacturing enviro	onment			
CO4: Analysis the	e prerequisites for IoT				
CO5: Understand	the applications of IoT in manufacturing				
COC IZ 1					

CO6: Know the places where the IoT can be implemented

#### UNIT I

#### INTRODUCTION

Security issues Opportunities for IoT -Issues in implementing IoT. Technological challenges, RFID and the Electronic Product Code (EPC) network, the web of things.

#### UNIT II

#### **DESIGN OF IoT**

Design challenges in IoT -Standardization, Security and privacy, Infrastructure, Analytics. Design steps for implementing IoT.

#### UNIT III

#### **PROTOTYPING OF IoT**

Design principles for connected devices -Embedded devices, physical design, online components, embedded coding system. Informed Manufacturing plant Elements, IoT implementation in Transportation and logistics, Energy and utilities, Automotive Connected supply chain, Plant floor control automation, remote monitoring, Management of critical assets, Energy management and resource optimization, proactive maintenance.

#### UNIT IV PREREQUISITES FOR IoT

IOT Technologies Wireless protocols low-power design (Bluetooth Low Energy), range extension techniques (data mining and mesh networking), and data-intensive IoT for continuous recognition applications Data storage and analysis Localization algorithms Localization for mobile systems.

#### APPLICATION IN MANUFACTURING

Applications HCI and IoT world -Multilingual Interactions Robotics and Autonomous Vehicles Sensing and data Processing-Simultaneous mapping and Localization-Levels of autonomy, Smart factories,

Future research challenges

#### References

UNIT V

- 1. Code Halos: How the Digital Lives of People, Things, and Organizations are Changing the Rules of Business, by Malcolm Frank, Paul Roehrig and Ben Pring, published by John Wiley & Sons.
- 2. Internet of Things: A Hands-On Approach by Vijay Madisetti, Arshdeep Bahga, VPT; 1st edition 2014.
- 3. Jan Holler, Vlasios Tsiatsis, Catherine Mulligan, Stamatis Karnouskos, Stefan Avesand, David -to-Machine to the Internet of Things -Introduction to a New Age of intelligence, Elsevier.
- 4. Meta Products -Building the Internet of Things by Wimer Hazenberg, Menno Huisman, BIS Publishers 2014

Course Outcomes				ł	Progr	am O	utcor	nes (l	POs)				Prog		pecific (PSOs)	e Outcomes )
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	3			1				1	1		3	1	1		3	
CO2	2	2	2	1		2	1	1	1		2	2	2		3	2
CO3	2	1	1	1		1	2	1	1		2	2	1		3	2
CO4	2	1	1	1		1	2	1	1		2	2	2		3	
CO5	2	1	1	1		1	2	1	1		2	2	2		3	2
CO6	2	1	1	1		1	3	1	1		2	2	2		3	

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191MEEK	MODERN MACHINING PROCI	ESSES			L-T-P	C
					3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:	-	C	Category:	PC
Prerequisites:	Manufacturing Technology					
Aim:	To understand the various unconventional applications	machinir	ng pro	oces	ses, advan	tages a
<b>Course Outcom</b>	les:					
The students will	be able to					
CO1. Classify ur	conventional machining process and identify varia	ous proce	ess sel	ectio	on paramet	ers
CO2. Learn varie	ous mechanical energy based process					
CO3. Understand	the various unconventional machining process ba	used on e	lectric	al e	nergy	
CO4. Study the v	various chemical energy machining process, param	eters aff	ecting	it a	nd application	ons
CO5. Know the	nachining process that fall under electro chemical	energy.	its par	ame	eters and an	plication

CO5. Know the machining process that fall under electro chemical energy, its parameters and applications

CO6. Explain the various thermal energy based machining processes in detail along with their applications

## MECHANICAL ENERGY BASED PROCESSES

Unconventional machining Process – Need – classification – Brief overview – Abrasive Jet Machining – Water Jet Machining – Abrasive Water Jet Machining – Ultrasonic Machining (AJM, WJM, AWJM and USM) – Working Principles – equipment used – Process parameters – MRR – Variation in techniques used – Applications

#### UNIT II

**UNIT** I

#### ELECTRICAL ENERGY BASED PROCESSES

Electric Discharge Machining (EDM) – working Principle – equipment's – Process Parameters – Surface Finish and MRR – electrode / Tool – Power and control Circuits – Tool Wear – Dielectric – Flushing – Wire cut EDM – Applications

#### **UNIT III**

#### CHEMICAL ENERGY BASED PROCESSES

Chemical machining and Electro-Chemical machining (CHM and ECM) – Etchants – maskants – techniques of applying maskants – Process Parameters – Surface finish and MRR – Applications

#### UNIT IV ELECTRO-CHEMICAL ENERGY BASED PROCESSES

Principles of ECM – equipment's – Surface Roughness and MRR – Electrical circuit – Process Parameters – ECG and ECH – Applications

#### THERMAL ENERGY BASED PROCESSES

Laser Beam machining and drilling (LBM), plasma Arc machining (PAM) and Electron Beam Machining (EBM) – Principles – Equipment –Types – Beam control techniques – Applications

#### Total Periods: 45

Text Books

UNIT V

- 1. Vijay K. Jain, "Advanced Machining Processes", Allied Publishers Pvt. Ltd., New Delhi, (2014)
- 2. Mishra P.K., **"Non-Conventional Machining"**, The Institution of Engineers, India, (2015) ferences

References

- 1. Benedict G.F., "Nontraditional Manufacturing Processes", Marcel Dekker Inc., New York, (2014)
- 2. Pandey P.C. and Shan H.S., "Modern Machining Processes", Tata McGraw-Hill, New Delhi (2015)
- 3. Mc Geough, "Advanced Methods of Machining", Chapman and Hall, London, (2010)
- 4. Paul De Garmo, Black J.T. and Ronald A. Kohser., "Material and Processes in Manufacturing", Prentice Hall of India Pvt. Ltd., New Delhi, (2012)

Course Outcomes		Program Outcomes (POs)											Program Specific Outcomes (PSOs)					
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4		
CO1	3	3			1				1	1		3	1	1		3		
CO2	3	2	2	2	1		2	1	1	1		2	2	2		3		
CO3	3	2	1	1	1		1	2	1	1		2	2	1		3		
CO4	3	2	1	1	1		1	2	1	1		2	2	2		3		
CO5	3	2	1	1	1		1	2	1	1		2	2	2		3		
CO6	3	2	1	1	1		1	3	1	1		2	2	2		3		

191MEEL	RAPID PROTOTYPING			L-T-P	С
				3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:		Category:	PE
Prerequisites:	161ME31-Manufacturing Technology			8 .	
1	To provide knowledge on different types of	Rapid	Prototy	ping systems	and its
Aim:	applications in various fields	1	5	185	
<b>Course Outcom</b>					
The students will	be able to				
CO1. Gain depth	knowledge in different types of Rapid Prototyping	system	s and its	applications in	n various
fields					
	the various geometric modeling and meshing techn	niques			
6	he data formats and interface				
	quid and solid based engineering and digitization to	echnique	es		
	owder sintering processes and its application				
CO6. Design and	generate supporting structures for any component				
UNIT I	BASICS OF RAPID PROTOT	VDINC			9
	ent of RP systems – RP process chain – Impact of Ra		atuning	n Product Dev	-
	ng – Virtual prototyping – Rapid Tooling – Benefit			II Floduct Dev	elopment
UNIT II	REVERSE ENGINEERING		lications		9
	ction – Data Processing for Rapid Prototyping:		ric mode	ling techniqu	-
	l solid modeling – data formats – Data interfacing,				
	design, Model Slicing and contour data organiza				
path generation					
	LIQUID BASED AND SOLID BASED RAPID I	PROTO	TYPIN	<b>G SYSTEMS</b>	9
	Apparatus: Principle, per-build process, part-				s, photo
porymenzation of	SL resins, part quality and process planning, r	recoating	g issues,	materials, ad	
	pplications. Working principle, process, strengths,				vantages,
limitations and ap deposition Modeli	pplications. Working principle, process, strengths, ng, Solid Ground Curing, Laminated object manufa	weakne cturing	esses and – Case st	applications udies	vantages, of Fused
limitations and ap	plications. Working principle, process, strengths,	weakne cturing	esses and – Case st	applications udies	vantages,
limitations and ap deposition Modelin UNIT IV Selective Laser Sin	pplications. Working principle, process, strengths, ng, Solid Ground Curing, Laminated object manufa <b>POWDER BASED RAPID PROTO</b> ntering(SLS): Principle, process, Indirect and direc	weakne cturing TYPIN t SLS –	esses and – Case st <b>G SYST</b> powder	l applications udies EMS structures, mo	vantages, of Fused 9 deling of
limitations and ap deposition Modelin UNIT IV Selective Laser Sin SLS, materials, po	pplications. Working principle, process, strengths, ng, Solid Ground Curing, Laminated object manufa <b>POWDER BASED RAPID PROTO</b> ntering(SLS): Principle, process, Indirect and direc st processing, post curing, surface deviation and acc	weakne cturing TYPIN t SLS – curacy, A	esses and – Case st G SYST powder Applicati	l applications udies EMS structures, mo ons – Laser Er	vantages, of Fused 9 deling of
limitations and ap deposition Modeli UNIT IV Selective Laser Si SLS, materials, po Net Shaping: Proc	pplications. Working principle, process, strengths, ng, Solid Ground Curing, Laminated object manufa <b>POWDER BASED RAPID PROTO</b> ntering(SLS): Principle, process, Indirect and direc st processing, post curing, surface deviation and acc esses, materials, products, advantages, limitations a	weakne cturing TYPIN t SLS – curacy, A nd appli	esses and – Case st G SYST powder Applicati cations –	applications udies EMS structures, mo ons – Laser Er Case Studies	vantages, of Fused 9 deling of ngineered
limitations and ap deposition Modelin UNIT IV Selective Laser Sin SLS, materials, po	pplications. Working principle, process, strengths, ng, Solid Ground Curing, Laminated object manufa <b>POWDER BASED RAPID PROTO</b> ntering(SLS): Principle, process, Indirect and direc st processing, post curing, surface deviation and acc	weakne cturing TYPIN t SLS – curacy, A nd appli	esses and – Case st G SYST powder Applicati cations –	applications udies EMS structures, mo ons – Laser Er Case Studies	vantages, of Fused 9 deling of
limitations and ap deposition Modelin UNIT IV Selective Laser Sin SLS, materials, po Net Shaping: Proce UNIT V	pplications. Working principle, process, strengths, ng, Solid Ground Curing, Laminated object manufa <b>POWDER BASED RAPID PROTO</b> ntering(SLS): Principle, process, Indirect and direc st processing, post curing, surface deviation and acc esses, materials, products, advantages, limitations a	weakne cturing TYPIN t SLS – curacy, A nd appli TECH	- Case st G SYST powder Applicati cations - NOLOG	l applications udies EMS structures, mo ons – Laser Er Case Studies IES	vantages, of Fused 9 deling of ngineered 9
limitations and ap deposition Modeli UNIT IV Selective Laser Sit SLS, materials, po Net Shaping: Proce UNIT V Three dimensional material system.	pplications. Working principle, process, strengths, ng, Solid Ground Curing, Laminated object manufa <b>POWDER BASED RAPID PROTO</b> ntering(SLS): Principle, process, Indirect and direc st processing, post curing, surface deviation and acc esses, materials, products, advantages, limitations a <b>OTHER RAPID PROTOTYPING</b> I Printing: Principle, basic process, Physics of 3DF Solid based, Liquid based and powder based	weakned cturing TYPIN t SLS – curacy, A nd appli TECHI P, types 3DP sy	- Case st - Case st G SYST powder Applicati cations - NOLOG of printin stems, s	l applications udies EMS structures, mo ons – Laser Er Case Studies IES ng, process cap trength and v	vantages, of Fused 9 deling of ngineered 9 pabilities, veakness,
limitations and ap deposition Modelin UNIT IV Selective Laser Sir SLS, materials, po Net Shaping: Proce UNIT V Three dimensional material system. Applications and	pplications. Working principle, process, strengths, ng, Solid Ground Curing, Laminated object manufa <b>POWDER BASED RAPID PROTO</b> ntering(SLS): Principle, process, Indirect and direc st processing, post curing, surface deviation and acc esses, materials, products, advantages, limitations a <b>OTHER RAPID PROTOTYPING</b> I Printing: Principle, basic process, Physics of 3DF Solid based, Liquid based and powder based case studies. Shape Deposition Manufacturing	weakned cturing TYPIN t SLS – curacy, A nd appli TECH P, types 3DP sy g: Intro	- Case st - Case st G SYST powder Applicati cations - NOLOG of printin stems, s duction,	l applications udies EMS structures, mo ons – Laser Er Case Studies IES ng, process cap trength and v basic process	vantages, of Fused 9 deling of ngineered 9 pabilities, veakness, ss, shape
limitations and ap deposition Modelin UNIT IV Selective Laser Sin SLS, materials, po Net Shaping: Proce UNIT V Three dimensional material system. Applications and decomposition, m	pplications. Working principle, process, strengths, ng, Solid Ground Curing, Laminated object manufa <b>POWDER BASED RAPID PROTO</b> ntering(SLS): Principle, process, Indirect and direc st processing, post curing, surface deviation and acc esses, materials, products, advantages, limitations a <b>OTHER RAPID PROTOTYPING</b> I Printing: Principle, basic process, Physics of 3DF Solid based, Liquid based and powder based	weakned cturing TYPIN t SLS – curacy, A nd appli TECH P, types 3DP sy g: Intro	- Case st - Case st G SYST powder Applicati cations - NOLOG of printin stems, s duction,	l applications udies EMS structures, mo ons – Laser Er Case Studies IES ng, process cap trength and v basic process	vantages, of Fused 9 deling of ngineered 9 pabilities, veakness, ss, shape
limitations and ap deposition Modelin UNIT IV Selective Laser Sir SLS, materials, po Net Shaping: Proce UNIT V Three dimensional material system. Applications and	pplications. Working principle, process, strengths, ng, Solid Ground Curing, Laminated object manufa <b>POWDER BASED RAPID PROTO</b> ntering(SLS): Principle, process, Indirect and direc st processing, post curing, surface deviation and acc esses, materials, products, advantages, limitations a <b>OTHER RAPID PROTOTYPING</b> I Printing: Principle, basic process, Physics of 3DF Solid based, Liquid based and powder based case studies. Shape Deposition Manufacturing	weakned cturing TYPIN t SLS – curacy, A nd appli TECH P, types 3DP sy g: Intro	- Case st - Case st G SYST powder Applicati cations - NOLOG of printin stems, s duction, ectron E	l applications udies EMS structures, mo ons – Laser Er Case Studies IES ng, process caj trength and v basic proces Beam Melting	vantages, of Fused 9 deling of ngineered 9 pabilities, veakness, ss, shape – Rapid
limitations and ap deposition Modeli UNIT IV Selective Laser Sir SLS, materials, po Net Shaping: Proce UNIT V Three dimensional material system. Applications and decomposition, m manufacturing	pplications. Working principle, process, strengths, ng, Solid Ground Curing, Laminated object manufa <b>POWDER BASED RAPID PROTO</b> ntering(SLS): Principle, process, Indirect and direc st processing, post curing, surface deviation and acc esses, materials, products, advantages, limitations a <b>OTHER RAPID PROTOTYPING</b> I Printing: Principle, basic process, Physics of 3DF Solid based, Liquid based and powder based case studies. Shape Deposition Manufacturing	weakned cturing TYPIN t SLS – curacy, A nd appli TECH P, types 3DP sy g: Intro	- Case st - Case st G SYST powder Applicati cations - NOLOG of printin stems, s duction, ectron E	l applications udies EMS structures, mo ons – Laser Er Case Studies IES ng, process cap trength and v basic process	vantages, of Fused 9 deling of ngineered 9 pabilities, veakness, ss, shape – Rapid
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limitations and ap deposition Modelii UNIT IV Selective Laser Sit SLS, materials, po Net Shaping: Proce UNIT V Three dimensional material system. Applications and decomposition, m manufacturing <b>Text Books</b> 1. Chua C.K	pplications. Working principle, process, strengths, ng, Solid Ground Curing, Laminated object manufa <b>POWDER BASED RAPID PROTO</b> Intering(SLS): Principle, process, Indirect and direct st processing, post curing, surface deviation and acce esses, materials, products, advantages, limitations a <b>OTHER RAPID PROTOTYPING</b> I Printing: Principle, basic process, Physics of 3DF Solid based, Liquid based and powder based case studies. Shape Deposition Manufacturing old SDM and applications. Selective Laser Mel	weakne cturing TYPIN t SLS – curacy, <i>I</i> nd appli TECHI P, types 3DP sy g: Intro ting, El	- Case st - Case st G SYST powder Applicati cations - NOLOG of printin stems, s duction, ectron E	l applications udies EMS structures, mo ons – Laser Er Case Studies IES ng, process cap trength and v basic process Beam Melting Total Periods	vantages, of Fused 9 deling of ngineered 9 pabilities, veakness, ss, shape – Rapid : 45
limitations and ap deposition Modeli UNIT IV Selective Laser Sit SLS, materials, po Net Shaping: Proce UNIT V Three dimensional material system. Applications and decomposition, m manufacturing <b>Text Books</b> 1. Chua C.K Scientific	pplications. Working principle, process, strengths, ng, Solid Ground Curing, Laminated object manufa POWDER BASED RAPID PROTO Intering(SLS): Principle, process, Indirect and direct st processing, post curing, surface deviation and accesses, materials, products, advantages, limitations a OTHER RAPID PROTOTYPING I Printing: Principle, basic process, Physics of 3DF Solid based, Liquid based and powder based case studies. Shape Deposition Manufacturing old SDM and applications. Selective Laser Mel ., Leong K.F., and Lim C.S., "Rapid prototyping Publishers, (2010)	weakned cturing - TYPIN t SLS – curacy, A nd appli TECHI P, types 3DP sy g: Intro ting, El : Princi	Applicati cations – <b>NOLOG</b> of printin stems, s duction, ectron E	l applications udies EMS structures, mo ons – Laser Er Case Studies IES ng, process cap trength and v basic proces Beam Melting Total Periods	vantages, of Fused 9 deling of ngineered 9 pabilities, veakness, ss, shape – Rapid : 45
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limitations and ap deposition Modelin UNIT IV Selective Laser Sir SLS, materials, po Net Shaping: Proce UNIT V Three dimensional material system. Applications and decomposition, m manufacturing Text Books 1. Chua C.K Scientific 2. Andreas G References	pplications. Working principle, process, strengths, ng, Solid Ground Curing, Laminated object manufa <b>POWDER BASED RAPID PROTO</b> ntering(SLS): Principle, process, Indirect and direc st processing, post curing, surface deviation and acc esses, materials, products, advantages, limitations a <b>OTHER RAPID PROTOTYPING</b> I Printing: Principle, basic process, Physics of 3DF Solid based, Liquid based and powder based case studies. Shape Deposition Manufacturing old SDM and applications. Selective Laser Mel ., Leong K.F., and Lim C.S., <b>"Rapid prototyping</b> Publishers, (2010) Behardt, <b>"Rapid prototyping"</b> , Hanser Gardener I	weakned cturing TYPIN t SLS – curacy, A nd appli TECHI P, types 3DP sy g: Intro tting, El : Princi	Applicati cations – NOLOG of printin stems, s duction, ectron E ples and ions, (20	l applications udies EMS structures, mo ons – Laser Er Case Studies IES ng, process cap trength and v basic process Beam Melting Total Periods I applications 03)	vantages, of Fused 9 deling of ngineered 9 pabilities, veakness, ss, shape - Rapid : 45 ", World
limitations and ap deposition Modeli UNIT IV Selective Laser Si SLS, materials, po Net Shaping: Proce UNIT V Three dimensional material system. Applications and decomposition, m manufacturing Text Books 1. Chua C.K Scientific 2. Andreas G References 1. Liou W. L	pplications. Working principle, process, strengths, ng, Solid Ground Curing, Laminated object manufa <b>POWDER BASED RAPID PROTO</b> Intering(SLS): Principle, process, Indirect and direct st processing, post curing, surface deviation and acce esses, materials, products, advantages, limitations a <b>OTHER RAPID PROTOTYPING</b> I Printing: Principle, basic process, Physics of 3DF Solid based, Liquid based and powder based case studies. Shape Deposition Manufacturing old SDM and applications. Selective Laser Mel ., Leong K.F., and Lim C.S., <b>"Rapid prototyping</b> Publishers, (2010) behardt, <b>"Rapid prototyping",</b> Hanser Gardener I 	weakned cturing TYPIN t SLS – curacy, A nd appli TECHI P, types 3DP sy g: Intro tting, El : Princi	Applicati cations – NOLOG of printin stems, s duction, ectron E ples and ions, (20	l applications udies EMS structures, mo ons – Laser Er Case Studies IES ng, process cap trength and v basic process Beam Melting Total Periods I applications 03)	vantages, of Fused 9 deling of ngineered 9 pabilities, veakness, ss, shape - Rapid : 45 ", World
limitations and ap deposition Modeli UNIT IV Selective Laser Sit SLS, materials, po Net Shaping: Proce UNIT V Three dimensional material system. Applications and decomposition, m manufacturing Text Books 1. Chua C.K Scientific 2. Andreas G References 1. Liou W. L prototype	polications. Working principle, process, strengths, ng, Solid Ground Curing, Laminated object manufa POWDER BASED RAPID PROTO Intering(SLS): Principle, process, Indirect and direct st processing, post curing, surface deviation and accesses, materials, products, advantages, limitations a OTHER RAPID PROTOTYPING I Printing: Principle, basic process, Physics of 3DF Solid based, Liquid based and powder based case studies. Shape Deposition Manufacturing old SDM and applications. Selective Laser Mel ., Leong K.F., and Lim C.S., "Rapid prototyping Publishers, (2010) Behardt, "Rapid prototyping", Hanser Gardener I Liou, Frank W. Liou, "Rapid Prototyping and En- development", CRC Press, (2007)	weakned cturing · TYPIN t SLS – curacy, A nd appli TECHI P, types 3DP sy g: Intro ting, El : Princi Publicat	Applicati cations – NOLOG of printin stems, s duction, ectron E ples and ions, (20	l applications udies EMS structures, mo ons – Laser Er Case Studies IES ng, process cap trength and v basic process Beam Melting Total Periods I applications 03) eations: A tool	vantages, of Fused 9 deling of ngineered 9 oabilities, veakness, ss, shape - Rapid : 45 ", World I box for
limitations and ap deposition Modelin UNIT IV Selective Laser Sir SLS, materials, po Net Shaping: Proce UNIT V Three dimensional material system. Applications and decomposition, m manufacturing Text Books 1. Chua C.K Scientific 2. Andreas C References 1. Liou W. L prototype 2. Ali K. Kar	pplications. Working principle, process, strengths, ng, Solid Ground Curing, Laminated object manufa POWDER BASED RAPID PROTO Intering(SLS): Principle, process, Indirect and direct st processing, post curing, surface deviation and accesses, materials, products, advantages, limitations a OTHER RAPID PROTOTYPING I Printing: Principle, basic process, Physics of 3DF Solid based, Liquid based and powder based case studies. Shape Deposition Manufacturing old SDM and applications. Selective Laser Mel ., Leong K.F., and Lim C.S., "Rapid prototyping Publishers, (2010) behardt, "Rapid prototyping", Hanser Gardener I tiou, Frank W. Liou, "Rapid Prototyping and En- development", CRC Press, (2007) nrani, Emad Abouel Nasr, "Rapid Prototyping: T	weakned cturing · TYPIN t SLS – curacy, A nd appli TECHI P, types 3DP sy g: Intro ting, El : Princi Publicat gineerin heory a	Applicati cations – NOLOG of printin stems, s duction, ectron E ples and ions, (20 ng applic nd pract	l applications udies EMS structures, mo ons – Laser Er Case Studies IES ng, process cap trength and v basic process Beam Melting Total Periods I applications 03) cations: A tool ice", Springer,	vantages, of Fused 9 deling of ngineered 9 pabilities, veakness, ss, shape – Rapid : 45 ", World 1 box for , (2006)
limitations and ap deposition Modelin UNIT IV Selective Laser Sir SLS, materials, po Net Shaping: Proce UNIT V Three dimensional material system. Applications and decomposition, m manufacturing Text Books 1. Chua C.K Scientific 2. Andreas G References 1. Liou W. L prototype 2. Ali K. Kar 3. Peter D.H	pplications. Working principle, process, strengths, ng, Solid Ground Curing, Laminated object manufa POWDER BASED RAPID PROTO Intering(SLS): Principle, process, Indirect and direct st processing, post curing, surface deviation and acce esses, materials, products, advantages, limitations a OTHER RAPID PROTOTYPING I Printing: Principle, basic process, Physics of 3DF Solid based, Liquid based and powder based case studies. Shape Deposition Manufacturing old SDM and applications. Selective Laser Mel ., Leong K.F., and Lim C.S., "Rapid prototyping Publishers, (2010) behardt, "Rapid prototyping", Hanser Gardener I Liou, Frank W. Liou, "Rapid Prototyping and En- development", CRC Press, (2007) mrani, Emad Abouel Nasr, "Rapid Prototyping: T Hilton Hilton/Jacobs, Paul F.Jacobs, "Rapid To	weakned cturing · TYPIN t SLS – curacy, A nd appli TECHI P, types 3DP sy g: Intro ting, El : Princi Publicat gineerin heory a	Applicati cations – NOLOG of printin stems, s duction, ectron E ples and ions, (20 ng applic nd pract	l applications udies EMS structures, mo ons – Laser Er Case Studies IES ng, process cap trength and v basic process Beam Melting Total Periods I applications 03) cations: A tool ice", Springer,	vantages, of Fused 9 deling of ngineered 9 pabilities, veakness, ss, shape – Rapid : 45 ", World 1 box for , (2006)
limitations and ap deposition Modelin UNIT IV Selective Laser Sir SLS, materials, po Net Shaping: Proce UNIT V Three dimensional material system. Applications and decomposition, m manufacturing Text Books 1. Chua C.K Scientific 2. Andreas G References 1. Liou W. L prototype 2. Ali K. Kar 3. Peter D.H Application	pplications. Working principle, process, strengths, ng, Solid Ground Curing, Laminated object manufa <b>POWDER BASED RAPID PROTO</b> ntering(SLS): Principle, process, Indirect and direc st processing, post curing, surface deviation and acc esses, materials, products, advantages, limitations a <b>OTHER RAPID PROTOTYPING</b> I Printing: Principle, basic process, Physics of 3DF Solid based, Liquid based and powder based case studies. Shape Deposition Manufacturing old SDM and applications. Selective Laser Mel ., Leong K.F., and Lim C.S., <b>"Rapid prototyping</b> Publishers, (2010) Behardt, <b>"Rapid prototyping"</b> , Hanser Gardener I Liou, Frank W. Liou, <b>"Rapid Prototyping and Eng</b> <b>development"</b> , CRC Press, (2007) mrani, Emad Abouel Nasr, <b>"Rapid Prototyping: T</b> filton Hilton/Jacobs, Paul F.Jacobs, <b>"Rapid To</b> <b>ons"</b> , CRC press, (2000)	weakned cturing TYPIN t SLS – curacy, A nd appli TECHI P, types 3DP sy g: Intro tring, El : Princi gineerin heory a poling:	Applicati cations – NOLOG of printin stems, s duction, ectron E ples and ions, (20 ng applic nd pract	l applications udies EMS structures, mo ons – Laser Er Case Studies IES ng, process cap trength and v basic process Beam Melting Total Periods l applications 03) eations: A tool logies and In	vantages, of Fused 9 deling of ngineered 9 pabilities, veakness, ss, shape – Rapid : 45 , World I box for , (2006) ndustrial
limitations and ap deposition Modelin UNIT IV Selective Laser Sin SLS, materials, po Net Shaping: Proce UNIT V Three dimensional material system. Applications and decomposition, m manufacturing Text Books 1. Chua C.K Scientific 2. Andreas G References 1. Liou W. L prototype 2. Ali K. Kar 3. Peter D.H Applicatio 4. Chee Kai	pplications. Working principle, process, strengths, ng, Solid Ground Curing, Laminated object manufa POWDER BASED RAPID PROTO Intering(SLS): Principle, process, Indirect and direct st processing, post curing, surface deviation and acce esses, materials, products, advantages, limitations a OTHER RAPID PROTOTYPING I Printing: Principle, basic process, Physics of 3DF Solid based, Liquid based and powder based case studies. Shape Deposition Manufacturing old SDM and applications. Selective Laser Mel ., Leong K.F., and Lim C.S., "Rapid prototyping Publishers, (2010) behardt, "Rapid prototyping", Hanser Gardener I Liou, Frank W. Liou, "Rapid Prototyping and En- development", CRC Press, (2007) mrani, Emad Abouel Nasr, "Rapid Prototyping: T Hilton Hilton/Jacobs, Paul F.Jacobs, "Rapid To	weakned cturing TYPIN t SLS – curacy, A nd appli TECHI P, types 3DP sy g: Intro tring, El : Princi gineerin heory a poling:	Applicati cations – NOLOG of printin stems, s duction, ectron E ples and ions, (20 ng applic nd pract	l applications udies EMS structures, mo ons – Laser Er Case Studies IES ng, process cap trength and v basic process Beam Melting Total Periods l applications 03) eations: A tool logies and In	vantages, of Fused 9 deling of ngineered 9 pabilities, veakness, ss, shape – Rapid : 45

Course Outcomes				ł	Progr	am O	utcor	nes (l	POs)				Program Specific Outcomes (PSOs)				
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	
CO1	1	3	1	2	3	2	1					1	1	2	2	3	
CO2	2	2	1	3	3	2	2					1	1	3	2	3	
CO3	1	2	1	3	3	2	3					1		2	3	2	
CO4	2	2	1	3	3	2	1					1		2	2	2	
CO5	1	2	1	3	3	2	1					1		2	2	2	
CO6	1	3	2	3	3	3	1					1		2	2	2	

<b>191MEEM</b>				P	OWI	ER P	LAN	NT E	NGI	NEE	RINO	j		]	L-T-P	С
															3-0-0	3
Programme:	I	B.E. 1	Mech	anica	al Eng	ginee	ring				Se	m:	7	Categ	ory:	PC
Prerequisites						-										
Aim:	]	Fo un			the va	ariou	s con	npone	ents,	operat	tions a	nd app	olicatio	ns of o	differen	t types of
Course Outcor			1													
The students wi		able	to													
CO1. Express t	he va	arious	s pow	ver pl	ants a	and b	oiler	s								
CO2. Identify t							liffere	ent ty	pes o	f cond	lenser					
CO3. Discuss the																
CO4. Select the																
CO5. List the a													bined c	cycle		
CO6. Compute											ver pla	ants				
INTRODUCT													~			9
Layout of Stean																
comparison and					ratior	n Cur	ves S	team	boile	ers and	d cycle	es – H1	gh pres	ssure a	ind Sup	er Critica
Boilers – Fluidi																
STEAM POW																9
Fuel and ash																
Electrostatic Pr																
power plant –					ne m	ateria	al - c	open	and	closed	d cycl	es – r	eheatır	ng – F	Regener	ation and
intercooling – c						T A NT	TO									
NUCLEAR AN									<u> </u>		D	· 1	4		וי ת	9
Nuclear Energy																
reactor, Waste d						Pow	er pla	int – I	Essen	tial el	ement	s, Sele	ction o	of turbi	nes, gov	/erning c
Turbines – Mici	•			•												
DIESEL AND																9
Types of diesel																
Pumped storage				l rece	eiver	syste	m, Pr	rincip	le of	worki	ng, W	ind end	ergy – 1	types -	- HAW	Г, VAW
<ul> <li>Tidal Energy,</li> </ul>				IIGG							0.10	DED	TION	10		
POWER PLAN																9
Fixed and opera																
plants and impa	ct on	n Env	ironn	nent -	– poli	utant	s and	l polli	ution	standa	ards –	Metho	_			
														Total	Period	s: 45
Text Books:																
1. Rajput									•	•			lication	n, (201	6)	
2. Nag P.I	K., "	Powe	er Pla	int Ei	ngine	ering	;", Та	ita M	cGra	w- Hi	ll, (20	14)				
References:																
1. EI-Wak							•									
2. Ramali	0		· ·				0	0	·			· · · ·	` '			
3. Nagpal																
4. Rai G.I	)., "I	Intro	duction	on to	Pow	er Pla	ant T	echno	ology	", Kh	anna l	Publisł	ners, (2	2009)		
Course				]	Progr	am O	utcoi	mes (l	POs)				Prog	-		Outcomes
Outcomes		1	1	1	-	1		` `	· ·	1	1	1		T	PSOs)	
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	2	2	2	2	1	1	2	1	<u> </u>			2	2	3		3
CO2	3	3	2	2		1	1	2	<u> </u>			2	2	3		2
CO3	2	2	2	3	2	2	2	2	2	1		2		3		2
CO4	3	2	2	2	2	3	2	2			2	2		3	[	2
C05	2	3	2	2	2	2	2	2	2	1	2	2	2	2		2

CO5

CO6

191MEEN	PROCESS PLANNING AND COST ES	STIMA	TION	N	L-T-P	С
					3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:		Cat	egory:	PE
Prerequisites:	Manufacturing Technology					
Aim:	To impart clear knowledge about process plannin time	g, costin	g and	estima	tion of n	nachining
<b>Course Outcome</b>	es:					
The students will b	e able to					
CO1. Demonstrate	the importance of Work study and Ergonomics					
CO2. Describe the	different approaches of Process Planning					
CO3. Illustrate man	nufacturing logic and knowledge					
CO4. Know the dif	fferent cost and its components					
CO5. Estimate the	cost in fabrication shops					

CO6. Find machining time calculation for different process

UNIT I	WORK STUDY AND ERGONOMICS	9
Method study - def	inition – objectives – motion economy – principles – Tools and Techniques – applica	ations –
work measurements	s – tools and techniques – standard time – ergonomics – principles – applications	
UNIT II	PROCESS PLANNING	9
Definition – object	ive – scope – approaches to process planning – Process planning activities – Finish	ed part
requirements - ope	erating sequences - machine selection - material selection parameters - docume	ents for
process planning -	developing manufacturing logic and knowledge – production time calculation	
UNIT III	COSTING AND ESTIMATION	9
Aims of costing and	d estimation – introduction to costs – cost accounting – classification of cost – elem	nents of
cost - types of est	imates - methods of estimates - data requirements and sources - collection of	cost –
allowances in estim	ation – depreciation – analysis of depreciation	
UNIT IV	ESTIMATION IN FABRICATION SHOPS	9
Estimation in found	dry shop - Pattern cost - Casting cost - Estimation in Forging shop - Losses in for	rging –
Forging cost – Estin	mation in welding shop – Gas cutting – Electric welding	
UNIT V	ESTIMATION OF MACHINING TIME AND COST	9
Estimation of mach	ining time for lathe operations – Estimation of machining time for drilling, boring, sl	haping,
planning, milling an	nd grinding operations	
	Total Periods:	45
Text Books		
1. Banga T.R	and Sharma S.C, "Estimating and Costing", Khanna publishers, New Delhi, (201)	2)
2. Khanna O.	P., "Industrial Engineering and Management", Dhanpat Rai & Sons, (2010)	
References		
1 Duggall D S	and Tailor, B.W, "Operations Management", PHI, (2008)	

- Russell R.S and Tailor, B.W, "Operations Management", PHI, (2008)
   Chitale A.V. and Gupta R.C., "Product Design and Manufacturing", PHI, (2003)
- Cliniale A. V. and Gupta R.C., Troubert Design and Wandacturing , TH, (2003)
   Tailor B., Willip F. Ostwalal and Jairo Munez, "Manufacturing Processes and Systems", John wiley, (1998)
- 4. Nadha Muni Reddy C., "Industrial Engineering and Management", New Age International (P) Limited, New Delhi, (2011)

Course Outcomes				F	Progra	am O	utcon	nes (P	POs)				Program Specific Outcomes (PSOs)				
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	
CO1					1					2	2		1	1		2	
CO2					1						2	1		1		2	
CO3							1	1		1	2		2	1		2	
CO4	1				1						2				1	2	
CO5	1										2	1		1		2	
CO6	1										2			1		2	

<b>191MEEO</b>	PRODUCTION PLANNING AND C	ONTR	OL		L-T-P	С
					3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:		C	Category:	PE
Prerequisites:	Manufacturing Technology					
Aim:	To realize the various components and functions production scheduling and inventory Control	s of proc	luct pl	anni	ing, process	planning,
<b>Course Outcom</b>	nes:					
The students will	be able to					
CO1. Familiarize	in production control and its development					
CO2. Understand	the concepts of work study and work measuremen	t				
CO3. Familiarize	the product planning and process planning					
	owledge in production scheduling					
CO5. Realize the	need of inventory control					
CO6. Know the re	ecent trends in PPC					

UNIT I	PRODUCTION CONTROL AND DEVELOPMENT	9
Objectives and bene	efits of planning and control - Functions of production control - Types of produ	iction –
	nt and design - Marketing, Functional, Operational, aesthetic, Durability and depen	dability
aspect – Profit const	deration – Standardization, Simplification & specialization – Break even analysis	
UNIT II	WORK STUDY AND WORK MEASUREMENT	9
	sic procedure - Selection - Recording of process - Critical analysis, Develop	
	Micro motion and memo motion study - work measurement - Techniques o	
measurement – Tim	he study – Production study – Work sampling – Predetermined motion time stand	lards
UNIT III	PRODUCT PLANNING AND PROCESS PLANNING	9
Product planning - I	Extending the original product information – Value analysis – Problems in lack of	product
planning – Process	planning and routing - Pre requisite information needed for process planning - S	Steps in
process planning -	Quantity determination in batch production – Machine capacity, balancing – Ana	lysis of
process capabilities	in a multi-product system	
UNIT IV	PRODUCTION SCHEDULING	9
Production Control	Systems - Loading and scheduling - Master Scheduling - Scheduling rules -	– Gantt
charts – Perpetual 1	oading – Basic scheduling problems – Line of balance – Flow production sched	luling –
Batch production so	cheduling – Product sequencing – Production Control systems – Periodic batch	control
- Dispatching - Pr	ogress reporting and expediting - Manufacturing lead time - Techniques for a	ligning
completion times an	nd due dates	
UNIT V	INVENTORY CONTROL AND RECENT TRENDS IN PPC	9
	Purpose of holding stock - Effect of demand on inventories - Ordering procedures	
	ng cycle system - Determination of Economic order quantity and economic lot size	- ABC
analysis - Recorder	procedure – Introduction to computer integrated production planning systems	_
	Total Periods:	45
Text Books		
1. Martand T	elsang, "Industrial Engineering and Production Management", S. Cha	nd and
Company, (	(2006)	
2. James B. I	Dilworth, "Operations Management: Providing Value in Goods and Ser	vices",
Dryden Pre	ss, (2000)	
References		
	yay S.K., "Production Planning Control, Text and Cases", PHI Publishers, (20	
2. Mahajan M	I., "Industrial Engineering and Production Management", Dhanpat Rai Pu	blisher,
(2010)		
3. Elwood S.		
T 1' 1'.'	Buffa, and Rakesh K. Sarin, "Modern Production/Operations Management"	, Wiley
	Buffa, and Rakesh K. Sarin, <b>"Modern Production/Operations Management"</b> n, (2009) edi, <b>"Production and Operations management",</b> Oxford university press, Edition	•

4. Kanishka Bedi, "Production and Operations management", Oxford university press, Edition (2016)

Course Outcomes				F	Progra	am O	utcon	nes (P	POs)				Program Specific Outcomes (PSOs)				
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	
CO1					1					2	2		1	1		2	
CO2					1						2	1		1		2	
CO3							1	1		1	2		2	1		2	
CO4	1				1						2				1	2	
CO5	1										2	1		1		2	
CO6	1										2			1		2	

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<b>191MEEP</b>	REFRIGERATION AND AIR COND	ITION	ING		L-T-P	С
					3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:		Ca	ategory:	PE
Prerequisites:	Engineering Thermodynamics					
Aim:	To provide knowledge on various refrigeration Refrigeration and Air conditioning systems	n cycles	, com	pone	nts, refrig	erants and
The students will	be able to					
CO1. Construct t	he fundamentals of air conditioning & refrigeration	n cycle a	and C.	O.P.		
CO2. Distinguish	the types of compressor and classifications of refi	rigerants	5			
CO3. Relate the	psychrometric processes using psychrometric chart	ts				
CO4. Analyze th	e performance of summer and window air conditio	ning				
CO5. Calculate t	he cooling load of air conditioning system	-				
	the duct design using friction method, air quality co	oncept a	ind app	olicat	tion about	the storage

#### **REFRIGERATION CYCLE**

Review of thermodynamic principles of refrigeration - Air Refrigeration cycles - Carnot refrigeration cycle -Vapour compression refrigeration cycle – use of P.H. charts – multistage compression and multiple evaporator systems - cascade system - COP comparison

#### UNIT II

UNIT I

#### **REFRIGERANTS AND SYSTEM COMPONENTS**

Refrigerants – properties – selection of refrigerants, Alternate Refrigerants, Cycling controls – Compressors - reciprocating and rotary (elementary treatment), Types of condensers, evaporators, cooling towers -Functional aspects

#### **PSYCHROMETRY**

Psychrometric processes use of psychrometric charts – Grand and Room Sensible Heat Factors – bypass factor - air washers, Cooling load calculation of air conditioning system

UNIT IV

**UNIT III** 

#### **AIR CONDITIONING SYSTEMS**

Comfort air conditioning – summer and Winter Air conditioning – working principles of centralized air conditioning systems, Split, Ductable split, Packaged Air conditioning, VAV & VRV Systems - Duct Design by equal friction method, Indoor Air quality concepts - Environmental effects UNIT V 9

## **UNCONVENTIONAL REFRIGERATION CYCLES**

Vapour Absorption system – Ejector jet, Steam jet refrigeration and thermo electric refrigeration – Applications - ice plant - food storage plants - milk - chilling plants - petroleum refineries

> **Total Periods:** 45

#### **Text Books**

Khurmi R.S. & Gupta J.K., "Refrigeration and Air Conditioning", S.Chand Publication, (2009) 1.

2. Arora C.P., "Refrigeration and Air Conditioning", Tata McGraw Hill, New Delhi, (2008)

#### References

- Roy J. Dossat, "Principles of Refrigeration", Pearson Education, (2007) 1.
- Jordon and Priester, "Refrigeration and Air Conditioning", Prentice Hall of India Pvt. Ltd., New 2. Delhi, (2015)
- Stoecker N.F. and Jones, "Refrigeration and Air Conditioning", TMH, New Delhi, (2011) 3.
- Jones, "Air Conditioning Engineering", Edward Amold Publication (2010) 4

Course Outcomes				I		Program Specific Outcomes (PSOs)									
Outcomes	PO1							PO11	PO12	PSO1	PSO2	PSO3	PSO4		
CO1	3	1	3	1		2	2				2	2	2		2
CO2	3	1	2	1		2	2				2	2	2		2
CO3	3	2	1	3		2	2				1	2	2		2
CO4	3	2	3	2		2	2				2	2	2		2
CO5	3	2	3	2		2	2				2	2	2		2
CO6	3	1	3	1		2	2				2	2	2		2

191MEEQ	WELDING TECH	NOLOGY		L-T-P	С
				3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:	Cate	gory:	PE
Prerequisites:	Manufacturing Processes				
Aim:	To learn the concepts of metal joining an	nd inspection			
<b>Course Outcome</b>	es:				
The students will b	e able to				
CO1. Understand t	he basic concepts, working principles of w	relding			
CO2. Know the sp	ecial welding processes				
CO3. Learn differe	nt welding methods and its applications				
CO4. Acquire know	wledge about welding automation				
CO5. Examine the	welding defects				
CO6. Learn destrue	ctive, non-destructive testing and inspectio	n of welded joints			

UNIT I BASICS AND PRINCIPLES OF WELDING PROCESS	9
Welding - weldability - classification of welding - types of weld joints - weld position - edge preparation	on – fluxes
- filler - safety aspects in welding - gas welding - arc welding - electrode: types, selection - coding	- welding
symbols	-
UNIT II SPECIAL WELDING PROCESSES	9
Shielded metal arc welding, GTAW, GMAW, SAW, Resistance welding (spot, seam, projection, percus	sion, flash
types) – atomic hydrogen arc welding – Thermit welding	
UNIT III ADVANCED WELDING PROCESSES	9
Electron beam and Laser beam welding - plasma arc welding - stud welding - friction welding - explosive	ve welding
- ultrasonic welding - welding of plastics - brazing and soldering - welding of Aluminum, Copper	
UNIT IV AUTOMATED WELDING	9
Automation - welding automation - welding operation, structure analysis - classification of welding automation	comation –
Introduction to welding robots - robotic welding system - types of welding robots - Robot selection m	echanics –
Design of welding robots – Joint tracking system – welding fixtures	
UNIT V WELD DEFECTS AND INSPECTION AND TESTING OF WELDING	9
Weld defect - Surface defects, subsurface defect - Sources of weld defect - Introduction to inspection and	l testing of
welds - Types of testing & inspection: Visual inspection and measurement, Destructive Testing - Ten	sile Tests,
Impact Tests, Bend Tests, Break Tests, Etch Tests - Non-Destructive Testing - Liquid Penetrant Testing	, Magnetic
Particle Testing, Eddy Current Testing, Radio Graphic Testing, Magneto Graphic Testing, Ultrosonic	Testing -
Acceptance levels of arc welding defects	
Total Periods	: 45
Text Books	
1. Little, "Welding technology", Tata McGraw Hill Publishing Company Pvt. Ltd., New Delhi, (20	)04)
2. Khanna O.P., "A text book of Welding Technology", Dhanpat rai publications, New Delhi, (200	)2)
References	
1. Parmer R.S., "Welding Engineering & Technology", Khanna Publishers, New Delhi, (2008)	
2. Baldev Raj, V. Shankar, A. K. Bhaduri, "Welding Technology for Engineers", Alpha Science Int	ernational,
USA, (2006)	
3. Rizvi S.A., "Advanced Welding Technology", S. K. Kataria & Sons, New Delhi, (2010)	

 William A. Bowditch, Kevin E. Bowditch, Mark A. Bowditch, "Welding Technology Fundamentals", Goodheart Willcox Publisher, USA, (2009)

Course Outcomes				ł	Progr	am O	utcor	nes (l	POs)				Program Specific Outcomes (PSOs)				
Outcomes				PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	
C01	3		2			2	1		2			3				3	
CO2	3		2			2	1		2			3				3	
CO3	3		1			2	1		2			2				3	
CO4	3		1			2	1		2			2				3	
CO5	3		1			2	1		2			2				3	
CO6	3		1			2	1		2			2				3	

# **OPEN ELECTIVES**

9

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1910E6A	MAINTENANCE ENGINEER	ING		L-T-P	С
	·			3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:		Category:	OE
Prerequisites:	Nil				
Aim:	To understand the principles, functions and practi management of maintenance activities	ices adap	ted in	industry for the	successful
<b>Course Outcon</b>	ies:				
The students will	be able to				
CO1. Know the	principles of maintenance planning				
CO2. Gain know	ledge in maintenance organization and economics				
CO3. Understan	d the maintenance policies - preventive maintenan	ice			
CO4. Familiariz	e the condition monitoring				
CO5. Identify th	e repair methods for basic machine elements				
CO6 Understan	d the repair methods for material handling equipme	ent			

CO6. Understand the repair methods for material handling equipment

#### UNIT I PRINCIPLES AND PRACTICES OF MAINTENANCE PLANNING 9

Basic Principles of maintenance planning - Objectives and principles of planned maintenance activity -Importance and benefits of sound Maintenance systems - Reliability and machine availability - MTBF, MTTR and MWT - Factors of availability - Maintenance organization - Maintenance economics

#### UNIT II MAINTENANCE POLICIES-PREVENTIVE MAINTENANCE

categories – Comparative category - Preventive maintenance, Maintenance merits of each maintenance schedules, repair cycle - Principles and methods of lubrication - TPM

#### UNIT III

#### **CONDITION MONITORING**

Condition Monitoring - Cost comparison with and without CM - On-load testing and off- load testing -Methods and instruments for CM - Temperature sensitive tapes - Pistol thermometers - wear-debris analysis

#### **UNIT IV**

#### **REPAIR METHODS FOR BASIC MACHINE ELEMENTS**

Repair methods for beds, slideways, spindles, gears, lead screws and bearings – Failure analysis – Failures and their development – Logical fault location methods – Sequential fault location

#### UNIT V

#### **REPAIR METHODS FOR MATERIAL HANDLING EQUIPMENT**

Repair methods for Material handling equipment - Equipment records - Job order systems - Use of computers in maintenance **Total Periods:** 45

#### **Text Books**

- 1. Srivastava S.K., "Industrial Maintenance Management", S. Chand and Co., (2018)
- Bhattacharya S.N., "Installation, Servicing and Maintenance", S. Chand and Co., (2017) 2.

#### References

- 1. White E.N., "Maintenance Planning", Gower Press, (1979)
- 2. Garg M.R., "Industrial Maintenance", S. Chand & Co., (1986)
- 3. Higgins L.R., "Maintenance Engineering Hand book", McGraw Hill, (1988)
- 4. Davies, "Handbook of Condition Monitoring", Chapman & Hall, (1996)

Course Outcomes				ł		Program Specific Outcomes (PSOs)										
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
C01	3	3	3	1	2	2	2	2	1	3		2		2		2
CO2		2	2	3	1	1	2	1	1	2	2	2		2		2
CO3	1	2	2	2	2	2	2	2	2		2	2	1	2		2
CO4	1	3	2	2	2		1	2	2	1		2	1	2		2
CO5	1	3	2	2	2	2	2		2			2	1	2		2
CO6	2	3	2	3	3				3	2		2		2	2	2

1910E6B	NON-DESTRUCTIVE TESTING AND N	MATEI	RIAL	S	L-T-P	С
					3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:		C	Category:	OE
Prerequisites:	Nil					
Aim:	To study and understand the various Non-Destru	uctive E	valuat	ion	and Testing	methods,
Am:	theory and their industrial applications				_	
<b>Course Outcom</b>	les:					
The students will	be able to					
CO1. Differentia	te various defect types and select the appropriate N	JDT met	hods f	for b	etter evaluat	tion
CO2. Explain bas	sic knowledge of surface NDE techniques					
CO3. Handle var	ious inspection instrument with established proced	lures				
CO4. Demonstra	te their understanding of non-destructive testing pr	rinciples				
CO5. have a basi	c knowledge of ultrasonic testing which enables th	iem to pe	erform	ins	pection of sa	amples
	adiographic testing, interpretation and evaluation	•			^	-

UNIT I	OVERVIEW OF NDT	9
	Non-Destructive Testing NDT Versus Mechanical testing, Methods for the detec	
e	ects as well as material characterization, Relative merits and limitations, Various p materials and their applications in NDT., Visual inspection	nysicai
UNIT II	SURFACE NDE METHODS	9
limitations of varie Theory of magnet	esting – Principles, types and properties of liquid penetrants, developers, advantagous methods, Testing Procedure, Interpretation of results – Magnetic Particle Te ism, inspection materials Magnetization methods, Interpretation and evaluation les and methods of demagnetization, Residual magnetism	sting –
UNIT III	THERMOGRAPHY AND EDDY CURRENT TESTING	9
applications - Eddy	es and limitation – infrared radiation and infrared detectors, Instrumentations and m v Current Testing – Generation of eddy currents, Properties of eddy currents, Eddy Probes, Instrumentation, Types of arrangement, Applications, advantages, Limi- uation	current
UNIT IV	ULTRASONIC TESTING AND ACOUSTIC EMISSION	9
÷	- Principle, Transducers, transmission and pulse-echo method, straight beam and	•
	tion, data representation, A/Scan, B-scan, C-scan - Phased Array Ultrasound, T	ime of
Flight Diffraction -	- Acoustic Emission Technique-Principle, AE parameters, Applications	
UNIT V	RADIOGRAPHY	9
and screens, geom contrast, character	on of X-Ray with matter, imaging, film and film less techniques, types and use of etric factors, Inverse square, law, characteristics of films – graininess, density, istic curves, Penetrameters, Exposure charts, Radiographic equivalence. Fluoro Computed Radiography, Computed Tomography	speed,
	Total Periods:	45
Text Books		
Publishing	j, Jayakumar T., Thavasimuthu M., <b>"Practical Non Destructive Testing",</b> House, (2009) sh, <b>"Non Destructive Testing Techniques",</b> New Age International Publishers, (	
References	sii, Non Destructive resting rechniques, New Age international rubisners, (	2010)
<ol> <li>Gnanaguru Chennai, (2</li> <li>Paul E. Mi</li> </ol>	R. and Hari Balaji V., <b>"Non Destructive Testing and Materials",</b> Sams Pub 2016) x, <b>"Introduction to Non Destructive testing: a training guide",</b> Wiley, (2005)	lishers, 2001)

Course Outcom					Prog	gram O	utcom	es (POs	5)				Progr	Program Specific Outcomes (PSOs)						
es	РО 1	PO 2	PO 3	PO 4	PO 5	PO 6	<b>PO</b> 7	PO 8	PO 9	PO1 0	PO1 1	PO1 2	PSO 1	PSO 2	PSO 3	PSO 4				
CO1	3		2	2	2	2	1		2	2	1			2	2	3				
CO2	2	1	2		2	2	2		2	1			2	1		3				
CO3	2			1	2	1	2		2						2	3				
CO4	2	3	2	1	2				1		2	3	2			3				
CO5	3	2	1	1			2	1	1		3		3	2		3				
CO6		3	2	1	1		2	2		3	2	1		2	2	3				

1910E6C	<b>OPERATIONS RESEARCH AND</b>	MANAG	EMI	ENT	L-T-P	С
	•				3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:			Category:	OE
Prerequisites:	Nil					
Aim:	To understand the various techniques of operations research techniques for industria				zation of res	ources,
<b>Course Outcome</b>	s:					
The students will be	e able to					
CO1. Gain knowled	lge on Operations Research for industrial solu	utions				
CO2. Apply L.P.P.	in industrial optimization problems					
CO3. Solve transpo	rtation problems using various OR methods					
CO4. Solve assignm	nent problems using various algorithms					
CO5. Analyze the s	hortest route and critical path in a network					
COC A DI OD	1 1 1 1 1					

CO6. Apply OR methods in replacement strategy

UNIT	I LINEAR MODELS	9
	of Operations Research - The phases of O.R - Applications - Linear Programming: Formu	lation –
Graphi	cal method – Simplex method – Artificial Variable techniques: Big M Method	
UNIT		9
	ortation Problems: Optimal solution by North West corner method – Vogel's Approximation n cost method – MODI method	nethod –
UNIT		9
0	ment Problems: Formulation – Unbalanced Assignment Problem – Hungarian algorithm – T aan Problem	raveling
UNIT	IV NETWORK MODELS	9
	rk models – Shortest route – Minimal spanning tree – Maximum flow models – Project networ nd PERT networks – Critical path scheduling	ς —
UNIT	V REPLACEMENT MODELS	9
& not of Text B	changing with time – Optimum replacement policy: Individual & Group replacement Total Periods:	45
		11 · 1 oth
	Hamdy A. Taha, <b>"Operations Research - An Introduction"</b> , Pearson Publications., New De Edition (2017) Natarajan A.M., Balasubramani P., Tamilarasi A., <b>"Operations Research"</b> , Pearson Publi New Delhi, 2 nd Edition (2014)	
Refere		
2. 3.	Ravindran A., Phillips Don T., Solberg James J., <b>"Operations Research: Principles and Pr</b> John Wiley & Sons, New Delhi, 2 nd Edition (2011) Panneerselvam R., <b>"Operations Research"</b> , Prentice Hall of India., New Delhi, 2 nd Edition ( Prem Kumar Gupta and Hira D.S., <b>"Introduction to Operations Research"</b> , S. Chand and C Delhi, 1 st Edition (2012) Frederick S. Hillier, Gerald J. Lieberman, Bodhibrata Nag, Preetam Basu, <b>"Operations Re</b>	2010) So., New
	<b>Concepts and Cases",</b> Tata McGraw-Hill Publishing Company Pvt. Ltd., New Delhi, 7 th (2017)	

Course Outcomes					Program Specific Outcomes (PSOs)											
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1	2	3		3	1						3	2	3	2	2	3
CO2	2	3		3	1						3	2	3	2	2	3
CO3	2	3		3	1						3	2	3	2	2	3
CO4	2	3		3	1						3	2	3	2	2	3
CO5	2	3		3	1						3	2	3	2	2	3
CO6	2	3		3	1						3	2	3	2	2	3

1910E6D	RENEWABLE SOURCES OF E	NERG	Y		L-T-P	С
					3-0-0	3
<b>Programme:</b>	B.E. Mechanical Engineering	Sem:		C	ategory:	OE
Prerequisites:	Nil					
Aim:	To study the renewable energy resources ar environmental merits	nd its e	conomi	cs of	the utilization	ation and
<b>Course Outcom</b>	es:					
The students will b	be able to					
CO1. Clarify the d	lifferent renewable energy sources and its application	ons				
CO2. Explain the	wind energy systems with hybrid systems					
CO3. Group the bi	o energy sources and its environmental merits					
CO4. Illustrate the	various power plants and their environmental issu	es				
CO5. Propose the	new power generation systems					
CO6. Do research	in fuel cells					

UNIT I SOLAR ENERGY	9
Solar Radiation - Measurements of solar Radiation and sunshine - Solar Thermal Collectors - F	lat Plate and
Concentrating Collectors - Solar Applications - fundamentals of photo Voltaic Conversion - sola	ur Cells – PV
Systems – PV Applications	
UNIT II WIND ENERGY	9
Wind Data and Energy Estimation - wind Energy Conversion Systems - Wind Energy gener	ators and its
performance – Wind Energy Storage – Applications – Hybrid systems	
UNIT III BIO – ENERGY	9
Biomass, Biogas, Source, Composition, Technology for utilization - Biomass direct combustion	on – Biomass
gasifier – Biogas plant – Digesters – Ethanol production – Bio diesel production and economics	
UNIT IV OTEC, TODAL, GEOTHERMAL AND HYDEL ENERGY	9
Tidal energy - Wave energy - Data, Technology options - Open and closed OTEC Cycles -	Smallhydro,
turbines – Geothermal energy sources, power plant and environmental issues	
UNIT V NEW ENERGY SOURCES	9
Hydrogen, generation, storage, transport and utilization, Applications: power generation, transport	– Fuel cells –
technologies, types – economics and the power generation	
Total Periods:	45
Text Books	
1. Gupta A., "Non-Conventional Energy Resources", Umesh Publication, (2012)	
2. Rai G.D., "Non-Conventional Sources of Energy", Khanna Publisher, New Delhi, (200	)9)
References	
1. Godfrey Boyle, "Renewable Energy, Power for a Sustainable Future", Oxford University	Press, U.K.,
(2000)	

2. Twidell J.W. & Weir A., "Renewable Energy Sources", EFN Spon Ltd., UK, (1986)

- 3. Tiwari G.N., "Solar Energy Fundamentals Design, Modelling and applications", Narosa Publishing House, New Delhi, (2002)
- 4. Freris L.L., "Wind Energy Conversion systems", Prentice Hall, UK, (2002)

Course Outcomes				I	Progr	am O	utcor	nes (l	POs)				Program Specific Outcomes (PSOs)					
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4		
CO1		2			3	2	3	2		2	3	3	2	2	2			
CO2	2	2	2	2	3	3	3	2		2	3	3	2	3	3	2		
CO3			1				3	3		3	3	3		3				
CO4	3		2			3	3	3		2	2	3	1	2		3		
CO5	2		2	3	2	2	3	3	2	2	3	3	2	2		1		
CO6	1	2	2	3		2		2	3	3	2	2	2	2		3		

191OE6E	ROBOTICS			L-T-P	С
				3-0-0	3
Programme:	B.E. Mechanical Engineering	Sem:		Category:	OE
Prerequisites:	Nil				
Aim:	To understand the basic concepts associated applications of Robots and robot programming	with th	e desig	n and function	ning and
Course Outcom					
CO2. Define robo CO3. Identify the CO4. Know the in CO5. Demonstrate	be able to robot anatomy, robot parts and functions t drive systems and end effectors concept of sensors and actuators mage processing and analysis for inspection and id e the robot kinematics and programming principle e implementation and robot economics			bl	
UNIT I	FUNDAMENTALS OF ROBOT	1			9
Specifications - Pi	n – Robot Anatomy – Co-ordinate Systems, Wo itch, Yaw, Roll, Joint Notations, Speed of Motion, Different Applications ROBOT DRIVE SYSTEMS AND E	Pay Loa	id – Rob	ot Parts and Fu	
	<b>NUDUI DRIVE SISIENIS AND E</b>	AND EFI	LUIU	NO	<u> </u>
UNIT III Requirements of a Encoders, Pneuma Approach, Time o Capacitive, Ultraso Slip Sensors – Ca	SENSORS AND MACHIN a sensor – Position of sensors (Piezo Electric atic Position Sensors), Range Sensors (Triang of Flight Range Finders, Laser Range Meters), I onic and Optical Proximity Sensors), Touch Sensor amera, Frame Grabber, Sensing and Digitizing In Techniques – Image Processing and Analysis – Al	c Senso gulation Proximity ors, Wris mage Da	r, LVD Principl y Sensors st Sensor uta – Sig	e, Structured, s (Inductive, Ha rs, Compliance gnal Conversio	Lighting all Effect Sensors
UNIT IV	ROBOT KINEMATICS AND ROBOT	r prog	RAMM	ING	9
Reverse Kinemati 3 Dimensional) – Robot programm	ics, Inverse Kinematics and Differences – DH cs of Manipulators with Two, Three Degrees of Deviations and Problems – Teach Pendant Prog ing Languages – VAL Programming – Motior ls, and Simple programs	Freedon grammin	n, Four I g, Lead	Degrees of Free through progr	edom (In amming
UNIT V	IMPLEMENTATION AND ROBOT	ECON	OMICS		9
	plementation of Robots in Industries – Various S omic Analysis of Robots – Pay back Method, EU				
			Г	<b>Sotal Periods:</b>	45
Text Books					
Hill, (200 2. Fu K.S., C	M.P., <b>"Industrial Robotics–Technology, Progr</b> 1) Gonzalz R.C., and Lee C.S.G., <b>"Robotics Contro</b> Hill Book Co. (1987)	_	_		

McGraw-Hill Book Co., (1987)

#### References

- 1. Deb S.R., "Robotics Technology and Flexible Automation", Tata McGraw-Hill Publication, (2008)
- 2. Yoram Koren, "Robotics for Engineers", McGraw-Hill Book Co., (1992)
- 3. Janakiraman P.A., "Robotics and Image Processing", Tata McGraw-Hill, (1995)
- 4. Saha S., "Introduction to Robotics", Tata McGraw-Hill Publication, (2008)

Course Outcomes				I	Progr	am O	utcor	nes (l	POs)				Program Specific Outcomes (PSOs)					
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4		
CO1	3	1	3	1		2	2					2	2	2		2		
CO2	3	1	2	1		2	2					2	2	2		2		
CO3	3	2	1	3		2	2					1	2	2		2		
CO4	3	2	3	2		2	2					2	2	2		2		
CO5	3	2	3	2		2	2					2	2	2		2		
CO6	3	1	3	1		2	2					2	2	2		2		

# **Mandatory Courses**

191	MC01	DESIGN THINKING	G	L	Т	Р	C
				2	0	0	0
Progr	amme:	B.E., / B. Tech		Ca	atego	ory:	MC
Aim:		t knowledge on design thinking process for ur ills to analyze design thinking issues and appl					rovide
Cours	e Outcom	es: Students will be able to					
CO1.	Demonstr	ate knowledge of design thinking process					
CO2.		sign thinking techniques to design relevant pro-					
CO3.		man centered design (HCD) methodology for					
CO4.		ion techniques for developing innovative prod					
CO5.		he causes for the problems in the design of pr					
CO6.	Perform t	he steps to gain practical knowledge of protot UNIT-I OVERVIEW OF DESIGN THINI			l <b>.</b>		
		UNIT-I OVERVIEW OF DESIGN THINK	KING PROC	.E88			6
vs Desi tools. H	gn thinking Iuman-Cer	sign thinking: Definition, Origin of design thi g, Problem solving, Understanding design thin ttered Design (HCD) process - Empathize, De ze, Solve and Test.	nking and its	process model,	Desi	ign th	inking
		UNIT-II EMPATHIZE					6
	to be done ve questior	prior to empathy mapping, creation of user points UNIT-III SOLVE / IDEAT		omer journey m	appı	ng, H	low 6
		ng, metaphors for ideation, CREATE and Wh		ideation, introd	luctio	on to '	-
		UNIT-IV ANALYZE / DEFI	NE				6
		is, conflict of interest, perspective analysis, bing through function modeling.	ig picture thin	nking through s	ysten	n ope	rator,
		UNIT-V TEST (PROTOTYPING AND	VALIDATIC	DN)			6
Prototy present		mptions during the design thinking process, V	alidation in t	he market, best	t prac	ctices	of
				Total	Peri	ods	30
Refere	nces						
1. 2.	Karl T. U	Ramadurai, "Karmic Design Thinking", First I Irich, "Design Creation of Artifacts in Society , USA, 2011					sylvan

Course Outcomes				P	rograi	mme (	Dutco	mes (F	POs)				Programme Specific Outcomes (PSOs)				
Outcomes	PO1													PSO2	PSO3	PSO4	
CO1	1	2	2		2		1	2	1	1	2	1		2			
CO2		1	2		1		2	1	1	1	1	1		1			
CO3			1				1		2					1			
CO4		2	2		2				2		2			1			
CO5	1		2			1		1		1		1		2			
CO6	1		2		1		2			1	1			1			

191MC02	ESSENCE OF INDIAN TRADITIONAL	т	т	р	C	
	KNOWLEDGE	L	1	r	C	

			2	0	0	0
Progra	amme:	B.E., / B. Tech	C	itego	rv:	MC
0		te the students with the concepts of Indian traditional knowledge and		0	÷	
Aim:		d the Importance of roots of knowledge system.				
Cours		es: Students will be able to				
		e concept of Traditional knowledge and its importance				
		e need and importance of protecting traditional knowledge.				
		the various enactments related to the protection of traditional knowled	doe			
		he concepts of Intellectual property to protect the traditional knowled	-			
	-	ine concepts of interfectual property to protect the industribut knowled ine importance of conservation and sustainable development of enviro	-	nt		
	-	ie importance of Traditional knowledge in Agriculture and Medicine.				
0.00	-	NIT-I INTRODUCTION TO TRADITIONAL KNOWLEDGE	•			6
Define		knowledge, nature and characteristics, scope and importance, kinds o	ftra	dition	nal	U
		ysical and social contexts in which traditional knowledge develop, th				nact of
	•	aditional knowledge systems. Indigenous Knowledge (IK), character				
	-	is indigenous knowledge, traditional knowledge Vs western knowled				iui
		is formal knowledge	.50 11	uunti	Jilui	
	6	NIT-II PROTECTION OF TRADITIONAL KNOWLEDGE				6
The nee		cting traditional knowledge Significance of TK Protection, value of	ГК і	ı glol	pal	Ū
	-	Government to harness TK.		- 8		
		II LEGAL FRAME WORK AND TRADITIONAL KNOWLED	<b>FE</b>			6
The Scl		bes and Other Traditional Forest Dwellers (Recognition of Forest Rig		• •	200	•
			ents	Act.	2006	o. Plant
			gnts)	Act,	2006	, Plant
Varietie	es Protecti	n and Farmer's Rights Act, 2001 (PPVFR Act);				
Varietie The Bio	es Protecti plogical D	n and Farmer's Rights Act, 2001 (PPVFR Act); versity Act 2002 and Rules 2004, the protection of traditional knowled				
Varietie The Bio Geogra	es Protecti plogical D phical ind	on and Farmer's Rights Act, 2001 (PPVFR Act); versity Act 2002 and Rules 2004, the protection of traditional knowle cators act 2003.	edge	bill, 2		
Varietie The Bio Geogra	es Protecti plogical D phical ind UNIT-IV	on and Farmer's Rights Act, 2001 (PPVFR Act); versity Act 2002 and Rules 2004, the protection of traditional knowle cators act 2003. <b>RADITIONAL KNOWLEDGE AND INTELLECTUAL PROPI</b>	edge E <b>RT</b>	bill, 2 Y	2016.	6
Varietie The Bio Geogra U System	es Protecti ological D phical ind UNIT-IV	on and Farmer's Rights Act, 2001 (PPVFR Act); versity Act 2002 and Rules 2004, the protection of traditional knowle cators act 2003. <b>TRADITIONAL KNOWLEDGE AND INTELLECTUAL PROPI</b> onal knowledge protection, Legal concepts for the protection of tradit	edge E <b>RT</b> iona	bill, 2 Y knov	2016.	6
Varietie The Bio Geogra U System Certain	es Protecti ological D phical ind UNIT-IV s of traditi non IPR 1	n and Farmer's Rights Act, 2001 (PPVFR Act); versity Act 2002 and Rules 2004, the protection of traditional knowled cators act 2003. <b>RADITIONAL KNOWLEDGE AND INTELLECTUAL PROPI</b> onal knowledge protection, Legal concepts for the protection of tradit nechanisms of traditional knowledge protection, Patents and traditional	edge E <b>RT</b> iona al kn	bill, 2 Y knov	2016. wledg	<b>6</b> ge,
Varietie The Bio Geogra U System Certain Strategi	es Protecti ological D phical ind UNIT-IV s of traditi non IPR 1 ies to incre	on and Farmer's Rights Act, 2001 (PPVFR Act); versity Act 2002 and Rules 2004, the protection of traditional knowle cators act 2003. <b>TRADITIONAL KNOWLEDGE AND INTELLECTUAL PROPI</b> onal knowledge protection, Legal concepts for the protection of tradit	edge E <b>RT</b> iona al kn	bill, 2 Y knov	2016. wledg	<b>6</b> ge,
Varietie The Bio Geogra U System Certain Strategi	es Protecti ological D phical ind UNIT-IV s of traditi non IPR 1 ies to incre Traditiona	on and Farmer's Rights Act, 2001 (PPVFR Act); versity Act 2002 and Rules 2004, the protection of traditional knowled cators act 2003. <b>TRADITIONAL KNOWLEDGE AND INTELLECTUAL PROPI</b> onal knowledge protection, Legal concepts for the protection of tradit nechanisms of traditional knowledge protection, Patents and traditional ase protection of traditional knowledge, global legal FORA for increa	E <b>RT</b> iona al kn using	bill, 2 Y knov	2016. wledg	<b>6</b> ge,
Varietie The Bio Geogra U System Certain Strategi Indian	es Protecti ological D phical ind JNIT-IV s of traditi non IPR 1 ies to incre Traditiona UNIT	n and Farmer's Rights Act, 2001 (PPVFR Act); versity Act 2002 and Rules 2004, the protection of traditional knowled cators act 2003. <b>RADITIONAL KNOWLEDGE AND INTELLECTUAL PROPI</b> onal knowledge protection, Legal concepts for the protection of tradit techanisms of traditional knowledge protection, Patents and traditional ase protection of traditional knowledge, global legal FORA for increa Knowledge.	edge E <b>RT</b> iona al kn asing	bill, 2 Y knov owle prote	2016. wledg dge, ection	6 ge, 1 of
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Course Outcomes		Programme Outcomes (POs)											Programme Specific Outcomes (PSOs)			
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1				1												

CO2		2						
CO3		1						
CO4		1						
CO5		1						
CO6		1						

191	MC03	C03INDIAN CONSTITUTIONLTP								
					2	0	0	0		
Programme:         B.E., / B. Tech         Category:										
Aim:	To understand the importance of Indian constitution, Administration, Concept and Development of									
Ann.	Human Rights, election commission.									
Course Outcomes: Students will be able to										

	regulation 201
CO1. Know the sources, features and principles of Indian Constitution.	
CO2. Learn about Union Government and its administration.	
CO3. Learn about State government and its administration.	
CO4. Get acquainted with Local administration and Panchayat Raj	
<b>CO5.</b> Be aware of basic concepts and developments of Human Rights.	
<b>CO6.</b> Gain knowledge on roles and functioning of Election Commission.	
UNIT-I INTRODUCTION TO INDIAN CONSTITUTION	6
Constitution' meaning of the term, Indian Constitution- Sources and constitutional history.	
Citizenship, Preamble, Fundamental Rights and Duties, Directive Principles of State Polic	
UNIT-II UNION GOVERNMENT AND STATE GOVERNMENT	6
Union Government and its Administration Structure of the Indian Union: Federalism, C	-
relationship, President: Role, power and position, PM and Council of ministers, Cabinet ar	
Secretariat, Lok Sabha, Rajya Sabha, The Supreme Court and High Court: Powers and Fu	
State Government and its Administration	ictions,
Governor: Role and Position, CM and Council of ministers, State Secretariat: Organization	n Structure and
Functions	i, Siructure allu
UNIT-III LOCAL ADMINISTRATION AND PACHAYAT RAJ	6
Local Administration District's Administration head: Role and Importance, Municipalitie	
	s: introduction,
Mayor and role of Elected Representative, CEO of Municipal Corporation,	7:1. D
<b>Panchayat raj:</b> Introduction, PRI: Zila Panchayat, Elected officials and their roles, CEO Z	-
Position and role, Block level: Organizational Hierarchy (Different departments), Village	evel: Role of
Elected and Appointed officials, Importance of grass root democracy.	
UNIT-IV CONCEPT AND DEVELOPMENT OF HUMAN RIGHTS	
Meaning Scope and Development of Human Rights, United Nations and Human Rights –	
1948, ICCPR 1996 and ICESCR 1966, Human Rights in India: Protection of Human Right	
(NHRC and SHRC), First, Second and Third Generation Human Rights, Judicial Activism	and Human
Rights. UNIT-V ELECTION COMMISSION	
	6
Election Commission- Role and Functioning, Chief Election Commissioner and Election C	
State Election Commission: Role and Functioning, Institute and Bodies for the welfare of	SC/ST/OBC and
women	Domin da 20
	al Periods 30
References	
<ol> <li>Durga Das Basu, Introduction to the Constitution of India, Prentice – Hall of India I</li> <li>SubashKashyap, Indian Constitution, National Book Trust</li> </ol>	vt. Ltd. New Delh
<ol> <li>SubashKashyap, Indian Constitution, National Book Trust</li> <li>J.A. Siwach, Dynamics of Indian Government &amp; Politics</li> </ol>	
<ol> <li>D.C. Gupta, Indian Government and Politics</li> </ol>	
5. H.M.Sreevai, Constitutional Law of India, 4E, 3 volumes (Universal Law Publicat	tion)
6. J.C. Johari, Indian Government and Politics Hans	,
7. J. Raj Indian Government and Politics	
8. M.V. Pylee, Indian Constitution	
9. Durga Das Basu, Human Rights in Constitutional Law, Prentice – Hall of India Py	
10. Noorani, A.G., (South Asia Human Rights Documentation Centre), Challenge Challenges to Civil Rights Guarantees in India, Oxford University Press 2012	s to Civil Right)
Chancinges to Civil Argins Quarantees in India, Oxford University Press 2012	
E-Resources:	
1. nptel.ac.in/courses/109104074/8	
2. nptel.ac.in/courses/109104045/	
3. nptel.ac.in/courses/101104065/	
J. npto.ac.m/courses/10110+003/	
4. www.hss.iitb.ac.in/en/lecture-details	

- 4. www.hss.iitb.ac.in/en/lecture-details
- 5. www.iitb.ac.in/en/event/2nd-lecture-institute-lecture-series-indian-constitution

Course Outcomes				Pro	ogram	ime O	utcom	ies (PO	Os)			Programme Specific Outcomes (PSOs)				
Outcomes	PO1	PO1         PO2         PO3         PO4         PO5         PO6         PO7         PO8         PO9         PO10         PO11         PO12								PO12	PSO1	PSO2	PSO3	PSO4		
CO1																
CO2																
CO3																
CO4																
CO5																
CO6																

191MC04	UNIVERSAL HUMAN VALU	L	Т	Р	С	
			2	0	0	0
Programme:	B.E., / B. Tech		C	atego	ry:	MC

	UNIT-II UNDERSTANDING HUMAN BEING AND ITS EXPANSION	6
encomp	assing Resolution for a Human Being, its details and solution of problems in the light of Reso	lution.
The bas	ic human aspirations and their fulfillment through Right understanding and Resolution; All-	
	UNIT-I INTRODUCTION	6
CO6.	Set do's and don'ts related to values.	
CO5.	Experiential Validation.	
COF	Verify the truth or reality in their own right, based on their Natural Acceptance and subseque	nt
CO4.	Begin with, and then to continue within the student leading to continuous self- evolution.	
CO3.	Critically evaluate their preconditioning and present beliefs.	
CO2.	Develop the understanding of human tradition and its various components.	
CO1.	Ensure the clarity about human aspirations, goal, activities and purpose of life.	
Course	Outcomes: Students will be able to	
Aim:	human being in the nature/existence.	01
	To facilitate the competence to understand the harmony in nature/existence and participation	of

#### UNIT-II UNDERSTANDING HUMAN BEING AND ITS EXPANSION

6

6

The domain of right understanding starts from understanding the human being (the knower, the experience and the doer); and extends up to understanding nature/existence – its interconnectedness and co-existence; and finally understanding the role of human being in existence (human conduct).

### **UNIT-III ACTIVITIES OF THE SELF**

Understanding the human being comprehensively is the first step and the core theme of this course; human being as co-existence of the self and the body; the activities and potentialities of the self; Reasons for harmony/contradiction in the self.

### UNIT-IV UNDERSTANDING CO-EXISTENCE WITH OTHER ORDERS

The need and the process of inner evolution (through self-exploration, self-awareness and self-evaluation)particularly awakening to activities of the Self: Realization, Understanding and Contemplation in the Self (Realization of Co-Existence, Understanding of Harmony in Nature and Contemplation of Participation of Human in this harmony/ order leading to comprehensive knowledge about the existence).

### UNIT-V EXPANSION OF HARMONY FROM SELF TO ENTIRE EXISTENCE

6

Understanding different aspects of All-encompassing Resolution (understanding, wisdom, science etc.), Holistic way of living for Human Being with All-encompassing Resolution covering all four dimensions of human endeavour viz., realization, thought, behavior and work (participation in the larger order) leading to harmony at all levels from self to Nature and entire Existence.

> **Total Periods** 30

References

- 1. A Foundation Course in Human Values and Profession Ethics (Text Book and Teachers' Manual), R. R. Gaur, R. Sangal, G. P. Bagaria (2010), Excel Books, New Delhi [ISBN 978-8-174-46781-2]
- 2. Avartansheel Arthshastra, A. Nagraj, Divya Path Sansthan, Amarkantak, India
- 3. Economy of Permanence (a quest for social order based on non-violence), J. C. Kumarappa (2010), Sarva-Seva-Sangh-Prakashan, Varansi, India

- 4. Energy and Equity, Ivan Illich (1974), The Trinity Press, Worcester & Harper Collins, USA
- 5. Ishandi Nau Upnishad, Shankaracharya, Geeta press, Gorakhpur,
- 6. Manav Vyavahar Darshan, A. Nagraj, Divya Path Sansthan, Amarkantak, India
- 7. Manaviya Sanvidhan, A. Nagraj, Divya Path Sansthan, Amarkantak, India

Course Outcomes		Programme Outcomes (POs)											Programme Specific Outcomes (PSOs)					
	PO1	PO2	PO3	PO4	PO5	PO6	<b>PO7</b>	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4		
CO1								1						1				
CO2								1						1				
CO3								1						1				
CO4								1						1				
CO5								1						1				
CO6								1						1				

191MC05	YOGA	L	Т	Р	С
		2	0	0	0
Programme:	B.E., / B. Tech	C	atego	ry:	MC

Aim:	To promote positive health, prevention of stress related health problems and rehabilitation throu	gh
1 1111	Yoga.	
Course O	utcomes: Students will be able to	
CO1:	Know about the history and evolution of Yoga.	
CO2:	Practice skills in Yoga for health.	
CO3:	Find out the habits to ensure mental and emotional balance.	
CO4:	Demonstrate basic skills associated with yoga activities including strength and flexibility, baland and coordination.	ce
CO5:	Demonstrate the ability to perform yoga movements in various combination and forms.	
CO6:	Demonstrate the ability to create and present various yoga sequences.	
	UNIT-I FOUNDATIONS OF YOGA	5
-	Yoga, History and Development of Yoga; Etymology and Definitions, Misconceptions, Aim and s of Yoga, True Nature and Principles of Yoga.	
	UNIT-II YOUTH AND YOGA	5
	<b>d yoga-</b> yoga as a tool for healthy lifestyle, Yoga as a preventive, promotive and curative method. a and Different Yoga traditions and their impacts.	
UNIT-III	ROLE OF YOGA IN PREVENTIVE HEALTH CARE	5
health: Ta	oga in preventive health care – Yoga as a way of life, Heyam dukham anagatam; Potential causes of patrayas and Kleshas, Physical and Physiological manifestation of Disease: Vyadhi, Alasya, yatva and Ssvasa-prashvasa.	DI III-
UNIT-IV	METHODS OF TEACHING YOGA	5
of Teachin	and Learning: Concepts and Relationship between the two; Principles of Teaching: Levels and Phang, Quality of perfect Yoga Guru; Yogic levels of learning, Vidyarthi, Shishya, Mumukshu; Meaning of Teaching methods, and factors influencing them; Sources of Teaching methods;	
UNIT-V	ASAN AND PRANAYAM	10
Asan and	Pranayam:	
• R	arious yog poses and their benefits for mind & body egularization of breathing techniques and its effects ifferent Phases in Pranayama Pracice: Puraka (Inhalation), Kumbhaka (Retension) and Recaka (Exhalation) Breathing Ratio in Pranayama Practice Application of Bandhas in Pranayama Total Periods	20
	I otal Periods	30
Reference	28	
2. S k 3. S	Yogic Asanas for Group Tarining-Part-I", Janardan Swami Yogabhyasi Mandal, Nagpur. wami Vivekananda, "Rajayoga or conquering the Internal Nature" Advaita Ashrama Public Colkata. ilva Mehta, Mira Mehta and Shyam Mehta, "Yoga: The Iyengar Way", Knopp publication, 1990. Yishnu-Devananda, "The Complete Illustrated Book of Yoga", 1995.	ation,

4. Vishnu-Devananda, "The Complete Illustrated Book of Yoga", 1995.

- 5. Timothy McCall, "Yoga as Medicine: The Yogic Prescription for Health and Healing", Harmony, 2007.
- 6. Hathayoga Pradipika of Swatmarama Kaivalyadhama, Lonavala
- 7. The Science of Yoga Taimini Theosophical Publishing House, Adyar, Madras

Course Outcomes	Programme Outcomes (POs)												Programme Specific Outcomes (PSOs)			
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4
CO1								1						1		
CO2														1		
CO3														1		
CO4														1		
CO5														1		
CO6														1		